

# Data Analysis: Deconvolution Models

- Convolution signal model:

$$Z(t) = \underbrace{\beta_0 + \beta_1 \cdot t}_{\text{baseline model}} + \alpha \cdot \sum_{m=0}^{p-1} \underbrace{f(t - m\Delta t)}_{\substack{\text{Stimulus} \\ \text{function} \\ (0 \text{ or } 1?)}} \cdot \underbrace{h(p\Delta t)}_{\substack{\text{hemodynamic} \\ \text{response} \\ \text{function}}} + \underbrace{\varepsilon(t)}_{\text{noise}}$$

- Deconvolution is computing  $f(t)$  and/or  $h(t)$  from data  $Z(t)$ 
  - ◇ Most common use in FMRI is computing each voxel's HRF  $h(t)$ , assuming we know the (common) input function  $f(t)$ 
    - ↪ Then compute various statistics about estimated  $h(t)$ 's:
      - ▷ Is it significantly different from zero (activation)?
      - ▷ Is the early part or the late part bigger?
  - ◇ Can also assume  $h(t)$  and try to find  $f(t)$ 
    - ↪ Might be useful with complex continuous stimuli (e.g., a video), to see which parts of the stimulus elicited a significantly increased activation in what parts of the brain
  - ◇ Can also try to find both  $f(t)$  and  $h(t)$  simultaneously: “blind deconvolution”
    - ↪ Must put some constraints on  $f(t)$ ,  $h(t)$  to get anywhere with this

- Variations and generalizations of the above model:

- ◇ Stimulus does not occur on the  $\Delta t$  time grid:

$$Z(t) = \beta_0 + \beta_1 \cdot t + \sum_{s=1}^{N_s} h(t - \tau_s) + \varepsilon(t)$$

where the  $s^{\text{th}}$  stimulus occurs at time  $\tau_s$ , for  $s = 1, 2, \dots, N_s$

↪ Have replaced  $f(t)$  with known stimulus times

↪ Goal is to find  $h(t)$

↪ Question for the astute: what happened to  $\alpha$ ?

- ◇ Stimulus has two (or more) phases, which may occur at different times (e.g., presentation and response phases):

$$Z(t) = \beta_0 + \beta_1 \cdot t + \sum_{s=1}^{N_s} [h_1(t - \tau_s) + h_2(t - (\tau_s + \delta_s))] + \varepsilon(t)$$

where the first phase of the  $s^{\text{th}}$  stimulus occurs at time  $\tau_s$  and the second phase at time  $\delta_s$  later

↪ Goal is to find  $h_1(t)$  and  $h_2(t)$  separately

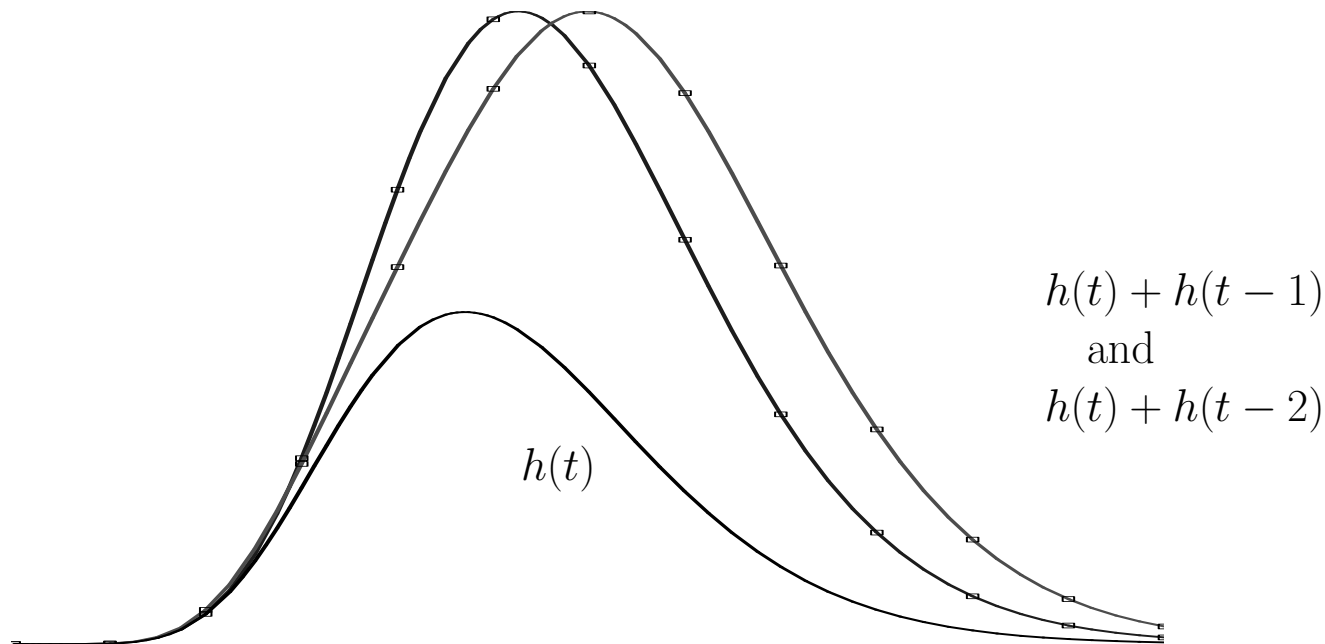
↪ Delay time  $\delta_s$  must vary (“jitter”) to make this feasible

▷ Otherwise, a single HRF  $h(t) = h_1(t) + h_2(t)$  is indistinguishable from this model

◇ There are two (or more) types of stimuli:

$$Z(t) = \beta_0 + \beta_1 \cdot t + \sum_{s=1}^{N_s} h_1(t - \tau_s) + \sum_{q=1}^{N_q} h_2(t - \mu_q) + \varepsilon(t)$$

where there are  $N_s$  stimuli of the first class (at times  $\tau_1, \tau_2, \dots$ ) and  $N_q$  stimuli of the second class (at times  $\mu_1, \mu_2, \dots$ )



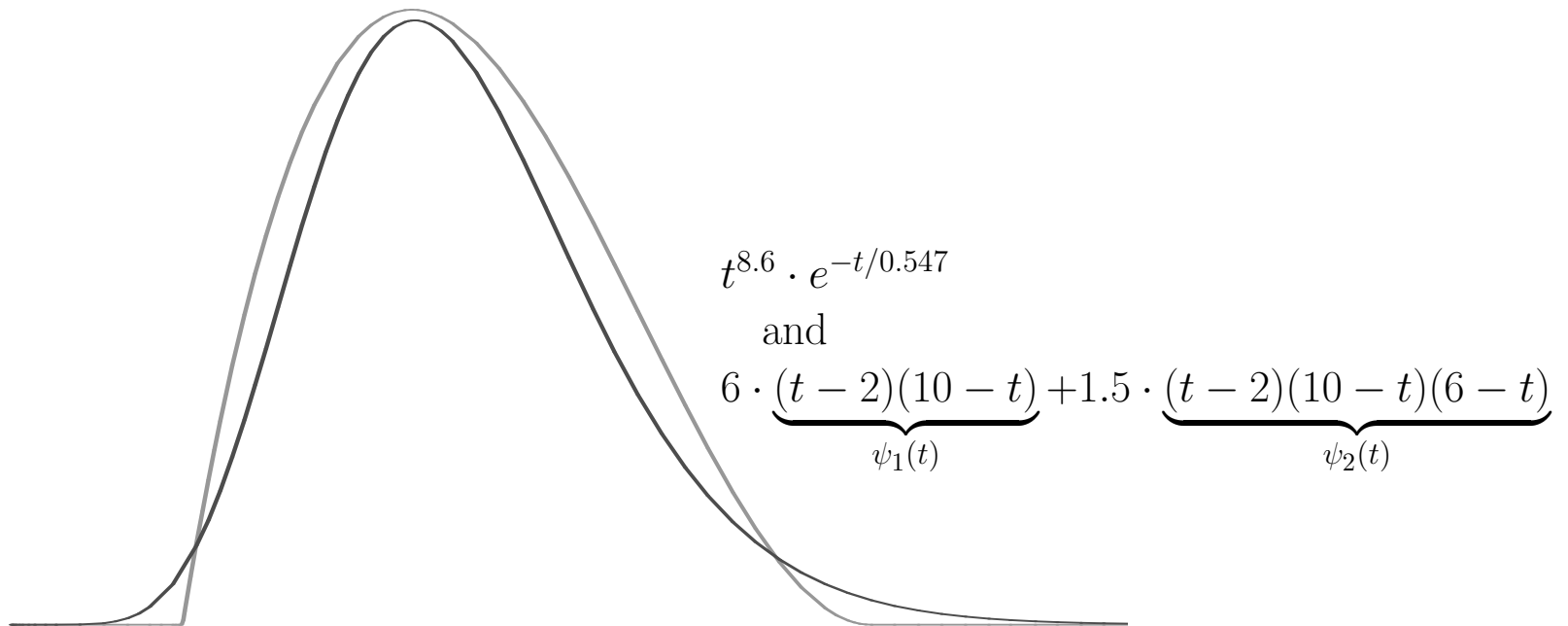
↪ Problem is to get enough data to distinguish between  $h(t) + h(t-1)$  and  $h(t) + h(t-2)$ , for example

◇ Constraints on HRF functions:

- ↪ Can either try to find  $h(t)$  in each voxel separately, or try to find a common HRF that works everywhere (e.g., component analyses)
- ↪ Can let  $h(t)$  be arbitrary function, or can limit it to make HRF be more “reasonable” and/or more “manageable”

▷ Linear constraint: 
$$h(t) = \sum_{a=0}^{N_a} \lambda_a \cdot \psi_a(t)$$

where each  $\psi_a(t)$  is a fixed “basis” function (which constrains shape of  $h(t)$ ) and the unknown amplitudes  $\lambda_a$  are to be determined from data



These two functions would be hard to tell apart without a lot of data!

▷ Nonlinear constraint:

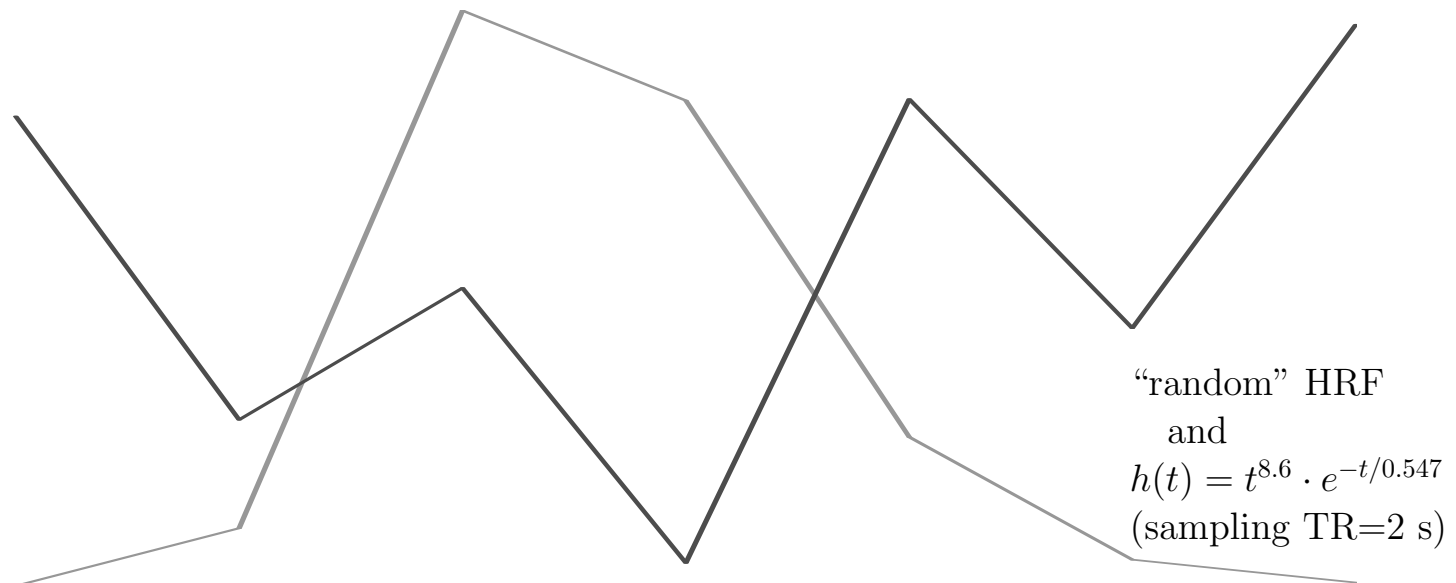
$$h(t) = \begin{cases} 0 & t \leq t_0 \\ A \cdot (t - t_0)^r \cdot e^{-(t-t_0)/b} & t > t_0 \end{cases}$$

where the unknowns are  $A$  (amplitude),  $t_0$  (time delay),  $r$  (rise exponent), and  $b$  (decay time)

- “Gamma variate” or “gamma density” model (not “gamma function”)
- Peak response is at  $t = t_0 + b \cdot r$  ;  $\text{FWHM} \approx 2.4 \cdot b^{1/2} \cdot r$

▷ “Reasonability” from constraints:

- If  $\text{TR}=2$  s and stimulus lasts 3 s  $\Rightarrow$  6–7 time points for  $h(t)$
- Arbitrary  $h(t)$  at these points could give something weird:



- Constraints can suppress “unreasonable” responses
- But such responses may be symptoms of problems you need to find

- AFNI programs for deconvolution analysis:
  - ◇ 3dDeconvolve will perform linear least squares to fit time series models to each voxel separately
    - ↪ Models can have fixed  $h(t)$  (one lag), or can have multiple lags to perform deconvolution
    - ↪ Can also use to analyze a single time series, as a test
  - ◇ 3dNLFit will perform nonlinear least squares to fit time series models to each voxel separately
    - ↪ Requires writing a C function to evaluate nonlinear model
    - ↪ Example model for gamma variate fitting is in AFNI distribution
    - ↪ This program is very slow
  - ◇ Both are command line programs: they read in datasets, compute for a while, and write out new datasets, which you then load back into AFNI for display/exploration
  - ◇ Both programs also have an interactive plugin which can be used to fit data in AFNI graph viewer
    - ↪ Useful for playing with model and determining if it useful/complete
    - ↪ Can be quite fun to overlay fitted responses on data graphs!
  - ◇ 3dConvolve is a program for generating 3D+time datasets from a convolution model

## Using 3dDeconvolve

- Written and maintained by Doug Ward of the Biophysics Research Institute, Medical College of Wisconsin, Milwaukee
- Master documentation: 3dDeconvolve.ps or 3dDeconvolve.pdf, available at AFNI Web site documentation pages:
  - PDF format  $\Rightarrow$  <http://afni.nimh.nih.gov/afni/docpdf/>
  - PostScript  $\Rightarrow$  <http://afni.nimh.nih.gov/afni/docps/>
  - ◇ Refer to this manual for more math, all input options, and many examples
  - ◇ 3dConvolve and the deconvolution plugin are also documented therein
- Ostensibly, 3dDeconvolve is a “command line” program, but in practice, there are so many inputs on the command line that you actually have to put the command into a script file, then execute the file
  - ◇ This also gives you a record of what you did, so you can do it again
  - ◇ To execute a command (or list of commands) in a file: source scriptfilename
  - ◇ A command “line” is a single logical line, but can be split across many physical lines in the script file:
    - $\hookrightarrow$  This is done by putting a backslash “\” at the end of each physical line but the last one

- ↪ Don't use the forward slash "/" for this!
- ↪ Don't put any blanks or other characters after the "\", or the logical command line will end right there (which is bad)
- ↪ Example (with the options and "/" characters made to line up):

```
3dDeconvolve -input fred+orig      \  
              -num_stimts 1        \  
              -stim_file 1 elvis.1D \  
              -stim_label 1 Elvis   \  
              -stim_minlag 1 1      \  
              -stim_maxlag 1 5      \  
              -bucket Ethel         \  
              -fout -tout           \  
              -fitts fredfit
```

- ↪ In this format, it is relatively easy to read and edit the script file
- ↪ Recommended text editor for "newbies" to Unix: nedit



- Setting up 3dDeconvolve for deconvolution analysis:

- ◇ Simplest case:

- ↪ Stimulus events take place on  $\Delta t$  grid
- ↪ Will allow arbitrary HRF to stimulus in each voxel

- ◇ There are 3 types of input files:

- ↪ AFNI formatted 3D+time datasets
- ↪ 1D files, representing time series on the  $\Delta t$  grid
  - ▷ Stored as a single ASCII number per line
- ↪ Matrix files, used to control generation of analysis results
  - ▷ Stored as a 2D layout of ASCII numbers in a text file
- ↪ Examples: a time series of length 5, and a  $2 \times 6$  matrix

```
1
0
1
0
1
0 -1 -1 1 0 0
0 -1 0 0 -1 -1
```

- ◇ User must divide stimulus events into classes

- ↪ Need a 0/1 time series series file for each class, indicating when the stimuli for that class occur
- ↪ Each class  $k$  will get its own HRF  $h_k(t)$ , for  $k = 1, 2, \dots$

- Important command line options for 3dDeconvolve:

- ◇ Format of the descriptions below:

- option arguments

- ↪ The string “-option” specifies the option, and must be typed as shown

- ↪ If an option has arguments (most of them do), their names are given in italics following the option name

- ↪ When you actually use an option, the arguments will be replaced with file-names, numbers, etc., as appropriate

- ◇ -input fname

- fname* specifies the input 3D+time AFNI dataset (e.g., *fred+orig*)

- ◇ -num\_stimts num

- This option specifies how many classes of stimuli are present; it is required. There is no built-in upper limit on *num*.

- ◇ -stim\_file k sname

- This option specifies the input time series for the  $k^{\text{th}}$  stimulus class

- ↪ *k* should be from 1 to *num* (from -num\_stimts)

- ↪ *sname* is the name of the file to be read in

- ↪ For event-related analyses, *sname* would usually be a time series consisting of 0s and 1s

- ↪ This input corresponds to the function  $f_k(t)$

◇ -stim\_label  $k$   $slabel$

This option specifies the label that will be attached to the output that is relevant to the  $k^{\text{th}}$  stimulus file

↪ Makes it easier to interpret the output file

↪  $slabel$  should be enclosed in 'quotes' if it contains "special" characters such as: blank, \* [] {} ;

◇ -stim\_minlag  $k$   $m$

This option specifies that the minimum lag to be used for the  $k^{\text{th}}$  stimulus file is the number  $m$

↪ If this option is not present, then  $m = 0$

◇ -stim\_maxlag  $k$   $n$

This option specifies that the maximum lag to be used for the  $k^{\text{th}}$  stimulus file is the number  $n$  ( $n \geq m$  is required)

↪ If this option is not present, then  $n = 0$

↪ The response to the  $k^{\text{th}}$  stimulus is 
$$r_k(t) = \sum_{q=m}^n f_k(t - q\Delta t) \cdot h_k(q\Delta t)$$

One goal of the program is to compute the set  $\{h_k(q\Delta t) : q = m \dots n\}$

↪ The default case  $m = n = 0$  corresponds to simple linear regression

▷ Then  $h_k(0)$  is the amplitude of  $f_k(t)$  in the data

◇ -iresp  $k$   $iprefix$

This option specifies that the  $k^{\text{th}}$  HRF function  $h_k(t)$  is to be saved in an AFNI dataset with prefix name given by the string  $iprefix$

↪ This dataset is useful if you want to graph the HRF results

◇ -sresp  $k$   $sprefix$

This option specifies that the standard deviation of the  $k^{\text{th}}$  HRF function  $h_k(t)$  should be saved in an AFNI dataset with prefix name given by the string  $sprefix$

↪ This dataset lets you visually inspect the confidence you should have in  $h_k(t)$

◇ -fitts  $fprefix$

This option specifies that the fitted model should be written to an AFNI 3D+time dataset with prefix name given by the string  $fprefix$

↪ Using the Dataset#2 plugin and 1D Transform, and the Double Plot graphing option, you can use this to overlay the fitted time series model on each voxel's actual data

↪ Another way to make this type of graph is with the Deconvolution plugin

◇ -bucket *bprefix*

This option specifies that the statistical output should be written to an AFNI “bucket” dataset with prefix name *bprefix* — you almost surely want to use this option!

- ↪ The bucket output contains multiple sub-bricks, with various statistical parameters; it provides a convenient way to gather all the diverse possible outputs into one place
- ↪ The sub-bricks are labeled via `-stim_label`, and can be used within AFNI as a statistical threshold and/or to generate colored overlays
- ↪ Additional options are needed to specify which statistics go into this dataset:
  - ▷ -fout specifies that the  $F$ -statistics for the full model (with all stimulus functions) and for each individual partial model (with one stimulus function at a time) be included in the bucket dataset
    - Full  $F$  measures significance of overall model
    - Partial  $F$  measures significance of each component of model
  - ▷ -rout specifies that the  $R^2$ -statistics for the full and partial models be included in the bucket dataset (these are generalizations of the correlation coefficient, and are equivalent to the  $F$ -statistics if the Gaussian white noise model is correct)
  - ▷ -tout specifies that the  $t$ -statistics for each regression parameter ( $h_k(q\Delta t)$  for all  $k$  and  $q$ ) be saved into bucket dataset sub-bricks

◇ General Linear Tests (GLTs):

- ↪ These are used to perform tests on linear combinations of regression parameters ( $h_k(q\Delta t)$  for all  $k$  and  $q$ , plus the baseline parameters)
- ↪ The resulting  $F$ -statistics are added to the output bucket dataset
- ↪ To specify a test, you input a matrix that gives the coefficient of the linear combinations you want to test against zero
- ↪ In most cases, this matrix will have only 0, 1, and -1 as entries (0=ignore, 1=add, -1=subtract)
- ↪ To specify the test, you must know the order of the regression parameters in the output
  - ▷ Baseline parameters come first (usually, 2 of them:  $\beta_0, \beta_1$ )
  - ▷  $h_1(q\Delta t)$  for  $q = m_1 \dots n_1$  comes next
  - ▷  $h_2(q\Delta t)$  for  $q = m_2 \dots n_2$  comes next, etc.
  - ▷ Example: 2 stimulus classes, 4 lags each  $\Rightarrow$  parameter vector is  $\{ \beta_0 \beta_1 h_1(0) h_1(\Delta t) h_1(2\Delta t) h_1(3\Delta t) h_2(0) h_2(\Delta t) h_2(2\Delta t) h_2(3\Delta t) \}$
  - ▷ To test if  $h_1(\Delta t)$  is different from  $h_2(\Delta t)$  (that is, if  $h_1(\Delta t) - h_2(\Delta t) \neq 0$ ), the matrix is
$$\begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 \end{bmatrix}$$
  - ▷ -glt  $s$  *gltname*  
Indicates to do a GLT with  $s$  rows, reading the matrix from file *gltname*
    - Example above:  $s = 1$ ; matrix file contains 0 0 0 1 0 0 0 -1 0 0

▷ To test if  $h_1(t) = h_2(t)$  for all  $t$  computed, we need four input lines:

```
0 0 1 0 0 0 -1 0 0 0
0 0 0 1 0 0 0 -1 0 0
0 0 0 0 1 0 0 0 -1 0
0 0 0 0 0 1 0 0 0 -1
```

▷ The result from this is an  $F$ -statistic

▷ ANOVA type analyses can be carried out with `-glt`

▷ `-glt_label k glabel`

This option attaches the label string *glabel* to the output for the  $k^{\text{th}}$  GLT (in order on the command “line”)

◇ Other things you can do:

↪ -censor *cname*

*cname* is a 1D time series file specifying which points to keep (input=1) and which to delete (input=0) from the analysis (default=keep all points)

↪ -concat *rname*

3dDeconvolve can deal with 3D+time input datasets that are catenated from multiple imaging runs (via program 3dTcat)

▷ To deal properly with the discontinuity across runs, you must specify the starting point in the input dataset for each imaging run

▷ *rname* is the name of a 1D time series file whose  $j^{\text{th}}$  entry is the time index for the start of the  $j^{\text{th}}$  run within the input dataset

▷ Note that each run will get a separate  $\beta_0$  and  $\beta_1$ , which must be allowed for when setting up -glts matrices

↪ -mask *mname*

*mname* is the name of a 3D dataset that can be used to mask off unwanted regions from analysis; voxels where the mask dataset is 0 will not be analyzed by 3dDeconvolve

▷ A mask dataset might be created using program 3dClipLevel

↪ -polort *pnum*

*pnum* sets the polynomial order of the baseline model; the default is 1; useful values would be from 0 to 3