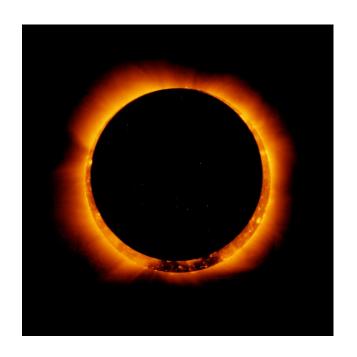
Alignment and Atlases





What does aligning mean and why do we want to do it?

- Alignment means to bring two objects into the same space so that each location within one object corresponds to the same location in the other
- Why?
 - motion correction across time
 - align EPI to anatomical data or vice versa to assign a location with a functional result
 - compare data from longitudinal studies
 - compare data from different scanners, sites
 - compare results with a standard template or atlas for standardized locations and structures

Alignment goals and tools in AFNI

- EPI data across time in a single run or across runs to a base image
 - 3dvolreg motion correction (rigid)
 - align data to template
 - 3dWarpDrive, @auto_tlrc align similar volumes (affine) even across subjects
 - 3dQwarp, auto_warp.py align similar volumes nonlinearly to template
 - align images across modalities EPI to anat
 - 3dAllineate align different or similar volumes
 - align_epi_anat.py general alignment script to align EPI with anatomical data
- Include motion correction, alignment of EPI to anatomical in fMRI processing pipeline script
 - afni_proc.py
- Correct for motion between two volumes by aligning in two dimensions using corresponding slices
 - ♦ @2dwarper.Allin non-linear alignment of slices
 - @2dwarper, 2dimreg limit alignment to specific plane

Alignment tools in AFNI (continued)

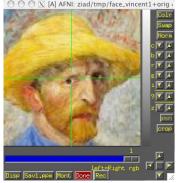
- align partial data to roughly the right part of the brain
- Nudge plug-in visually align two volumes
- rotate by known amount between volumes
- 3drotate moves (shifts and rotates) volumes
- 3dWarp make oblique, deoblique to match another dataset
- Put centers of data from outside sources in roughly the same space
- @Align_Centers, 3dCM put centers or centers of mass of dataset in same place
- align specific regions across subjects
- 3dTagalign, tagset plugin place and align volumes using corresponding fiducial marker points
- align one jpeg image to another
- imreg align two 2D images

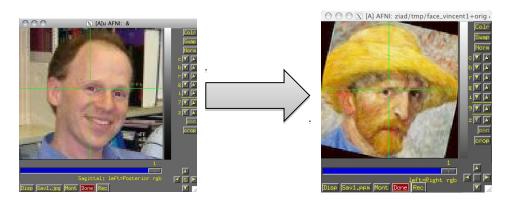
Image and Volume Registration with AFNI

- Goal: bring images collected with different methods and at different times into spatial alignment
- Facilitates comparison of data on a voxel-by-voxel basis
 - Functional time series data will be less contaminated by artifacts due to subject movement
 - Can compare results across scanning sessions once images are properly registered
 - Can put volumes in standard space such as the stereotaxic Talairach-Tournoux coordinates
- Most (all?) image registration methods now in use do pair-wise alignment:
 - Given a base image J(x) and target (or source) image I(x), find a geometrical transformation T[x] so that I(T[x]) ≈ J(x)
 - T[x] will depend on some parameters
 - Goal is to find the parameters that make the transformed I a 'best fit' to J
 - ♦ To register an entire time series, each volume $I_n(x)$ is aligned to J(x) with its own transformation $T_n[x]$, for n=0, 1, ...
 - \rightarrow Result is time series $I_n(T_n[x])$ for n=0, 1, ...
 - → User must choose base image J(x)

- Most image registration methods make 3 algorithmic choices:
 - ♦ How to measure mismatch E (for error) between I(T[x]) and J(x)?
 - → Or ... How to measure goodness of fit between I(T[x]) and J(x)?
 - ♦ How to adjust parameters of T[x] to minimize E?
 - How to interpolate I(T[x]) to the J(x) grid?
 - So we can compare voxel intensities directly
- The input volume is transformed by the optimal **T[x]** and a record of the transform is kept in the header of the output.
- Finding the transform to minimize E is the bulk of the registration work. Applying the transform is easy and is done on the fly in many cases.
- If data starts off far from each other, may add a coarse pass (twopass) step
 - guess a lot among all the parameters (rotations, shifts, ...), measure cost
 - best guesses, tweak the parameters (optimize) and measure again

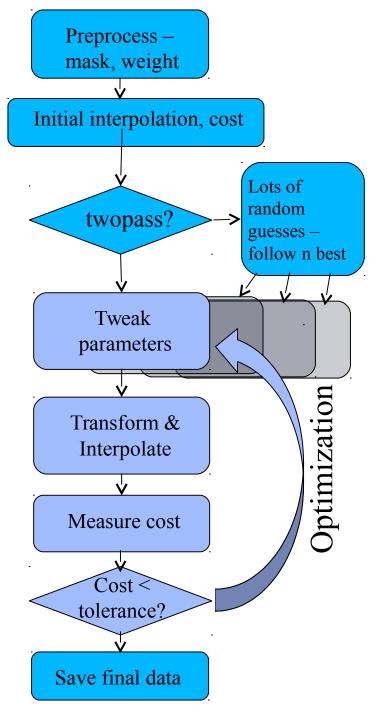
Now, applications of alignment...



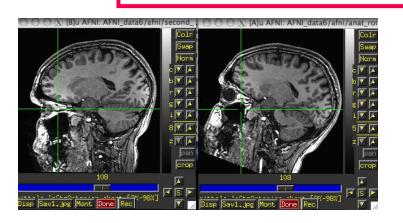


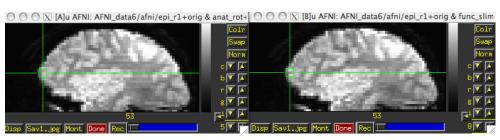
Alignment process - overview

- Preprocess mask data, weight data
- If far off, take some random guesses (-twopass)
- Optimize parameters on initial or best sets (6,12,39,1000's)
 - Use new parameters to transform input
 - Interpolate onto base data's grid
 - Measure alignment error with cost functional
 - Less than minimum error finished
 - Better keep adjusting with same direction
 - Worse try other parameters
- Create final output by interpolating onto output grid
 - save datasets, transform parameters



Within Modality Registration





- AFNI <u>3dvolreg</u> and <u>3dWarpDrive</u> programs match images by grayscale (intensity) values
 - ♦ E = (weighted) sum of squares differences = $\sum_{x} w(x) \cdot \{I(T[x]) J(x)\}^2$
 - Only useful for registering 'like images':
 - □ Good for SPGR↔SPGR, EPI↔EPI, but not good for SPGR↔EPI
 - Several interpolation methods :
 - → Fourier, linear, cubic, quintic, and heptic polynomials
 - ♦ <u>3dvolreg</u> is designed to run VERY fast for EPI↔EPI registration with small movements good for FMRI purposes but restricted to 6-parameter rigid-body transformations.
 - <u>3dWarpDrive</u> is slower, but it allows for up to 12 parameters affine transformation. This corrects for scaling and shearing differences in addition to the rigid body transformations.

Looking for Motion

afni GUI – graph-image video/ricochet, arrow keys. Graph spikes.

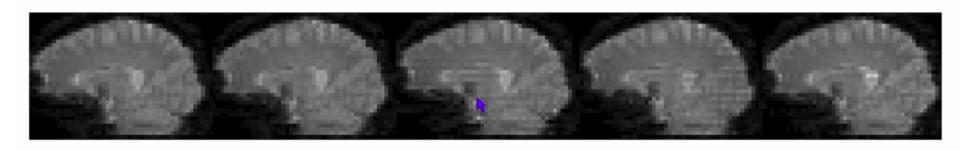


Image courtesy of Jonathan Power, NIMH

In statistical results, "activation" / "deactivation" occurs at high contrast boundaries like edge of brain or ventricles.

- AFNI program 3dvolreg is for aligning 3D volumes by rigid movements
 - T[x] has 6 parameters:
 - ➤ Shifts along x-, y-, and z-axes; Rotations about x-, y-, and z-axes
 - Generically useful for intra- and inter-session alignment
 - Motions that occur within a single TR (2-3 s) cannot be corrected this way, since method assumes rigid movement of the entire volume
- AFNI program <u>3dWarpDrive</u> is for aligning 3D volumes by affine transformations
 - T[x] has up to 12 parameters:
 - \rightarrow Same as <u>3dvolreg</u> plus 3 Scales and 3 Shears along x-, y-, and z-axes
 - Generically useful for intra- and inter-session alignment
 - Generically useful for intra- and inter-subject alignment
 - AFNI program 2dImReg is for aligning 2D slices
 - ♦ T[x] has 3 parameters for each slice in volume:
 - Shift along x-, y-axes; Rotation about z-axis
 - ➤ No out of slice plane shifts or rotations!
 - Useful for sagittal EPI scans where dominant subject movement is 'nodding' motion that may be faster than TR
 - It is possible and sometimes even useful to run 2dImReg to clean up sagittal nodding motion, followed by 3dvolreg to deal with out-of-slice motion

• Intra-session registration example:

```
3dvolreg -base 4 -heptic -zpad 4 \
-prefix fred1_epi_vr \
-1Dfile fred1_vr_dfile.1D \
fred1_epi+orig 
Input dataset name
```

- → base 4 ⇒ Selects sub-brick #4 of dataset fred1_epi+orig as base image J(x)
- → heptic ⇒ Use 7th order polynomial interpolation
- → zpad 4 ⇒ Pad each target image, I(x), with layers of zero voxels 4 deep on each face prior to shift/rotation, then strip them off afterwards (before output)
 - → Zero padding is particularly desirable for -Fourier interpolation
 - → also good for large rotations, some data may get 'lost' if no zero padding
- → -1Dfile fred1_vr_dfile.1D ⇒ Save estimated movement parameters into a 1D (i.e., text) file with the given name
 - → Movement parameters can be plotted with the 1dplot command and used later....

```
Try this (in AFNI_data6/afni):

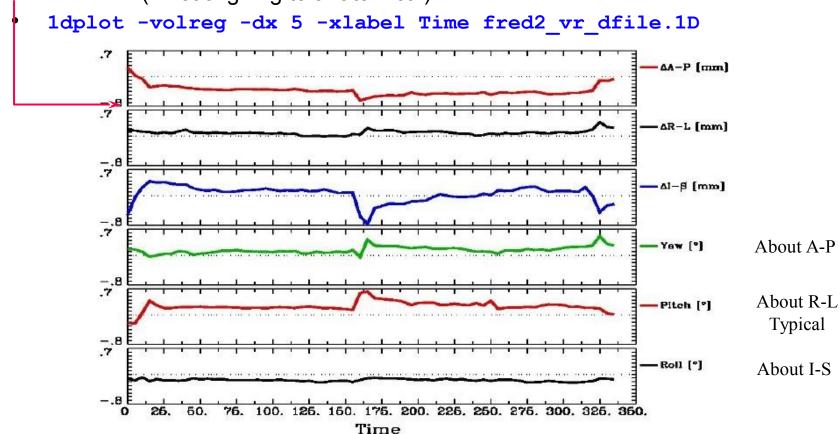
3dvolreg -base 3 -cubic -prefix epi_r1_vrt -1Dfile vr_dfile.1D epi_r1+orig

1dplot -volreg vr_dfile.1D &
```

-12- ♦ Can now register second dataset from same session:

```
3dvolreg -base `fred1_epi+orig[4]' -heptic -zpad 4 \
    -prefix fred2_epi_vr -1Dfile fred2_vr_dfile.1D \
    fred2_epi+orig
```

- Note base is from different dataset (fred1_epi+orig) than input (fred2_epi+orig)
 - Aligning all EPI volumes from session to EPI closest in time to SPGR (if not aligning to anatomical)



→ Note motion peaks at time ≈ 160s: subject jerked head up at that time

"Fixing Motion"

- Motion occurs over slices and not volumes and moves data off original grid
- "Regressing out" motion parameters, derivatives, displacement, euclidean norm of derivatives (summary parameters)
- Censoring ("scrubbing", "sweeping under the mat",...)
- Experimental design kids, monkeys, juice, talking, waving hands wildly....
- Interpreting results differences in motion between groups or something physiological
- Notice activation following high contrast borders, "blinds" effects

```
Try this (in AFNI_data6/afni):

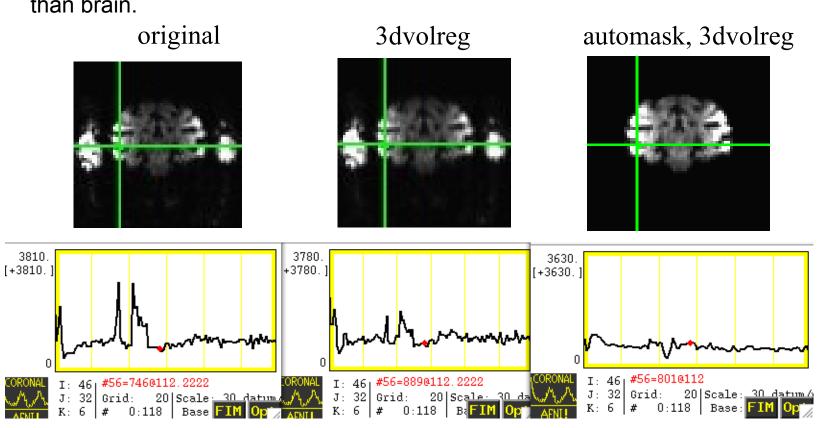
1d_tool.py -infile vr_dfile.1D -set_nruns 1 -censor_motion 1 ett

1dplot ett_enorm.1D &

cat ett CENSORTR.txt
```

Motion correction – caveats

- Motion is usually not completely correctable, so set motion parameters as regressors of no interest. Interpolation generally blurs data and depends on method and grid/resolution of EPI.
- Check in the AFNI GUI to be sure the data is not bouncing around after correction
- Example Monkey sips juice at stimulus time, and large jaw muscles move. If the muscles are not masked, then motion correction may track muscles rather than brain.



Cross Modality Registration

- 3dAllineate can be used to align images from different methods
 - For example, to align EPI data to SPGR / MPRAGE:
 - ► Run 3dSkullStrip on the SPGR dataset so that it will be more like the EPI dataset (which will have the skull fat suppressed)
 - Use 3dAllineate to align the EPI volume(s) to the skull-stripped SPGR volume
 - → Program works well if the EPI volume covers most of the brain
 - Allows more general spatial transformations affine, bilinear, non-linear (polynomial warping)
- 3dAllineate has several different "cost" functions (E) available

```
$ leastsq = Least Squares (3dvolreg, 3dWarpDrive)
```

- mutualinfo = Mutual Information
- orm_mutualinfo = Normalized Mutual Information
- hellinger = Hellinger Metric [the default cost function]
- corrratio mul = Correlation ratio (symmetrized by multiplication)
- corratio add = Correlation ratio (symmetrized by addition)
- corratio_uns = Correlation ratio (unsymmetric)
 - lpc = Local Pearson Correlation (negative)
 - 1pa = Local Pearson Correlation (absolute value)

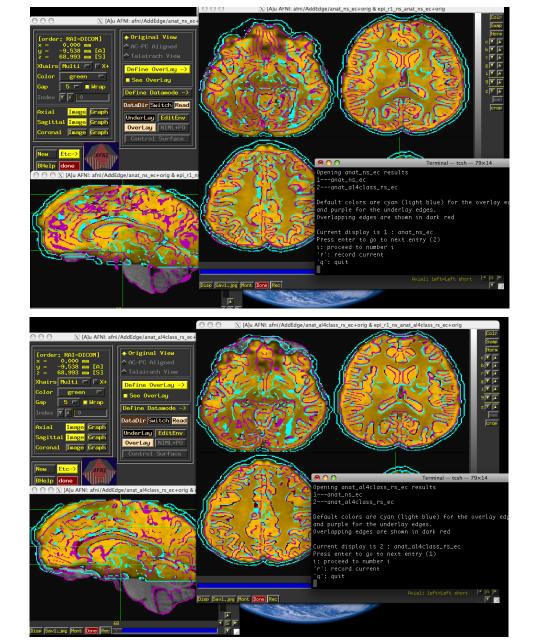
align_epi_anat.py

- Goal: Want to align anat and EPI (anat to EPI or EPI to anat or dset1to2 or dset2to1)
- LPC method Local Pearson Correlation to match dark CSF in anatomical data with bright CSF in EPI data.
- align_epi_anat.py script preprocessing and calls 3dAllineate for alignment
- @AddEdge for visualization
- Simple Example:

```
align_epi_anat.py -anat anat+orig \
-epi epi_r1+orig \
-AddEdge -epi_base 0 -suffix _al4class
cd AddEdge
afni -niml -yesplugouts &

@AddEdge
```

Combines deoblique, motion correction, alignment and talairach transformations into a single transformation. Also performs slice timing correction and applies transformations to "child" datasets.



@AddEdge display

Before

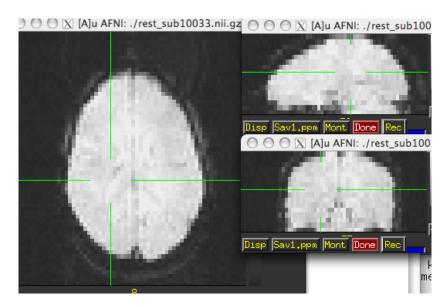
After

Alignment Visualization in AFNI

- Graph and image travel through time for motion correction or for a thousand datasets in a row.
- Multiple controllers and crosshairs up to ten datasets at a time, quick and rough.
- Overlay display opacity control, thresholding. A single pair good for different or similar datasets.
- Overlay toggle, Underlay toggle wiggle, good but a little tricky ('o' and 'u' keys in image viewer)
- Sliding Overlay ('4'/'5' keys), Fade-in overlay ('6' key), Checkerboard Underlay ('#' key) two similar datasets in underlay but must be virtually identical. Good for comparing two processing methods
- Edge display for underlay effective pairwise comparison for quick fine structure display and comparison with overlay dataset with opacity. One dataset should have reliable structure and contrast. Now with 'e' toggle.
- @AddEdge single or dual edges with good contrast for pairwise comparison.

Alignment strategies with align_epi_anat.py

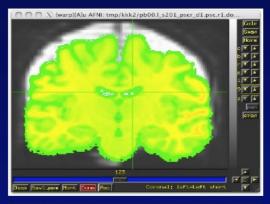
- Defaults work usually (>90% FCON1000)
 - Problems:
- Far off start "-big_move", "-giant_move", "-ginormous_move"
- Poor contrast "-cost lpa", "-cost nmi", "-cost lpc+ZZ"
- Poor non-uniformity "-edge", "-cost lpa"
- stroke/MS lesions, tumors, monkeys, rats, multi-modality (CT/PET/DTI/...), something else? – see us, post message

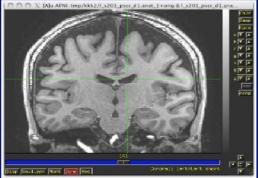


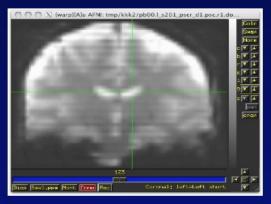
Real and Imaginary Problems

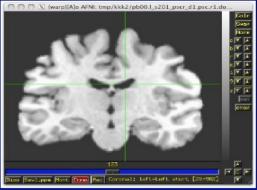
Saved by the contrast

 However, bias may result in erroneous group differences





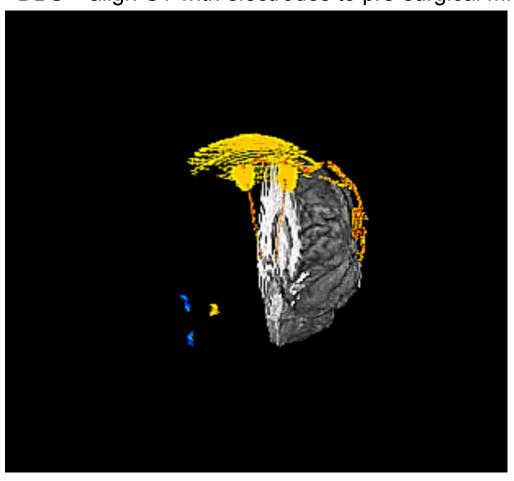




Z.S.S 10/04/10

Alignment -special cases

DBS – align CT with electrodes to pre-surgical MRI

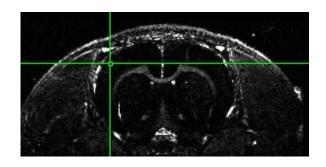


Also see

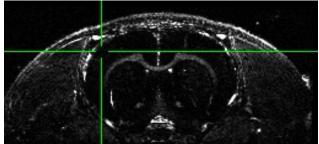
@Install_DBSproc
for DBS with CT
and DTI processing
(S. Horovitz)

Datasets courtesy of Justin Rajendra, Emory

Rat Brains



Alignment of 12 hour Manganese enhanced MRI scan (MEMRI) to start

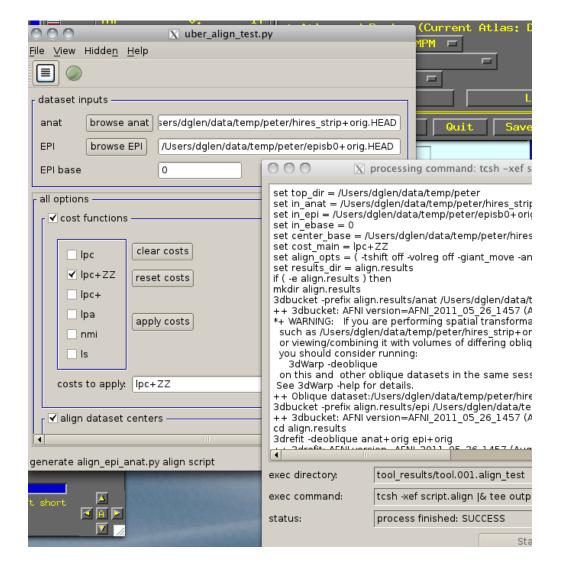


```
#!/bin/tcsh
# align_times.csh
set basedset = 14_pre+orig
foreach timedset ( 14_*hr+orig.HEAD)
    align_epi_anat.py -prep_off -anat $timedset -epi $basedset \
    -epi_base 0 -anat_has_skull no -epi_strip None -suffix _edge2prep \
    -cost lpa -overwrite -edge -rat_align
end
3dTcat -prefix 14_timealigned_edge 14_pre+orig. 14*edge2prep+orig.HEAD
```

Data from Der-Yow Chen (NINDS)

uber_align_test.py

select input
data
set options
create script
run script



afni_proc.py – alignment handling

- Single script to do all the processing of a typical fMRI pipeline including motion correction (3dvolreg), alignment (align_epi_anat.py)
- combines transformations when possible
- from example 6 in afni_proc.py's prodigious help:

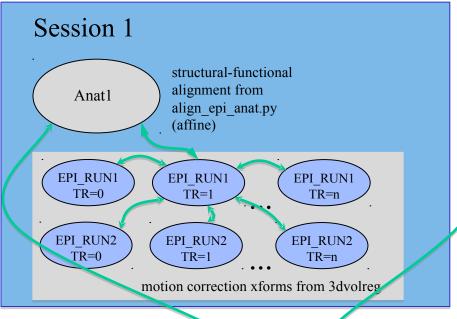
```
afni_proc.py -subj_id sb23.e6.align
    -dsets sb23/epi_r??+orig.HEAD
    -do_block align tlrc
    -copy_anat sb23/sb23_mpra+orig \
    -tcat_remove_first_trs 3
    -volreg_align_to last
    -volreg_align_e2a
    -volreg_tlrc_warp
```

To process in orig space, remove -volreg_tlrc_warp.

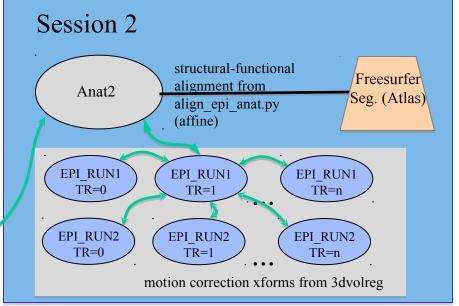
To apply manual tlrc transformation, use -volreg_tlrc_adwarp.

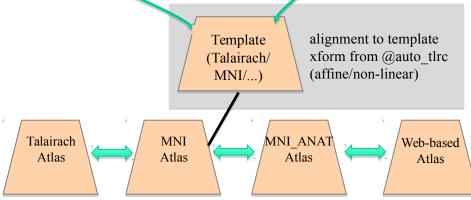
To process as anat aligned to EPI, remove -volreg_align_e2a.

Transformation Chains Example

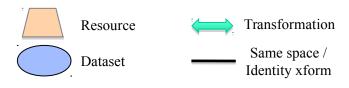


Known or User-defined transformations

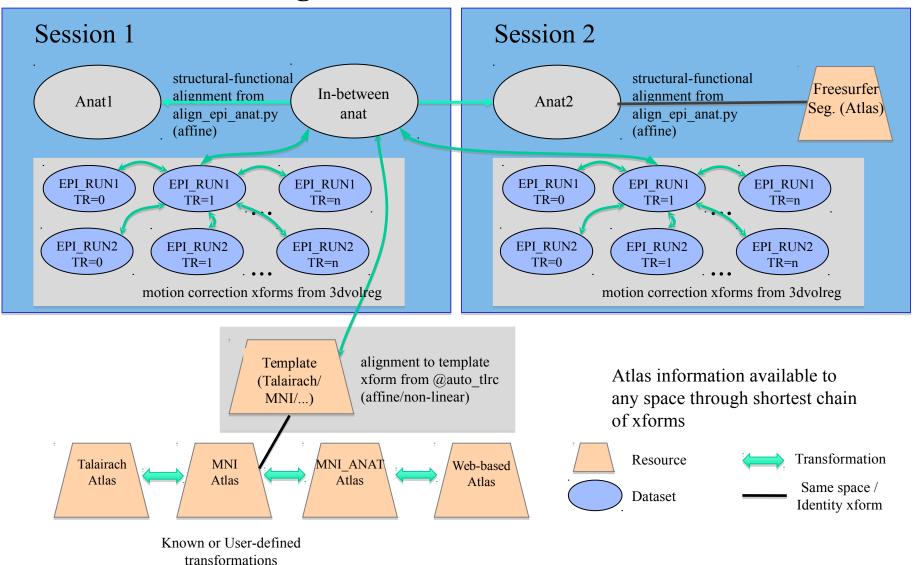




Atlas information available to any space through shortest chain of xforms



Alignment across two sessions



http://afni.nimh.nih.gov/sscc/dglen/alignmentacross2sessions

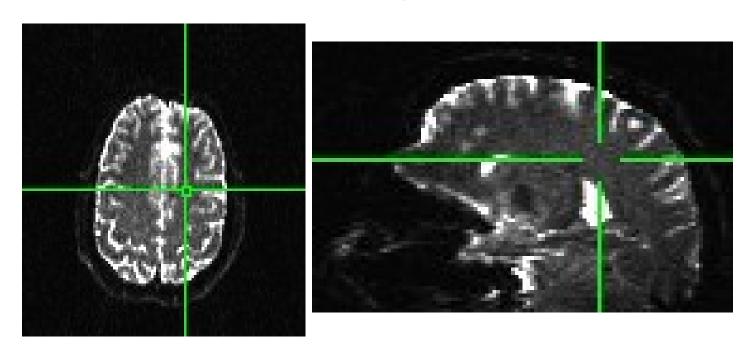
Nonlinear Warping

3dQwarp

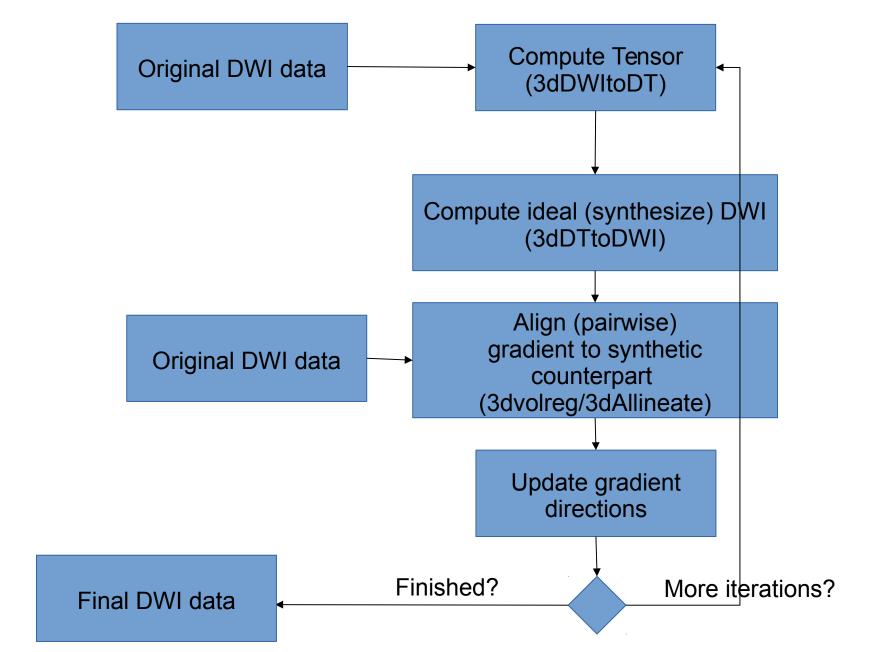
- $I_{\text{new}}(\mathbf{x}) = I_{\text{old}}(\mathbf{W}(\mathbf{x}))$
 - \diamond where **W**(**x**) depends on a *lot* of parameters (1000-50000+)
 - Method: Incremental transformation with Hermite cubic polynomials over finer and finer 3D patches. Output is both aligned dataset and the warp and the inverse warp deformations in Dx,Dy,Dz
 - **★** Better alignment of anatomical volumes to template space
 - → Then carry the functional results to template space for better group analyses?
 - → As an aid to brain segmentation and atlas-ing accuracy?
- ★ Pre- and post-surgical alignment, EPI distortion correction
- Related programs and scripts:
 - ♦ 3dNwarpApply, 3dNwarpCat, 3dNwarpCalc, 3dNwarpAdjust, 3dNwarpFuncs
 - auto_warp.py, afni_proc.py

UnwarpEPI.py - blipup-blipdown script (Vinai Roopchansingh)

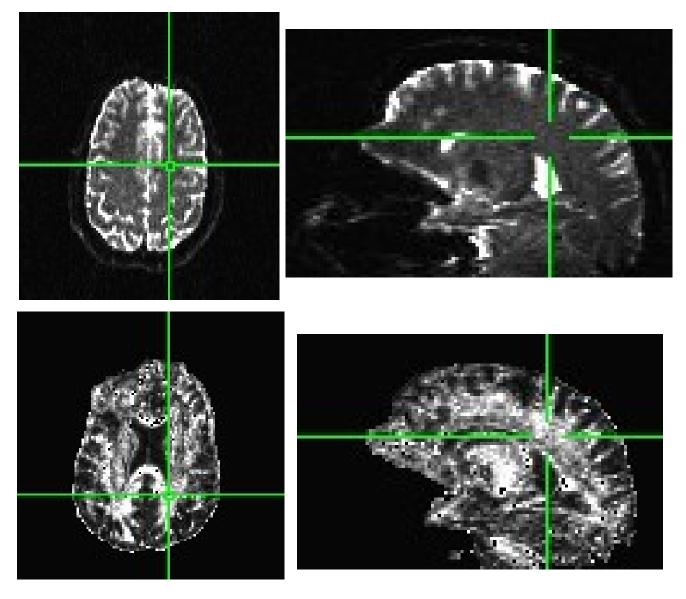
DWI Motion Correction



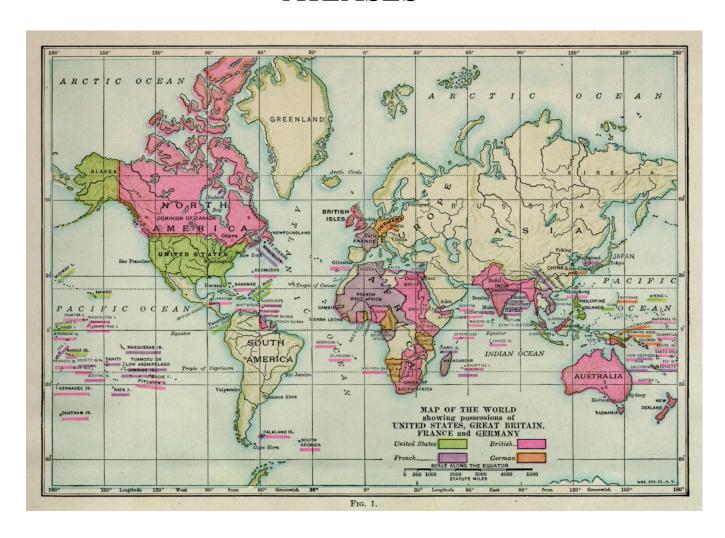
Method overview



DWI Motion Correction

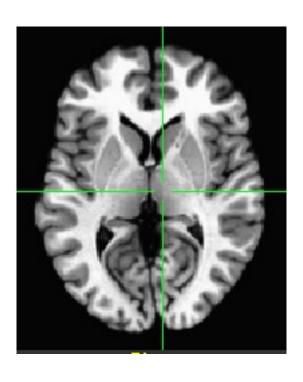


ATLASES



ATLAS DEFINITIONS

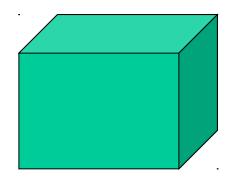
Template - a reference dataset used for matching shapes. Examples: TT_N27+tlrc, MNI_EPI+tlrc, TT_ICBM452+tlrc.



TT N27+tlrc

ATLAS DEFINITIONS

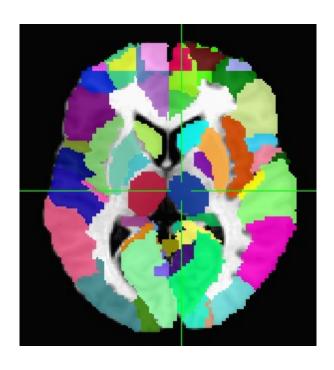
Template Space - x,y,z coordinate system shared by many datasets (the basic shoebox) Examples: TLRC (Talairach-Tourneaux), MNI, MNI_ANAT, ORIG.



ATLAS DEFINITIONS

Atlas - segmentation info.

Examples: TTatlas+tlrc, TT_N27_EZ_ML+tlrc, roidset+orig.



TT N27 EZ ML+tlrc

Registration To Standard Spaces

Transforming Datasets to Talairach-Tournoux Coordinates

The original purpose of AFNI (circa 1994 A.D.) was to perform the transformation of

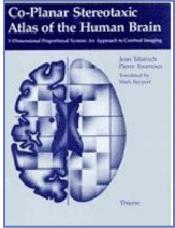
datasets to Talairach-Tournoux (stereotaxic) coordinates

- The transformation can be manual, or automatic
- In manual mode, you must mark various anatomical locations, defined in

Jean Talairach and Pierre Tournoux

"Co-Planar Stereotaxic Atlas of the Human Brain"

Thieme Medical Publishers, New York, 1988



- Marking is best done on a high-resolution T1-weighted structural MRI volume
- In automatic mode, you need to choose a template to which your data are aligned. Different templates are made available with AFNI's distribution. You can also use your own templates.
- Transformation carries over to all other (follower) datasets in the same directory
 - This is where the importance of getting the relative spatial placement of datasets done correctly in to3d really matters
 - You can then write follower datasets, typically functional or EPI timeseries, to disk in Talairach coordinates
 - → Purpose: voxel-wise comparison with other subjects
 - → May want to blur volumes a little before comparisons, to allow for residual anatomic variability: AFNI programs 3dmerge or 3dBlurToFWHM

- Hidden in GUI right click on "DataDir" or set AFNI_ENABLE_MARKERS to YES in .AFNIRC
- Manual Transformation proceeds in two stages:
 - 1. Alignment of AC-PC and I-S axes (to +acpc coordinates)
 - 2. Scaling to Talairach-Tournoux Atlas brain size (to +tlrc coordinates)
- Stage 1: Alignment to +acpc coordinates:
 - Anterior commissure (AC) and posterior commissure (PC) are aligned to be the y-axis
 - The longitudinal (inter-hemispheric or mid-sagittal) fissure is aligned to be the yzplane, thus defining the z-axis
 - The axis perpendicular to these is the x-axis (right-left)
 - Five markers that you must place using the [<u>Define Markers</u>] control panel:

```
AC superior edge = top middle of anterior commissure

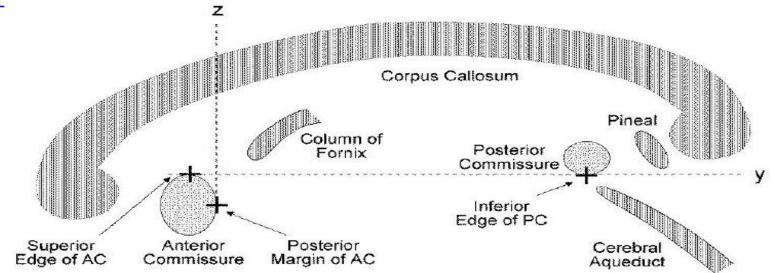
AC posterior margin = rear middle of anterior commissure

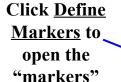
PC inferior edge = bottom middle of posterior commissure

First mid-sag point = some point in the mid-sagittal plane

Another mid-sag point = some other point in the mid-sagittal plane
```

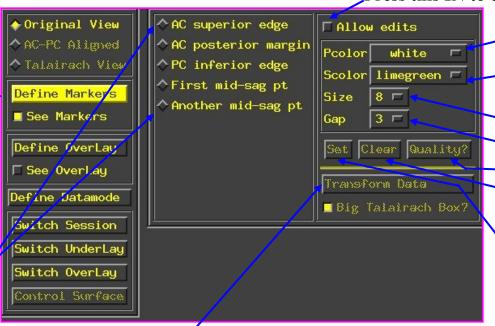
- This procedure tries to follow the Atlas as precisely as possible
 - ➤ Even at the cost of confusion to the user (e.g., you)





panel

Select which marker you are editing



Press this IN to create or change markers

Color of "primary" (selected) marker

Color of "secondary" (not selected) markers

Size of markers (pixels) Size of gap in markers

Clear (unset) primary marker

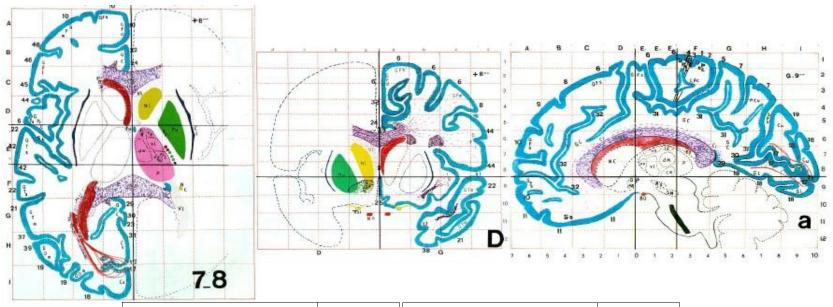
Set primary marker to current focus location

Carry out transformation to +acpc coordinates

Perform "quality" check onmarkers (after all 5 are set)

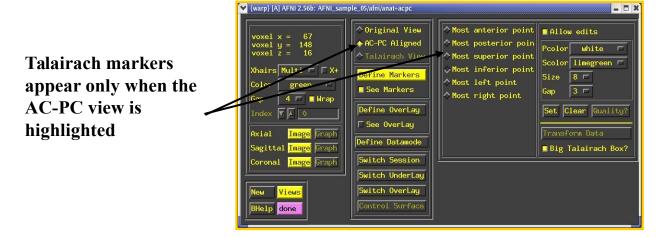
• Stage 2: Scaling to Talairach-Tournoux (+tlrc) coordinates:

 Once the AC-PC landmarks are set and we are in ACPC view, we now stretch/shrink the brain to fit the Talairach-Tournoux Atlas brain size (sample TT Atlas pages shown below, just for fun)



Most anterior to AC	70 mm		
AC to PC	23 mm		
PC to most posterior	49 mm		470
		Length of cerebrum	172mm
AC to most superior AC to left (or right)	74 mm 68 mm	Height of cerebrum Width of cerebrum	116mm

- Selecting the Talairach-Tournoux markers for the bounding box:
 - ♦ There are 12 sub-regions to be scaled (3 A-P x 2 I-S x 2 L-R)
 - ♦ To enable this, the transformed +acpc dataset gets its own set of markers
 - → Click on the [AC-PC Aligned] button to view our volume in ac-pc coordinates
 - ► Select the [Define Markers] control panel
 - A new set of six Talairach markers will appear and the user now sets the bounding box markers (see Appendix C for details):

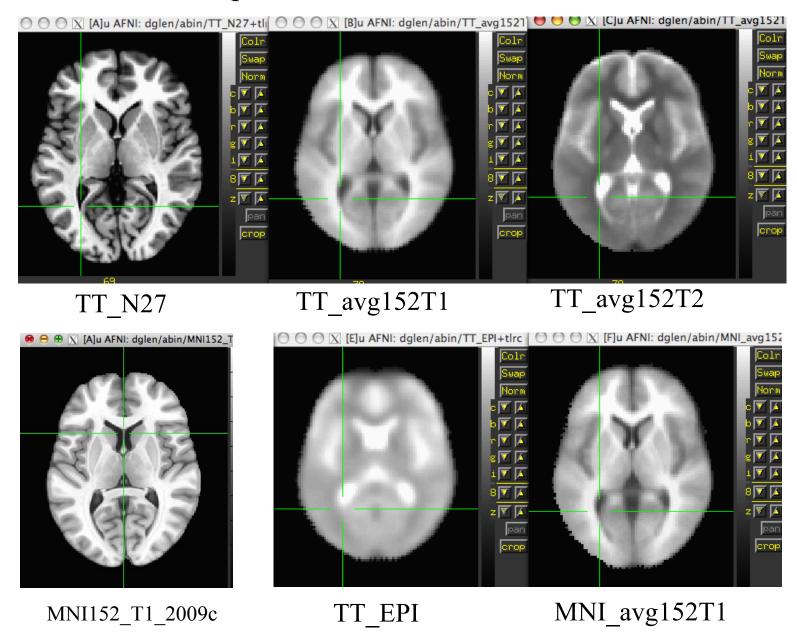


- Once all the markers are set, and the quality tests passed. Pressing [<u>Transform Data</u>] will write new *header* containing the Talairach transformations (see Appendix C for details)
 - ➤ Recall: With AFNI, spatial transformations are stored in the header of the output

- - Is manual selection of AC-PC and Talairach markers bringing you down? You can now perform a TLRC transform automatically using an AFNI script called @auto tlrc.
 - Differences from Manual Transformation:
 - ► Instead of setting ac-pc landmarks and volume boundaries by hand, the anatomical volume is warped (using 12-parameter affine transform) to a template volume in TLRC space.
 - → Anterior Commisure (AC) center no longer at 0,0,0 and size of brain box is that of the template you use.
 - For various reasons, some good and some bad, templates adopted by the neuroimaging community are not all of the same size. Be mindful when using various atlases or comparing standard-space coordinates.
 - ➤ You, the user, can choose from various templates for reference but be consistent in your group analysis.
 - ► Easy, automatic. Just check final results to make sure nothing went seriously awry. AFNI is perfect but your data is not.

- Templates in @auto tlrc that the user can choose from:
 - TT N27+tlrc
 - AKA "Colin brain". One subject (Colin) scanned 27 times and averaged. (www.loni.ucla.edu, www.bic.mni.mcgill.ca)
 - Has a full set of FreeSurfer (surfer.nmr.mgh.harvard.edu) surface models that can be used in SUMA (link).
 - Is the template for cytoarchitectonic atlases (www.fz-juelich.de/ime/spm_anatomy_toolbox)
 - For improved alignment with cytoarchitectonic atlases, I recommend using the TT_N27 template because the atlases were created for it. In the future, we might provide atlases registered to other templates.
 - TT icbm452+tlrc:
 - International Consortium for Brain Mapping template, average volume of 452 normal brains. (www.loni.ucla.edu, www.bic.mni.mcgill.ca)
 - TT avg152T1+tlrc:
 - Montreal Neurological Institute (www.bic.mni.mcgill.ca) template, average volume of 152 normal brains.
 - " TT_EPI+tlrc:
 - EPI template from spm2, masked as TT_avg152T1. TT_avg152 and TT_EPI volumes are based on those in SPM's distribution. (www.fil.ion.ucl.ac.uk/spm/)
 - MNI152 T1 2009c+tlrc:
 - MNI's 152 nonlinear asymmetric template

Templates included with AFNI



Steps performed by @auto_tlrc

- For warping a volume to a template (Usage mode 1):
 - Pad the input data set to avoid clipping errors from shifts and rotations
 - 2. Strip skull (if needed)
 - 3. Resample to resolution and size of TLRC template
 - 4. Perform 12-parameter affine registration using 3dWarpDrive

 Many more steps are performed in actuality, to fix up various

 pesky little artifacts. Read the script if you are interested.
 - Typically this steps involves a high-res anatomical to an anatomical template
 - ► Example: @auto_tlrc -base TT_N27+tlrc. -input anat+orig. -suffix NONE
 - One could also warp an EPI volume to an EPI template.
 - ➡ If you are using an EPI time series as input. You must choose one sub-brick to input. The script will make a copy of that sub-brick and will create a warped version of that copy.

Applying a transform to follower datasets

- Say we have a collection of datasets that are in alignment with each other. One
 of these datasets is aligned to a template and the same transform is now to be
 applied to the other follower datasets
- For Talairach transforms there are a few methods:
 - Method 1: Manually using the AFNI interface (see Appendix C)
 - Method 2: With program adwarp

```
adwarp -apar anat+tlrc -dpar func+orig
```

- → The result will be: func+tlrc.HEAD and func+tlrc.BRIK
- Method 3: With @auto_tlrc script in mode 2
 - ONLY when -apar dataset was created by @auto_tlrc
 - @auto_tlrc -apar SubjectHighRes+tlrc. \
 - -input Subject_EPI+orig. -dxyz 3
 - (the output is named Subject EPI at+TLRC, by default)
- Why bother saving transformed datasets to disk anyway?
 - ◆ Datasets without .BRIK files are of limited use, only for display of slice images

@auto_tlrc Example

- Transforming the high-resolution anatomical:
 - (If you are also trying the manual transform on workshop data, start with a fresh directory with no +tlrc datasets)

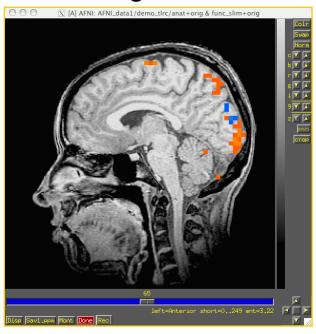
```
@auto_tlrc
   -base TT_N27+tlrc \
   -suffix NONE \
   -input anat+orig
Output:
anat+tlrc
```

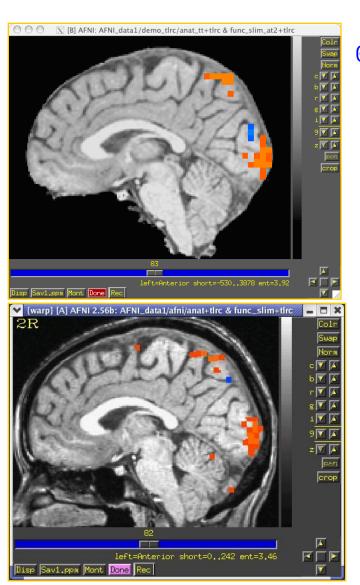
 Transforming the function ("follower datasets"), setting the resolution at 2 mm:

```
@auto_tlrc
-apar anat+tlrc \
-input func_slim+orig \
-suffix NONE \
-dxyz 2
Output:
func_slim+tlrc
```

 You could also use the icbm452 or the mni's avg152T1 template instead of N27 or any other template you like (see @auto_tlrc -help for a few good words on templates)

Original





@auto_tlrc

Manual

Standard Spaces

Why use a standard template space?

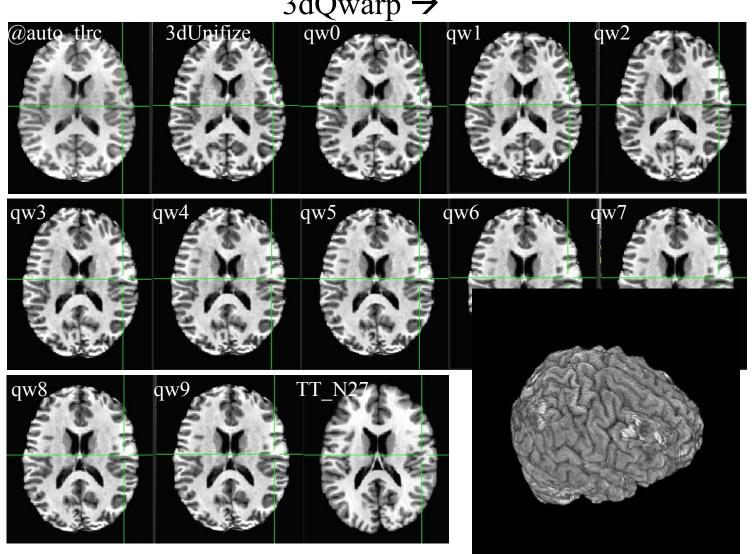
- Compare across subjects and groups easily for every voxel in the brain
- Standardize coordinates with others
- Know where a voxel is automatically from an atlas
- Mostly automated and no specific ROI drawing required

Why not use a standard template space?

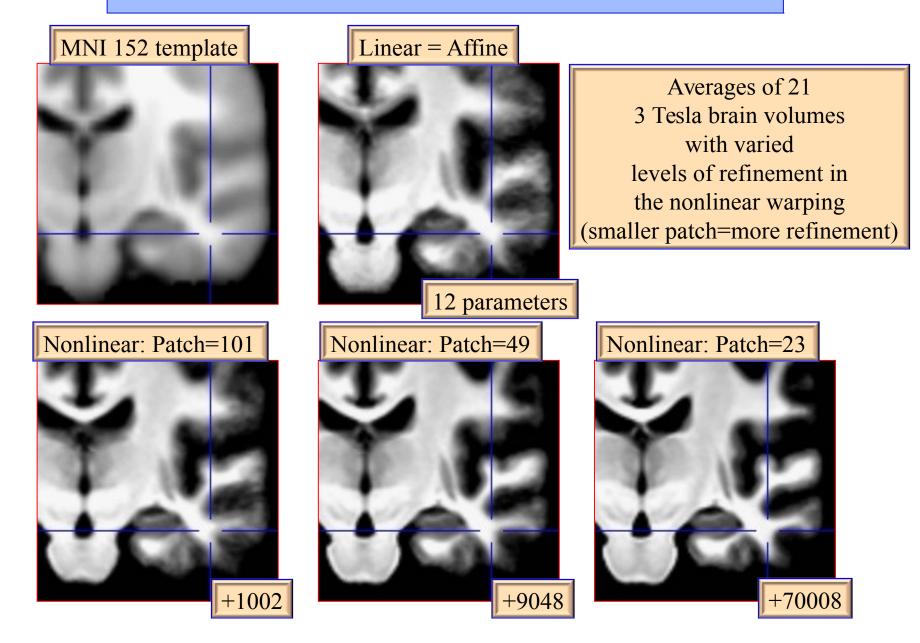
- Inconsistency among subjects
- Inconsistency among groups elderly versus younger
- Use consistent anatomical ROIs with good anatomical knowledge
- Lower threshold for multiple comparison adjustments

Nonlinear alignment to template

3dQwarp →



Example: Brain Averages



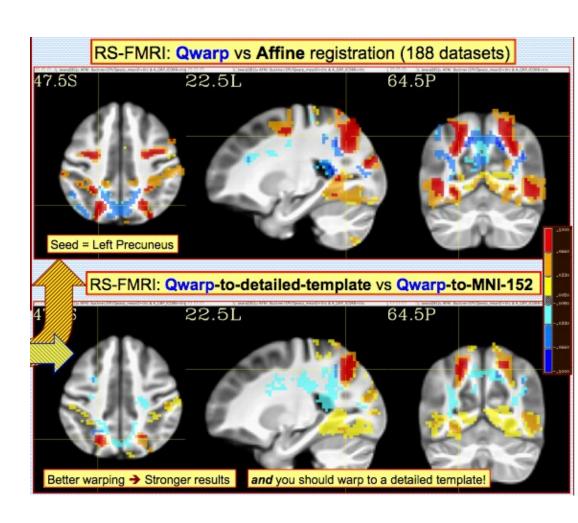
Nonlinear alignment

Advantages:

- Great alignment better spatial correspondence across data →
- Aligned data matches template

Disadvantages:

- Distortion of individual data
- Aligned data matches template.
 Choose template carefully
- End limits?
- Skullstripping must be done much more carefully
- Processing time much slower
- Not yet integrated into AFNI GUI for warp-on-demand



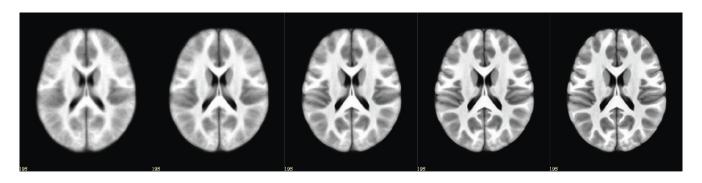
Comparing data

- How can I compare regions/voxels across subjects and groups?
 What works "best"?
 - @auto_tlrc affine registration method to align individual subjects to a template
 - auto_warp.py nonlinear alignment to template better.
 - manual Talairach based on specific markers divides data up based on AC-PC line and brain enclosing boxes. Better for looking at medial structures.
 - 3dTagalign place markers on specific corresponding points among datasets and align with affine transformation
 - ROI creation draw ROI's (Draw Dataset plug-in) for each structure

Choosing a template

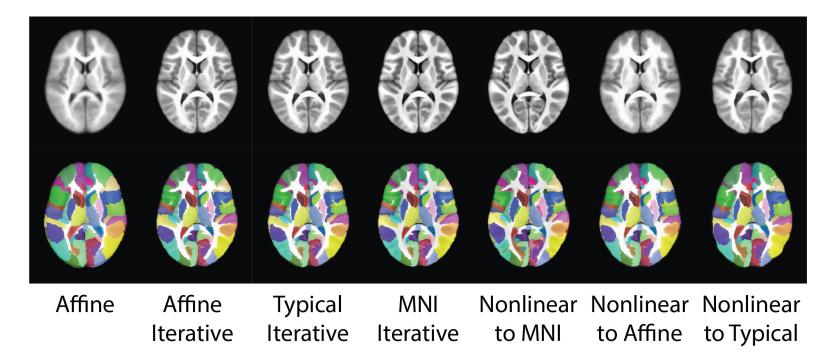
- Similar to subject group neonates, pediatric, young adults, elderly, macaque, rabbit...
- Same modality, similar coverage
- Relevant atlas segmentation
- Individual or group template
 - Group average or iterative
- Make your own template (and maybe an atlas too)
 - Haskins pediatric atlas research
 - → affine group averages
 - ➡ finding the most "typical" individual in group
 - → nonlinear alignment to typical
 - → iterative nonlinear alignment
 - @toMNI_Awarp, @toMNI_Qwarpar

ALTERNATIVE ATLAS CREATION TECHNIQUES: ITERATIVE AND TYPICAL METHODS

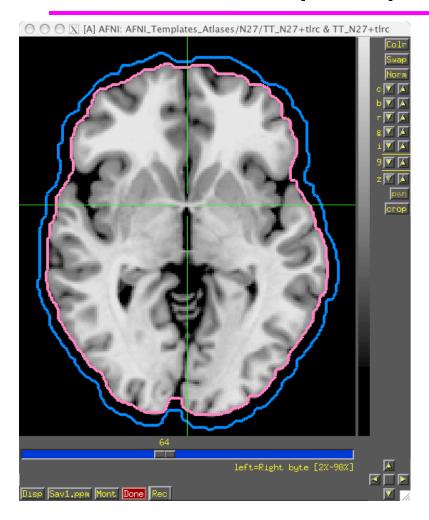


Iterative nonlinear alignment to affine template with progressively smaller patch sizes

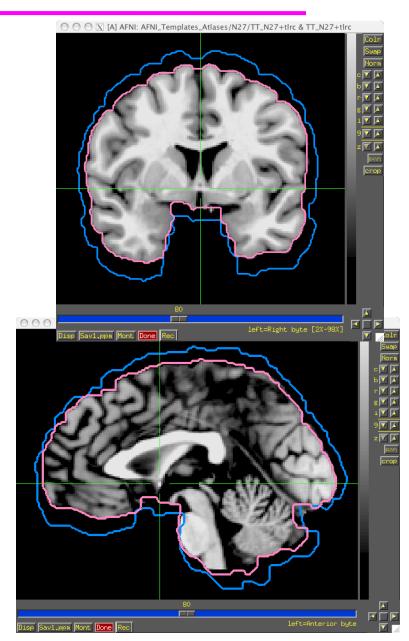
"Typical" Brain



Atlas/Template Spaces Differ In Size



MNI is larger than TLRC space.



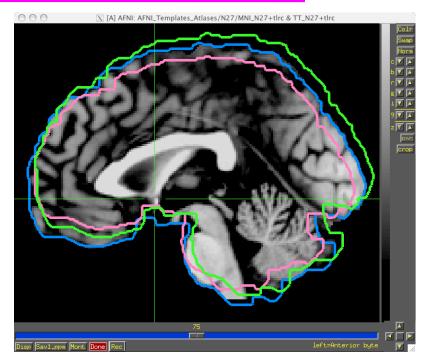
Atlas/Template Spaces Differ In Origin

TLRC MNI MNI-Anat.



From Space To Space

TLRC MNI MNI-Anat.



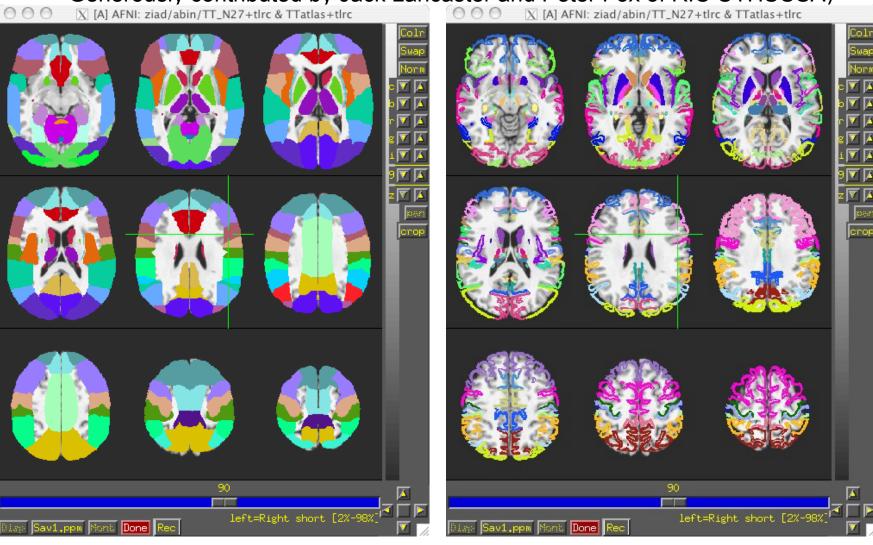
- Going between TLRC and MNI:
 - Approximate equation
 - used by whereami and 3dWarp
 - Manual TLRC transformation of MNI template to TLRC space
 - used by whereami (as precursor to MNI Anat.), based on N27 template
 - Multiple space coordinates reported in whereami output (AFNI_ATLAS_TEMPLATE_SPACE_LIST)
- Going between MNI and MNI Anatomical (Eickhoff et al. Neuroimage 25, 2005):
 - MNI + (0, 4, 5) = MNI Anat. (in RAI coordinate system)
- Going between TLRC and MNI Anatomical (as practiced in whereami):
 - Go from TLRC (TT_N27) to MNI via manual xform of N27 template
 - Add (0, 4, 5)

Atlases/Templates Use Different Coord. Systems

- There are 48 manners to specify XYZ coordinates
- Two most common are RAI/DICOM and LPI/SPM
- RAI means
 - ♦ X is Right-to-Left (from negative-to-positive)
 - ♦ Y is Anterior-to-Posterior (from negative-to-positive)
 - Z is Inferior-to-Superior (from negative-to-positive)
- LPI means
 - ♦ X is Left-to-Right (from negative-to-positive)
 - Y is Posterior-to-Inferior(from negative-to-positive)
 - Z is Inferior-to-Superior (from negative-to-positive)
- To go from RAI to LPI just flip the sign of the X and Y coordinates
 - Voxel -12, 24, 16 in RAI is the same as 12, -24, 16 in LPI
 - Voxel above would be in the Right, Posterior, Superior octant of the brain
- AFNI allows for all coordinate systems but default is RAI
 - Can use environment variable AFNI_ORIENT to change the default for AFNI AND other programs.
 - See whereami -help for more details.

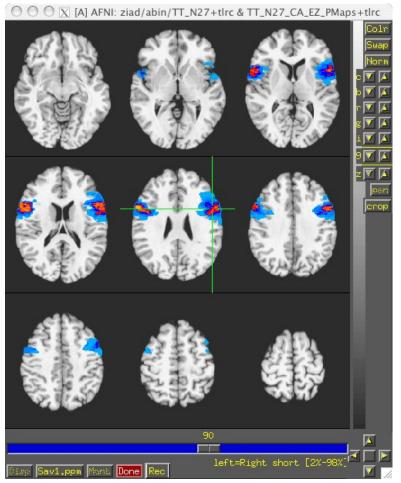
Atlases Distributed With AFNI TT_Daemon

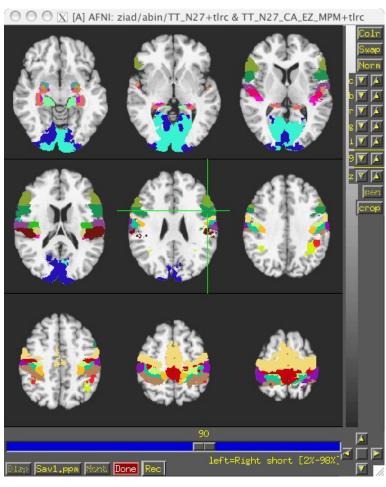
- TT_Daemon : Created by tracing Talairach and Tournoux brain illustrations.
 - Generously contributed by Jack Lancaster and Peter Fox of RIC UTHSCSA)



Atlases Distributed With AFNI Anatomy Toolbox: Prob. Maps, Max. Prob. Maps

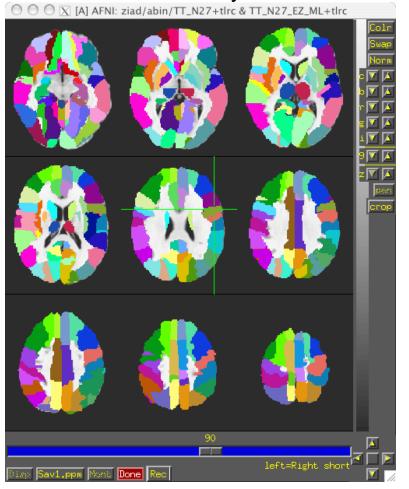
- CA_N27_MPM, CA_N27_ML, CA_N27_PM: Anatomy Toolbox's atlases with some created from cytoarchitectonic studies of 10 human post-mortem brains
 - Generously contributed by Simon Eickhoff, Katrin Amunts and Karl Zilles of IME, Julich, Germany

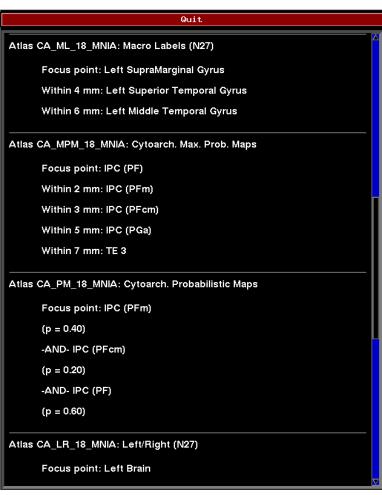




Atlases Distributed With AFNI: Anatomy Toolbox: MacroLabels

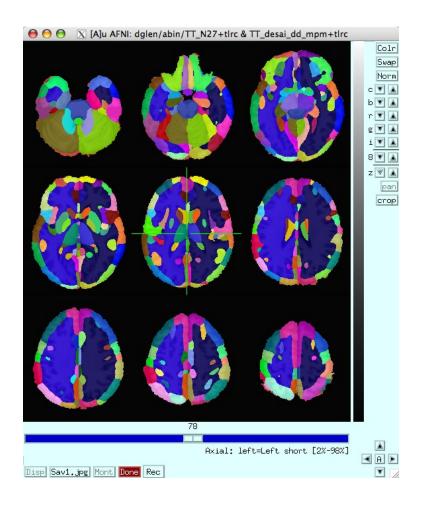
- CA_N27_MPM, CA_N27_ML, CA_N27_PM: Anatomy Toolbox's atlases with some created from cytoarchitectonic studies of 10 human post-mortem brains
 - Generously contributed by Simon Eickhoff, Katrin Amunts and Karl Zilles of IME, Julich, Germany

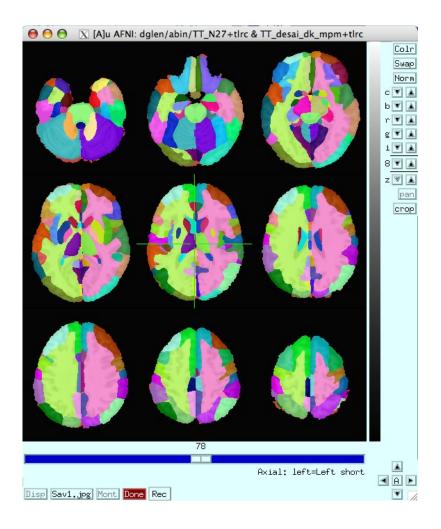




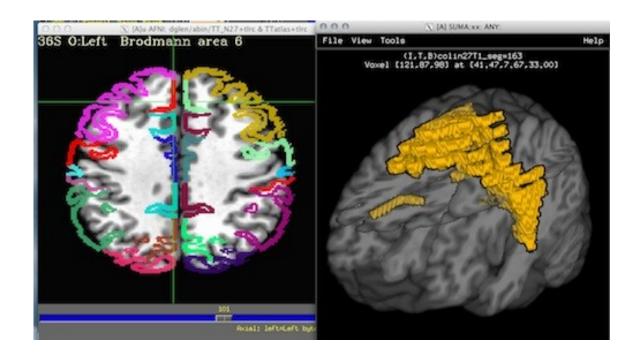
Atlases Distributed With AFNI: Desai PMaps and MPMs

 Atlases generated with typical AFNI pipeline using @auto_tlrc and FreeSurfer segmentation across multiple subjects





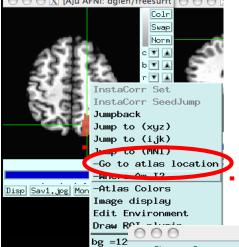
Talairach Daemon (TT_Daemon) problem



-63-

Some fun and useful things to do with +tlrc datasets are on the 2D slice viewer

Right click to get menu: [O O N [A]u AFNI: dglen/freesurft [O O D



Go to Atlas Location

Lets you jump to centroid of regions to current default atlas (set by AFNI_ATLAS_COLORS)
Works in +orig too

```
X menu
   -Choose One----
Brain Structure (from DD_Desai_MPM)
ctx_lh_G_and_S_cingul-Mid-Ant [ 3,-13, 32]
ctx_lh_G_and_S_cingul-Mid-Post [ 4, 15, 38]
ctx_lh_G_cingul-Post-dorsal [ 2, 39, 28]
ctx_lh_G_cingul-Post-ventral [ 4, 45, 5]
ctx_lh_G_cuneus [ 1, 81, 14]
ctx_lh_G_front_inf-Opercular [ 49,-12, 13]
ctx_lh_G_front_inf-Orbital [ 46,-28, -5]
ctx_lh_G_front_inf-Triangul [ 49,-30, 8]
ctx_lh_G_front_middle [ 35,-31, 36]
ctx_1h_G_front_sup [ 8,-22, 47]
ctx_lh_G_Ins_lg_and_S_cent_ins [ 37, 8, 5]
ctx_lh_G_insular_short [ 36, -9, 0]
ctx_lh_G_occipital_middle [ 38, 82, 9]
ctx_lh_G_occipital_sup [ 12, 89, 27]
ctx_lh_G_oc-temp_lat-fusifor [ 32, 43,-18]
ctx_lh_G_oc-temp_med-Lingual [ 5, 68, -8]
ctx_lh_G_oc-temp_med-Parahip [ 20, 12,-24]
ctx_lh_G_orbital [ 27,-34,-12]
ctx_lh_G_pariet_inf-Angular [ 43, 66, 35]
ctx_lh_G_pariet_inf-Supramar [ 56, 37, 33]
ctx_lh_G_parietal_sup [ 21, 63, 53]
ctx_lh_G_postcentral [ 44, 28, 52]
ctx_lh_G_precentral [ 41, 10, 49]
ctx_lh_G_precuneus [ 3, 58, 36]
ctx_lh_G_rectus [ 2,-38,-14]
     Quit
                      Apply
Index ▲ ▼ 15
```

[Where am I?]

Shows you where you are in various atlases and spaces

(works in +orig too, if you have a transformed parent)

For atlas installation, and much, much more, see help in command line version:

whereami -help

Quit AFNI whereami +++++ nearby Atlas structures ++++++ Original input data coordinates in TT N27 space Focus point (LPI)= -54 mm [L], -43 mm [P], 25 mm [S] {TLRC} -58 mm [L], -44 mm [P], 27 mm [S] {MNI} NeuroSynth SumsDB -58 mm [L], -48 mm [P], 32 mm [S] {MNI_ANAT} Atlas HaskinsPeds NL atlas1.0: session atlas Focus point: ctx-lh-superiortemporal Within 4 mm: ctx-lh-supramarginal Within 5 mm: ctx-lh-bankssts Within 7 mm: ctx-lh-inferiorparietal Atlas TT Daemon: Talairach-Tournoux Atlas Focus point: Left Inferior Parietal Lobule -AND- Left Brodmann area 40 Within 2 mm: Left Supramarginal Gyrus Within 3 mm: Left Brodmann area 13 Within 4 mm: Left Superior Temporal Gyrus Within 5 mm: Left Brodmann area 22 Within 6 mm: Left Insula

- whereami can provide the user with more detailed information regarding the output of 3dclust
 - For instance, say you want more information regarding the center of mass voxels from each cluster (from the 3dclust output). I.e., where do they fall approximately within the atlases?

```
3dclust -dxyz=1 -1clip 9.5 1 1000 func_FullF+tlrc > clusts.1D
whereami -coord_file clusts.1D'[1,2,3] -tab | less
```

```
++ Input coordinates orientation set by default rules to RAI
++ Input coordinates space set by default rules to TLRC
++++++ nearby Atlas structures ++++++
Focus point (LPI)
                                        Coord.Space
 42 mm [R], -61 mm [P], -3 mm [I]
                                       {T-T Atlas}
 43 mm [R], -63 mm [P], -7 mm [I]
                                       {MNI Brain}
 45 mm [R], -69 mm [P],
                          2 mm [I]
                                        {MNI Anat.}
Atlas
               Within Label
                                                                Prob.
                                                                        Code
               3.0
                       Right Middle Occipital Gyrus
                                                                        33
TT_Daemon
TT_Daemon
               3.0
                       Right Brodmann area 37
                                                                        113
TT_Daemon
                4.0
                       Right Inferior Temporal Gyrus
                                                                        29
                       Right Middle Temporal Gyrus
                                                                        35
TT_Daemon
                4.0
                       Right Inferior Occipital Gyrus
                                                                        28
TT_Daemon
               6.0
                       Right Brodmann area 19
                                                                        96
TT_Daemon
               7.0
CA_N27_MPM
                4.0
                       hOC5 (V5 / MT+)
                                                                 MPM
                                                                        110
CA_N27_ML
               0.0
                       Right Inferior Temporal Gyrus
                                                                        90
                                                                        86
CA_N27_ML
               1.0
                       Right Middle Temporal Gyrus
                       Right Inferior Occipital Gyrus
                                                                        54
CA_N27_ML
               5.0
                                                                        52
CA_N27_ML
               6.0
                        Right Middle Occipital Gyrus
****** Please use results with caution!
******* Brain anatomy is quite variable!
******* The database may contain errors! ******
```

Center of mass output, columns 1,2,3, from 3dclust output

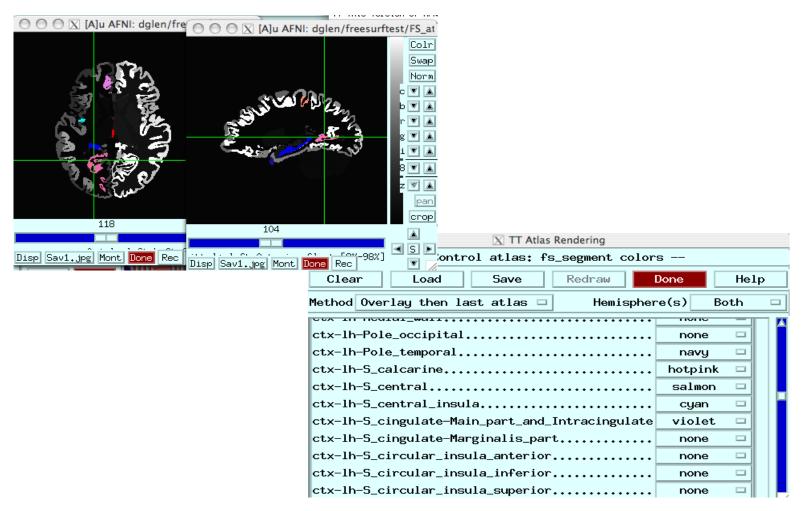
Shown: Cluster #1's coordinates according to various atlases (TT, MNI, etc), as well as the name of the anatomical structure that is located at or near these coordinates (which may vary by atlas)

 whereami can report on the overlap of ROIs with atlasdefined regions

whereami -omask anat_roi+tlrc

```
++ Input coordinates orientation set by default rules to RAI
++ Input coordinates space set by default rules to TLRC
++ In ordered mode ...
++ Have 2 unique values of:
   0 1
++ Skipping unique value of 0
++ Processing unique value of 1
     195 voxels in ROI
      195 voxels in atlas-resampled mask
Intersection of ROI (valued 1) with atlas TT_Daemon (sb0):
  89.2 % overlap with Middle Occipital Gyrus, code 33
  6.7 % overlap with Middle Temporal Gyrus, code 35
  95.9 % of cluster accounted for.
Intersection of ROI (valued 1) with atlas TT_Daemon (sb1):
  19.5 % overlap with Brodmann area 37, code 113
  1.5 % overlap with Brodmann area 19, code 96
  21.0 % of cluster accounted for.
      195 voxels in atlas-resampled mask
Intersection of ROI (valued 1) with atlas CA_N27_MPM (sb0):
  1.5 % overlap with hOC5 (V5 / MT+), code 110
  1.5 % of cluster accounted for.
      195 voxels in atlas-resampled mask
Intersection of ROI (valued 1) with atlas CA_N27_ML (sb0):
   61.0 % overlap with Right Middle Occipital Gyrus, code 52
  20.0 % overlap with Right Middle Temporal Gyrus, code 86
  81.0 % of cluster accounted for.
```

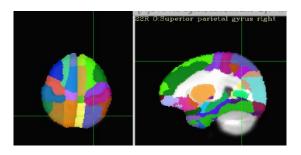
\$ [Atlas colors]

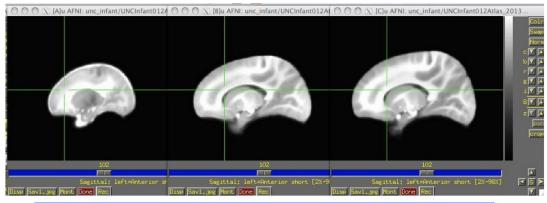


Lets you show atlas regions over your own data (works only in +tlrc).

Atlases and Templates Available!

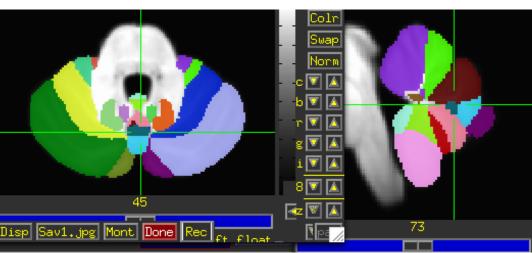
 Infant brain atlas and templates – neonate, 1-year, 2-year.
 Contributed by Feng Shi, UNC





UNC infant templates and atlases – neonate, 1 yr, 2 yr old

 Cerebellum atlas and templates – Jorn Diedrichsen, UCL, UK contribution

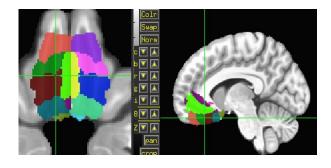


More Atlases and Templates Available!

Ventromedial Prefrontral Cortex (vmPFC, Scott Mackey)

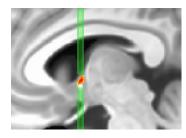
Waxholm Rat Atlas - Papp, et al. Rat brain templates in Paxinos space – Karolinska Institute, Woo Hyun Shim MGH contributions

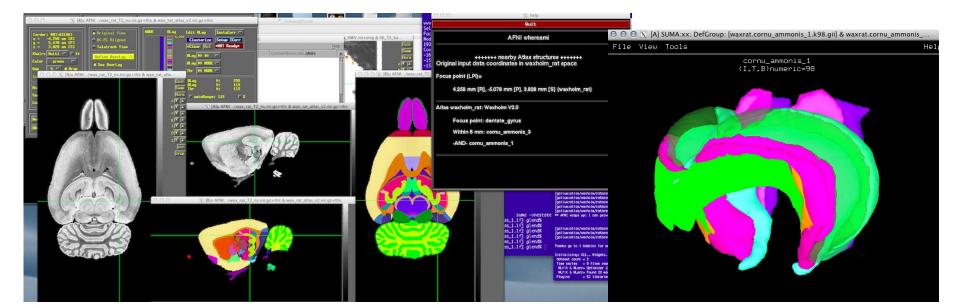
BNST – Torrisi, NIMH



All of these are user requests or contributions!

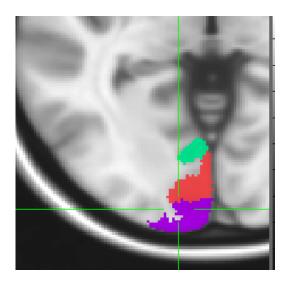
What do you need?

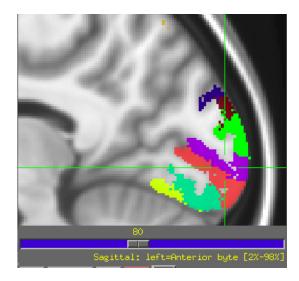




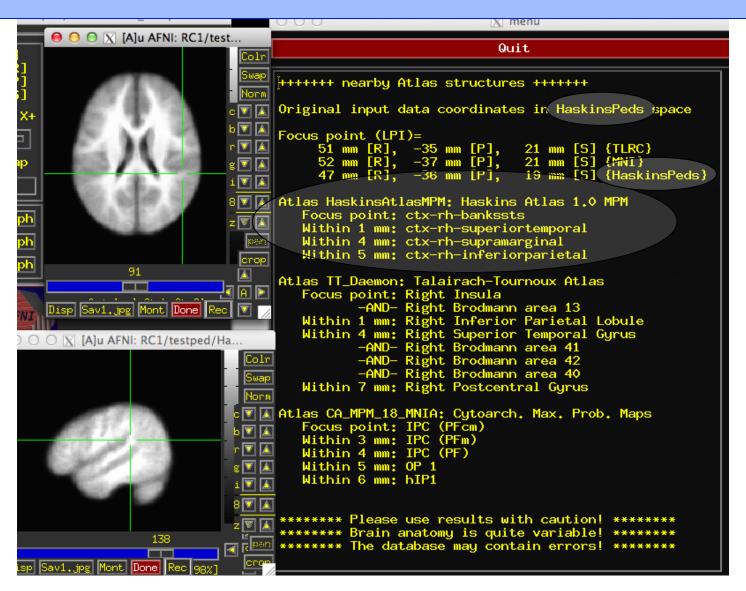
Upcoming atlases

- Eickhoff-Zilles 2.2 cytoarchitectonic atlases
- DTI fiber atlas Susumo Mori
- Princeton Visual Field Map, Kastner, et al.





Haskins Pediatric Atlas



Make your own atlas!

- New atlases easy and fun. Make your own!
 - make available in AFNI GUI and whereami and to other user

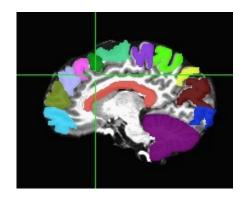
```
@AfniEnv -set AFNI_SUPP_ATLAS_DIR ~/MyCustomAtlases/
Then:
```

In ~/MyCustomAtlases/ you will now find atlas_for_all.nii along along with a modified CustomAtlases.niml file.

Individual Subjects



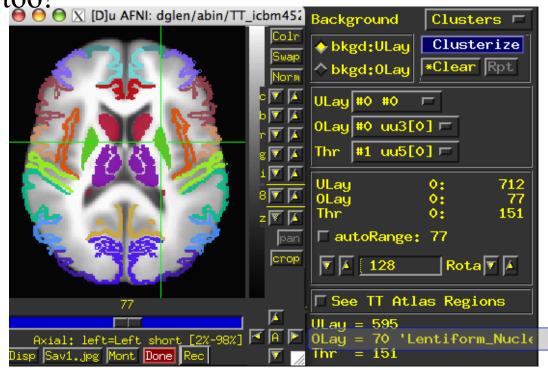
FreeSurfer segmentation



Manual segmentation

@SUMA_MakeSpecFS — atlasizes
too!

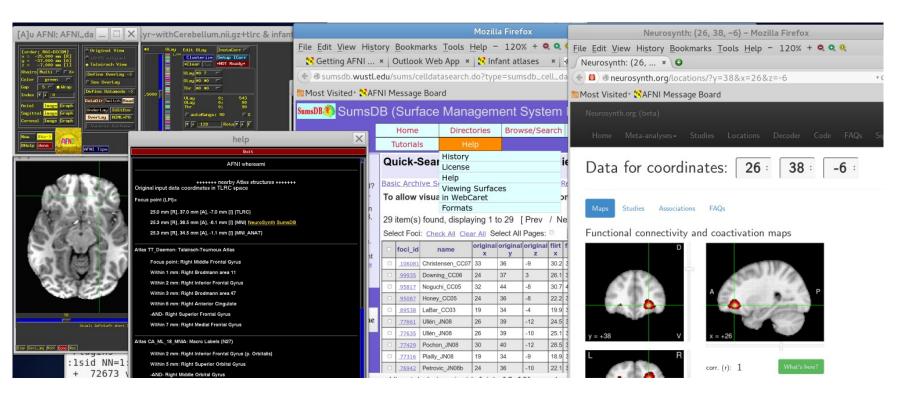
| Dig AFNI: dglen/abin/TT_icbm452 | Background | Clu



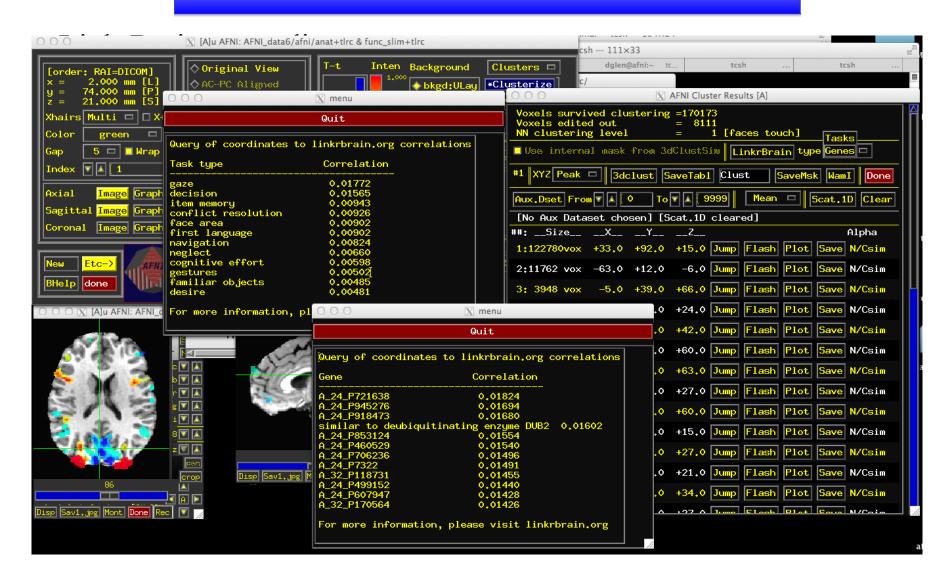
Overlay panel shows structure name. Now FreeSurfer segmentation can also be used in whereami

Web-based atlases

NeuroSynth, LinkrBrain, BrainMap.org, Allen Brain, ...

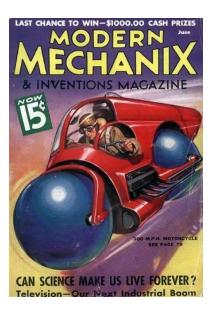


Web-based atlases

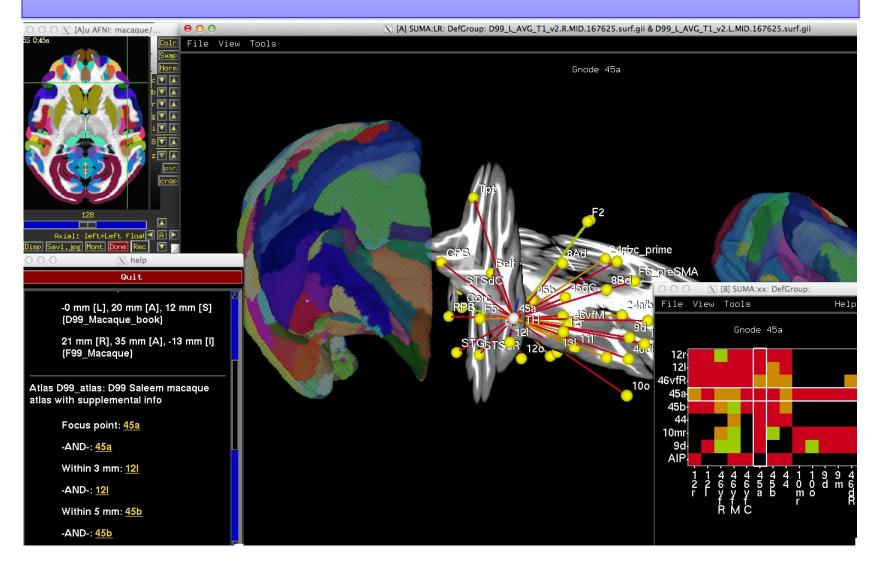


In Development

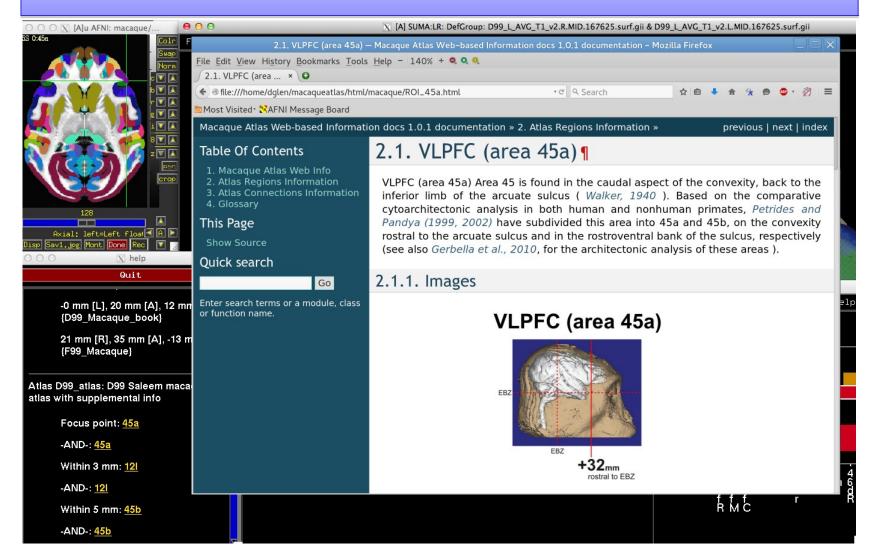
- New templates and template spaces fully supported in AFNI
 - macaque
 - ♦ rat, mouse, human
 - ♦ pediatric, ...
- On-the-fly transformations through all available template spaces
- Extra information about atlas structures
- HAWG standardized format atlases for everyone!



Saleem macaque atlas – MRI, surfaces, connections, supplemental webpages (in development)



Saleem macaque atlas – MRI, surfaces, connections, supplemental webpages (in development)

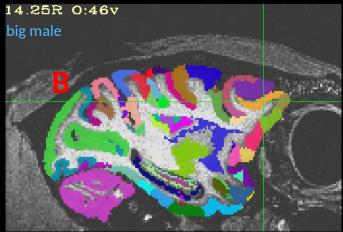


Mapping the digital atlas onto different macaques MRI



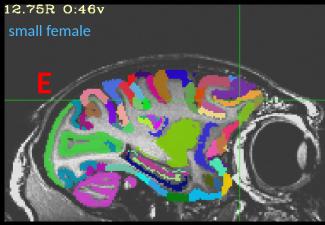
D99 - Digital atlas

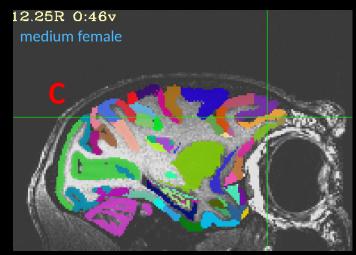
Reveley, Gruslys, Ye, Samaha, Glen, Saad, Seth, Leopold, and Saleem (in preparation)

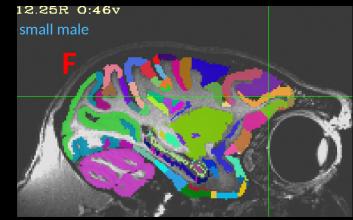


Spatial transformation of the atlas segmentation to each macaque's native space



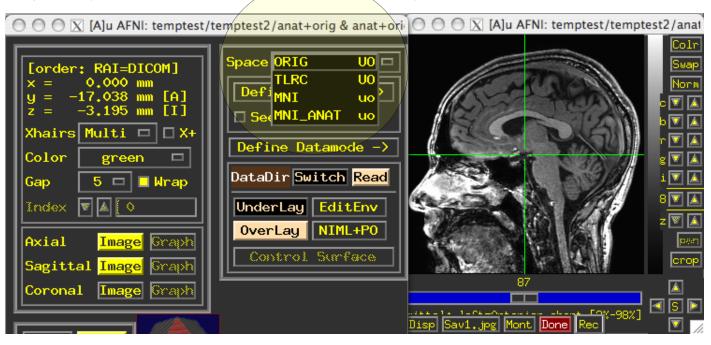






Atlas Spaces – Warp-on-demand (in development)

Not just your father's Talairach anymore....



Atlas Conclusions and Questions



Charles Atlas

Appendix A

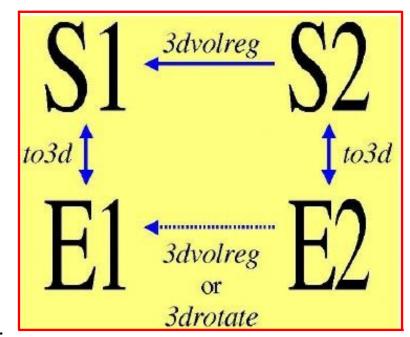
Inter-subject, inter-session registration

- Intra-subject, inter-session registration (for multi-day studies on same subject)
 - Longitudinal or learning studies; re-use of cortical surface models

Transformation between sessions is calculated by registering high-resolution

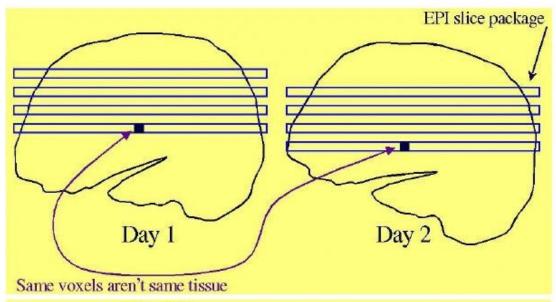
anatomicals from each session

- 3dvolreg computes relationship between sessions
- So can transform EPI from session 2 to orientation of session 1

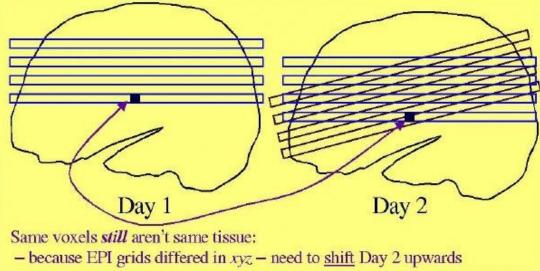


- Issues in inter-session registration:
 - Subject's head will be positioned differently (in orientation and location)
 - xyz-coordinates and anatomy don't correspond
 - → Anatomical coverage of EPI slices will differ between sessions
 - ➡ Geometrical relation between EPI and SPGR differs between session
 - Slice thickness may vary between sessions (try not to do this, OK?)

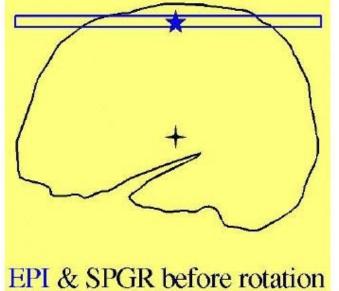
Anatomical coverage differs



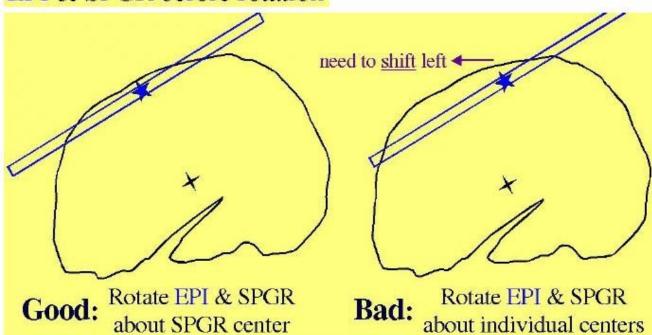
At acquisition:
 Day 2 is rotated relative to Day 1



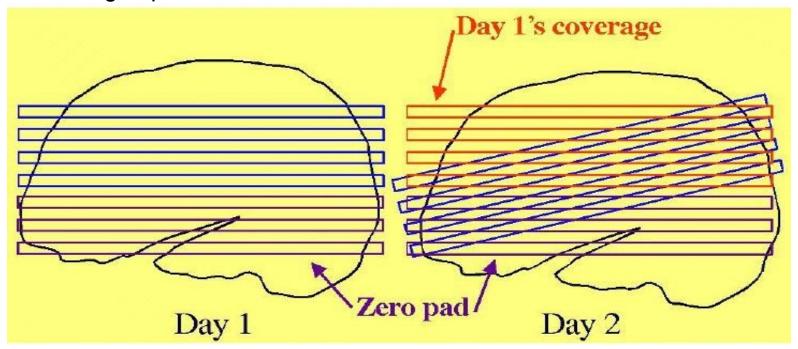
 After rotation to same orientation, then clipping to Day 2 xyz-grid



 Another problem: rotation occurs around center of individual datasets



- Solutions to these problems:
 - → Add appropriate shift to E2 on top of rotation
 - Allow for xyz shifts between days (E1-E2), and center shifts between EPI and SPGR (E1-S1 and E2-S2)
 - → Pad EPI datasets with extra slices of zeros so that aligned datasets can fully contain all data from all sessions
 - → Zero padding of a dataset can be done in to3d (at dataset creation time), or later using 3dZeropad
 - → 3dvolreg and 3drotate can zero pad to make the output match a "grid parent" dataset in size and location



- Recipe for intra-subject S2-to-S1 transformation:
 - 1. Compute S2-to-S1 transformation:

```
3dvolreg -twopass -zpad 4 -base S1+orig \ -prefix S2reg S2+orig for larger motions
```

- ► Rotation/shift parameters are saved in S2reg+orig. HEAD
- 2. If not done before (e.g., in to3d), zero pad E1 datasets:

```
3dZeropad -z 4 -prefix E1pad E1+orig
```

1. Register E1 datasets within the session:

```
3dvolreg -base 'Elpad+orig[4]' -prefix Elreg \
     Elpad+orig
```

Register E2 datasets within the session, at the same time executing larger rotation/shift to session 1 coordinates that were saved in S2reg+orig.HEAD:

- 2. -rotparent tells where the inter-session transformation comes from
- 3. -gridparent defines the output grid location/size of new dataset
 - Output dataset will be shifted and zero padded as needed to lie on top of E1reg+orig

- Recipe above does not address problem of having different slice thickness in datasets of the same type (EPI and/or SPGR) in different sessions
 - ➡ Best solution: pay attention when you are scanning, and always use the same slice thickness for the same type of image
 - → OK solution: use 3dZregrid to linearly interpolate datasets to a new slice thickness
- Recipe above does not address issues of slice-dependent time offsets stored in data header from to3d (e.g., 'alt+z')
 - → After interpolation to a rotated grid, voxel values can no longer be said to come from a particular time offset, since data from different slices will have been combined
 - ➡ Before doing this spatial interpolation, it makes sense to time-shift dataset to a common temporal origin
 - → Time shifting can be done with program 3dTshift
 - Or by using the -tshift option in 3dvolreg, which first does the time shift to a common temporal origin, then does the 3D spatial registration
- Further reading at the AFNI web site
 - File README.registration (plain text) has more detailed instructions and explanations about usage of 3dvolreg
 - File regnotes.pdf has some background information on issues and methods used in FMRI registration packages

Appendix B

3dAllineate for the curious

3dAllineate:

More than you want to know

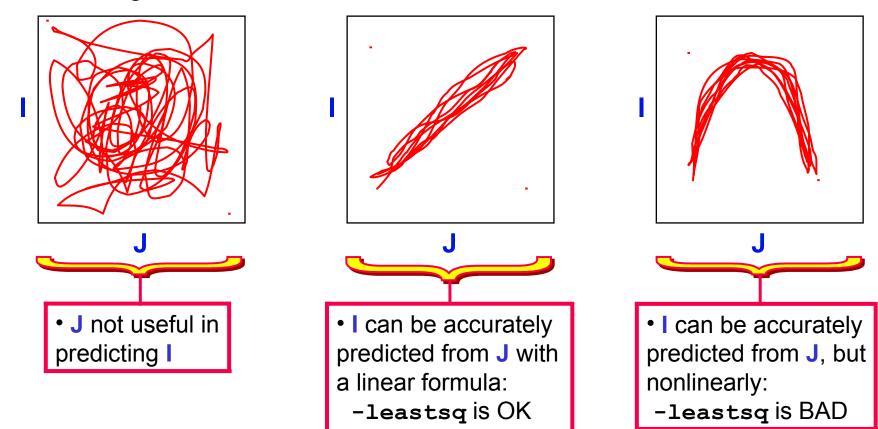
Algorithmic Features

- Uses Powell's NEWUOA software for minimization of general cost function
- Lengthy search for initial transform parameters if two passes of registration are turned on [which is the default]
 - Random and grid search through hundreds of parameter sets for 15 good (low cost) parameter sets
 - Optimize a little bit from each 'good' set, using blurred images
 - ➡ Blurring the images means that small details won't prevent a match
 - Keep best 4 of these parameter sets, and optimize them some more [keeping 4 sets is the default for -twobest option]
 - → Amount of blurring is reduced in several stages, followed by re-optimization of the transformation parameter sets on these less blurred images
 - → -twofirst does this for first sub-brick, then uses the best parameter sets from the first sub-brick as the starting point for the rest of the sub-bricks [the default]
 - Use best 1 of these parameter sets as starting point for fine (un-blurred) parameter optimization
 - → The slowest part of the program

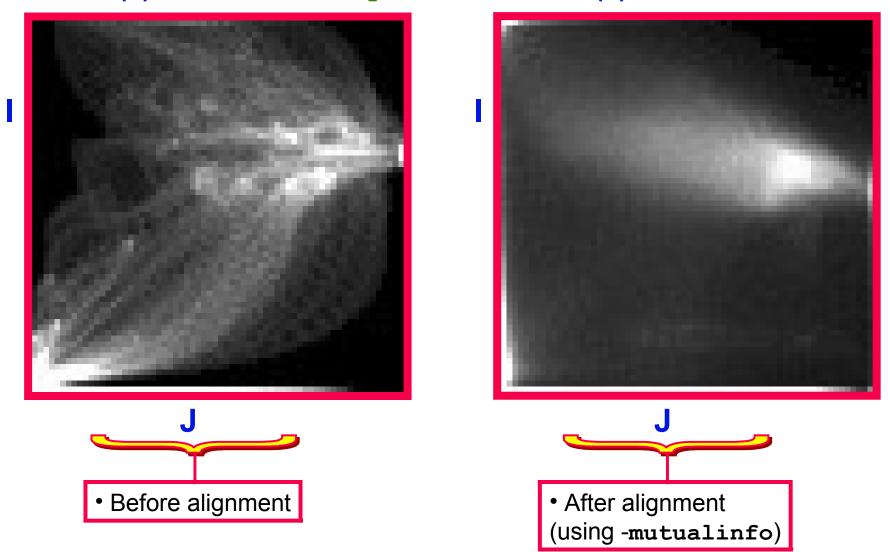
Algorithmic Features

- Goal is to find parameter set w such that E[J(x), I(T(x,w))] is small
 - ♦ T(x,w) = spatial transformation of x given w
 - ♦ J() = base image, I() = target image, E[] = cost function
- For each x in base image space, compute T(x,w) and then interpolate I() at those points
 - For speed, program doesn't use all points in J(), just a scattered collection of them, selected from an automatically generated mask
 - → Mask can be turned off with -noauto option
 - → At early stages, only a small collection of points [default=23456] is used when computing E[]
 - → At later stages, more points are used, for higher accuracy
 - Recall that each stage is less blurred than the previous stages
 - Large fraction of CPU time is spent in interpolation of image I() over the collection of points used to compute E[]

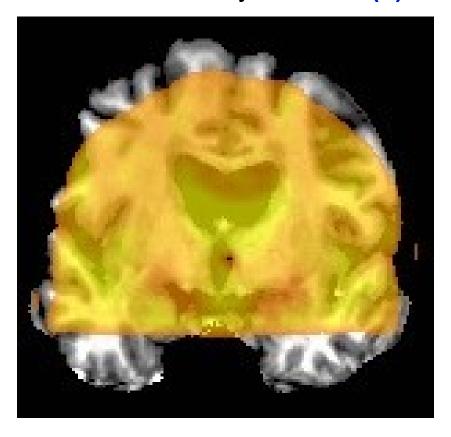
• Histogram cartoons:



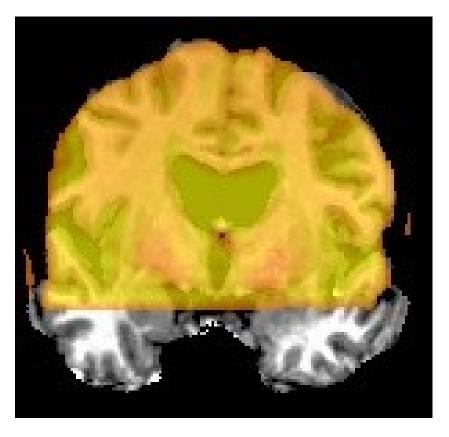
Actual histograms from a registration example



- grayscale underlay = J(x) = 3dSkullStrip-ed MPRAGE
- color overlay = I(x) = EPI volume





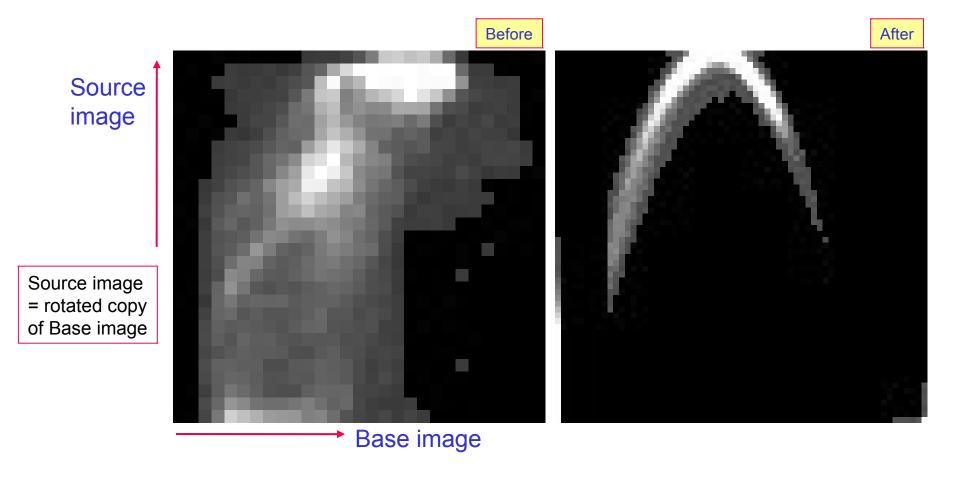


• After alignment (using -mutualinfo)

- Other <u>3dAllineate</u> capabilities:
 - ♦ Save transformation parameters with option -1Dfile in one program run
 - Re-use them in a second program run on another input dataset with option
 -1Dapply
 - ♦ Interpolation: linear (polynomial order = 1) during alignment
 - → To produce output dataset: polynomials of order 1, 3, or 5
- Algorithm details:
 - Initial alignment starting with many sets of transformation parameters, using only a limited number of points from smoothed images
 - ♦ The best (smallest E) sets of parameters are further refined using more points from the images and less blurring
 - This continues until the final stage, where many points from the images and no blurring is used
- So why not <u>3dAllineate</u> all the time?
 - Alignment with cross-modal cost functions do not always converge as well as those based on least squares.
 - See Appendix B for more info.
 - Improvements are still being introduced

Cost Functions

- Except for least squares (actually, ls minimizes E=1.0-Pearson correlation coefficient), all cost functions are computed from 2D joint histogram of J(x) and I(T(x,w))
 - Start and final histograms can be saved using hidden option -savehist



Histogram Based Cost Functions

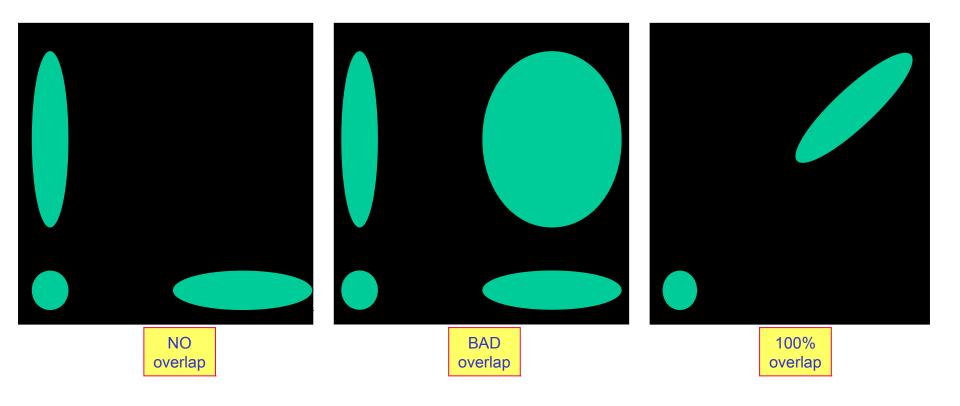
- Goal is to make 2D histogram become 'simple' in some sense, as a measurement of 'predictability' between J(x) and I(T(x,w))
- Entropy H() of a histogram (finite number of bins):
 - ♦ {p_i} = probabilities of index i occuring
 - $\Rightarrow H(\{p_i\}) = -\sum_i p_i \log_2(p_i) > 0$
 - H({p_i}) = Number of bits needed to encode a single value randomly drawn from the probabilities {p_i}
 - Smaller entropy H means the values are 'simpler' to encode
 - Largest H is for uniform histogram (all p_i equal)

Mutual Information

- Entropy of 2D histogram
 - $\Rightarrow H(\lbrace r_{ij}\rbrace) = \prod_{ij} r_{ij} \log_2(r_{ij})$
 - Number of bits needed to encode value <u>pairs</u> (i,j)
- Mutual Information between two distributions
 - Marginal (1D) histograms {p_i} and {q_i}
 - Φ MI = H({p_i}) + H({q_i}) H({r_{ii}})
 - Number of bits required to encode 2 values separately minus number of bits required to encode them together (as a pair)
 - ♦ If 2D histogram is independent (r_{ij}= p_i → q_i) then MI = 0 = no gain from joint encoding
- 3dAllineate minimizes E[J,I] = -MI(J,I) with -cost mi

Normalized MI

- NMI = $H(\{r_{ii}\})$ / [$H(\{p_i\}) + H(\{q_i\})$]
 - Ratio of number of bits to encode value pair divided by number of bits to encode two values separately
 - Minimize NMI with -cost nmi
- Some say NMI is more robust for registration than MI, since MI can be large when there
 is no overlap between the two images

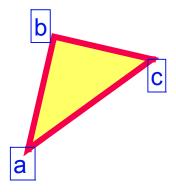


Hellinger Metric

- MI can be thought of as measuring a 'distance' between two 2D histograms: the
 joint distribution {r_{ii}} and the product distribution {p_i ~ q_i}
 - MI is not a 'true' distance: it doesn't satisfy triangle inequality d(a,b)+d(b,c) > d(a,c)
- Hellinger metric is a true distance in distribution "space":

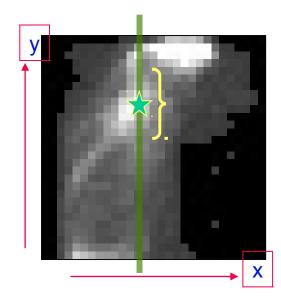
$$\rightarrow$$
 HM = $\sum_{ij} [\sqrt{r_{ij}} - \sqrt{(p_i - q_j)}]^2$

- 3dAllineate minimizes –HM with -cost hel
- This is the default cost function



Correlation Ratio

- Given 2 (non-independent) random variables x and y
 - Exp[y|x] is the expected value (mean) of y for a fixed value of x
 - Exp[a|b] ≡ Average value of 'a', given value of 'b'
 - Var(y|x) is the variance of y when x is fixed = amount of uncertainty about value of y when we know x
 - \rightarrow v(x) ≡ Var(y|x) is a function of x only

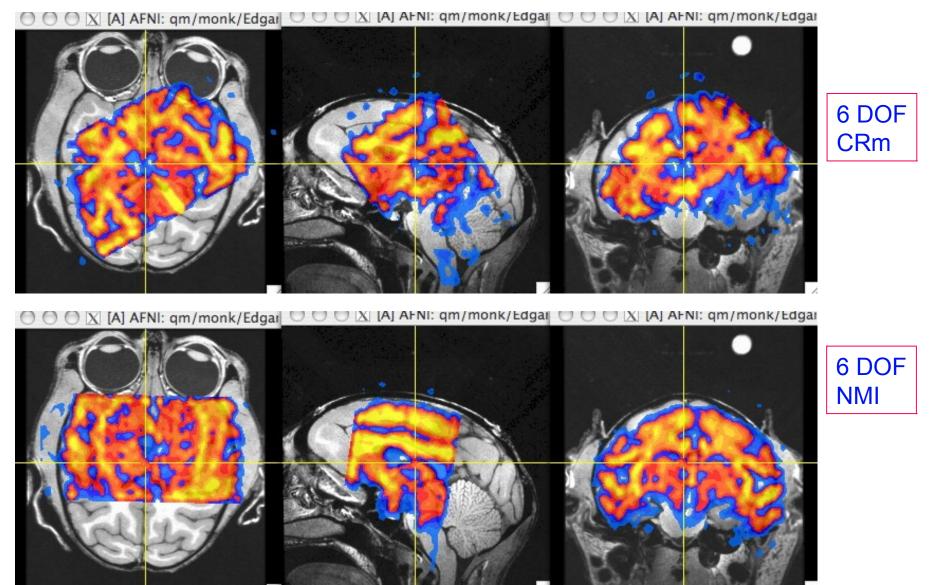


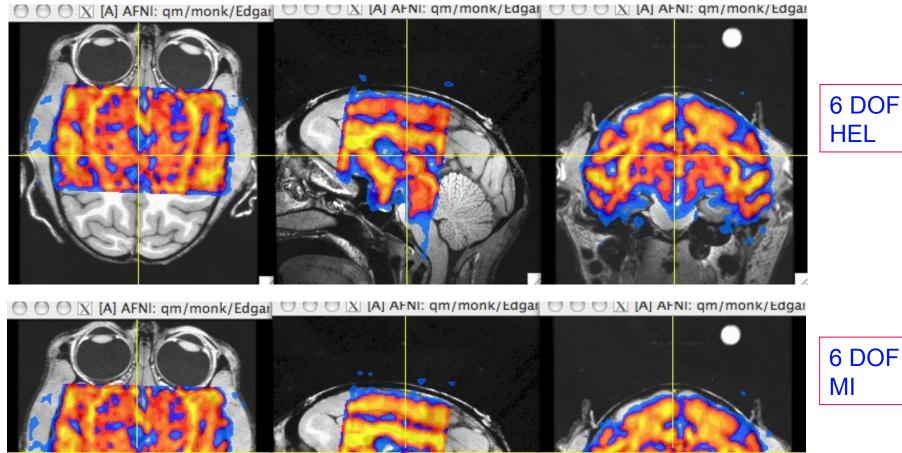
- $CR(x,y) \equiv 1 Exp[v(x)] / Var(y)$
 - Relative reduction in uncertainty about value of y when x is known; large CR means Exp[y|x] is a good prediction of the value of y given the value of x
 - Does not say that Exp[x|y] is a good prediction of the x given y
 - CR(x,y) is a generalization of the Pearson correlation coefficient, which assumes that $Exp[y|x] = \alpha \cdot x + \beta$

3dAllineate's Symmetrical CR

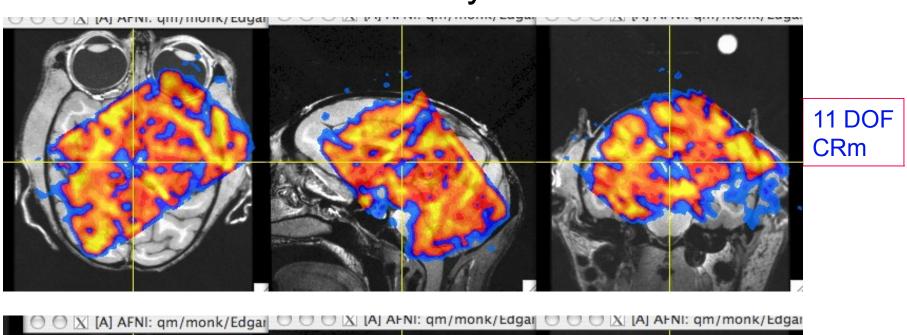
- First attempt to use CR in 3dAllineate didn't give good results
- Note asymmetry: $CR(x,y) \neq CR(y,x)$
- 3dAllineate now offers two different symmetric CR cost functions:
 - Compute both unsymmetric CR(x,y) and CR(y,x), then combine by Multiplying or Adding:

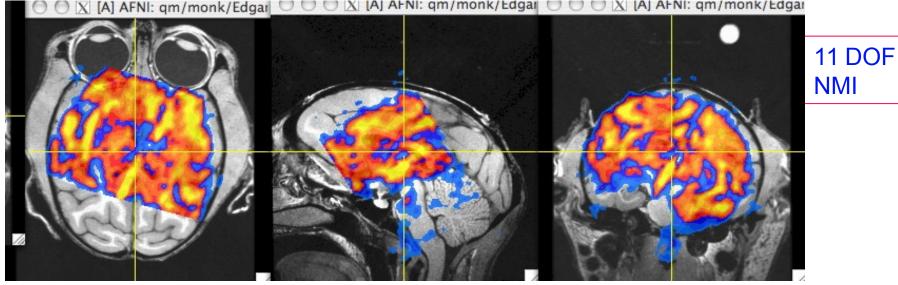
 - ♦ These work better than CR(J,I) in my test problems
- If Exp[y|x] can be used to predict y <u>and/or</u> Exp[x|y] can be used to predict x, then crM(x,y) will be large (close to 1)
- 3dAllineate minimizes 1-CRm(J,I) with option -cost crM
- 3dAllineate minimizes 1-CRa(J,I) with option -cost crA
- 3dAllineate minimizes 1-CR(J,I) with option -cost crU

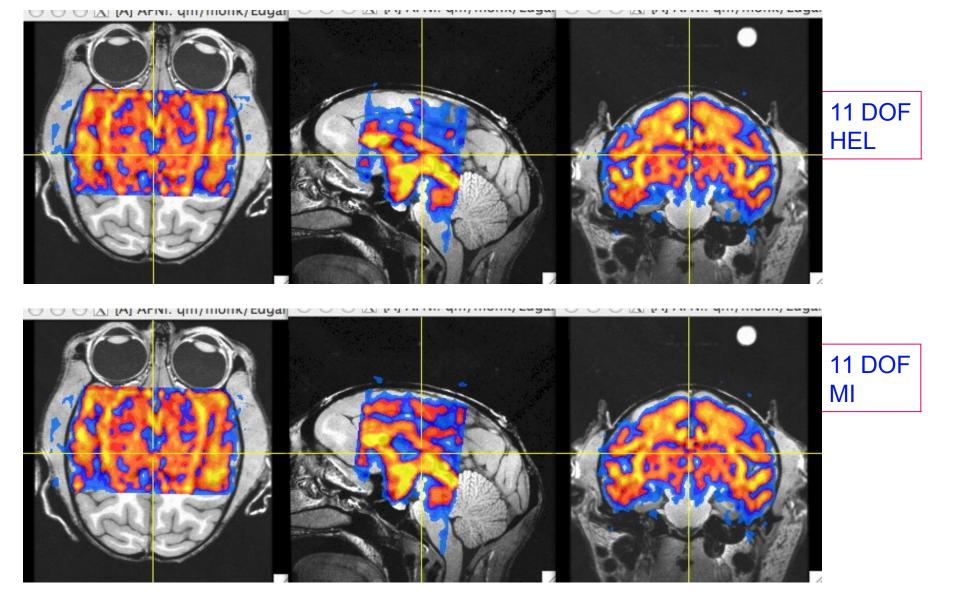




6 DOF







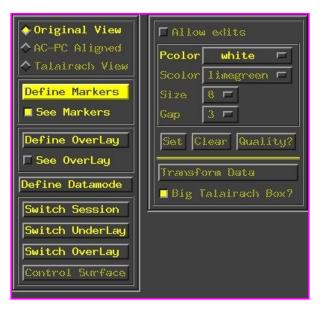
Appendix C

Talairach Transform from the days of yore

• <u>Listen up folks, IMPORTANT NOTE</u>:

Have you ever opened up the [Define Markers] panel, only to find the AC-PC markers

missing , like this:



Gasp! Where did they go?

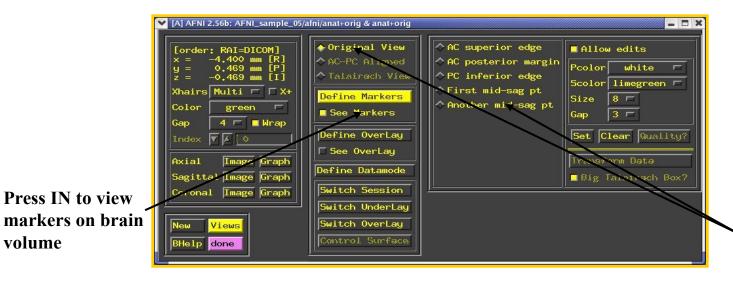
- There are a few reasons why this happens, but usually it's because you've made a copy of a dataset, and the AC-PC marker tags weren't created in the copy, resulting in the above dilemma.
 - In other cases, this occurs when afni is launched without any datasets in the directory from which it was launched (oopsy, your mistake).
- If you do indeed have an AFNI dataset in your directory, but the markers are missing and you want them back, run 3drefit with the -markers options to create an empty set of AC-PC markers. Problem solved!

3drefit -markers <name of dataset>

volume

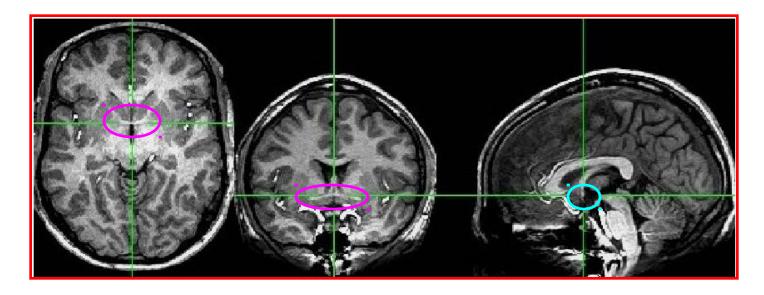
- Class Example Selecting the ac-pc markers:

 - ♦ afni & ⇒ This command launches the AFNI program
 - → The "&" keeps the UNIX shell available in the background, so we can continue typing in commands as needed, even if AFNI is running in the foreground
 - Select dataset anat+orig from the [Switch Underlay] control panel



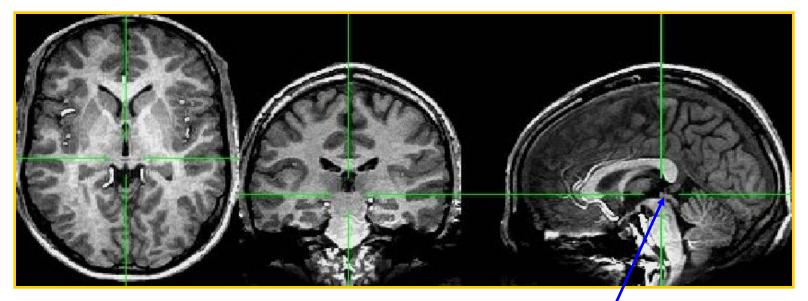
The AC-PC markers appear only when the orig view is highlighted

- Select the [Define Markers] control panel to view the 5 markers for ac-pc alignment
- Click the [See Markers] button to view the markers on the brain volume as you select them
- Click the [Allow edits] button in the ac-pc GUI to begin marker selection



- First goal is to mark top middle and rear middle of AC
 - ➤ Sagittal: look for AC at bottom level of corpus callosum, below fornix
 - ➤ Coronal: look for "mustache"; Axial: look for inter-hemispheric connection
 - → Get AC centered at focus of crosshairs (in Axial and Coronal)
 - → Move superior until AC disappears in Axial view; then inferior 1 pixel
 - → Press IN [AC superior edge] marker toggle, then [Set]
 - → Move focus back to middle of AC
 - → Move posterior until AC disappears in Coronal view; then anterior 1 pixel
 - ⇒ Press IN [AC posterior margin], then [Set]

- Second goal is to mark inferior edge of PC
 - → This is harder, since PC doesn't show up well at 1 mm resolution
 - → Fortunately, PC is always at the top of the cerebral aqueduct, which does show up well (at least, if CSF is properly suppressed by the MRI pulse sequence)



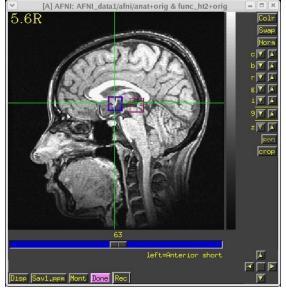
cerebral aqueduct

- → Therefore, if you can't see the PC, find mid-sagittal location just at top of cerebral aqueduct and mark it as [PC inferior edge]
- Third goal is to mark two inter-hemispheric points (above corpus callosum)
 - → The two points must be at least 2 cm apart
 - \rightarrow The two planes $\Delta C_PC_{-}#1$ and $\Delta C_PC_{-}#2$ must be no more than 2°

AC-PC Markers Cheat Sheet

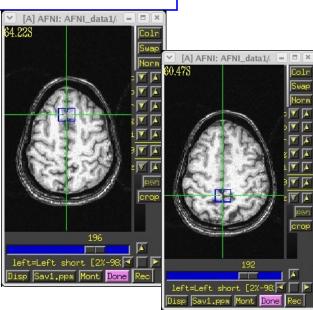
The AC-PC markers may take some time for the novice to master, so in the interest of time, we provide you with a little guide or "cheat sheet" to help you place markers on this example volume:

to: AC Superior Edge: 126 107 63 AC Posterior Margin: 127 108 63 PC Inferior Edge: 152 109 63 1st Mid-Sagittal Point: 110 59 60 2nd Mid-Sagittal Point: 172 63 60



AC-PC markers

mid-sagittal markers



- Once all 5 markers have been set, the [Quality?] Button is ready
 - → You can't [Transform Data] until [Quality?] Check is passed
 - In this case, quality check makes sure two planes from AC-PC line to midsagittal points are within 2°
 - Sample below shows a 2.43° deviation between planes ⇒ ERROR message indicates we must move one of the points a little

```
*** MARKERS QUALITY REPORT ***

*** ERROR: The AC + PC + mid-sag pts do not form a good plane.

Angular deviation between AC+PC+mid-sag pts: 2.43 degrees

Mismatch between AC-PC line and Talairach origin: 0.04 mm

Total rotation to align AC-PC and mid-sag: 4.41 degrees
```

Sample below shows a deviation between planes at less than 2°. Quality check is passed

```
*** MARKERS QUALITY REPORT ***

Angular deviation between AC+PC+mid-sag pts: 1.33 degrees
Mismatch between AC-PC line and Talairach origin: 0.06 mm
Total rotation to align AC-PC and mid-sag: 4.59 degrees
```

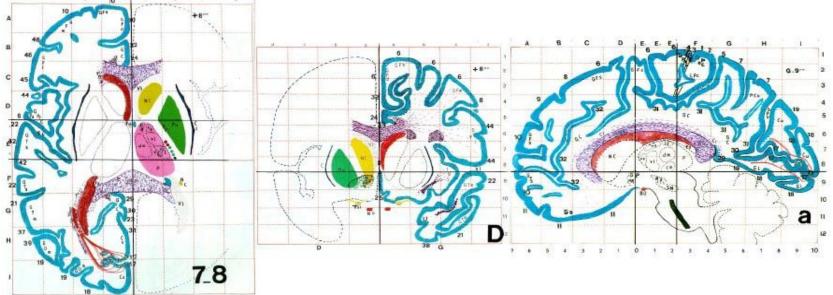
We can now save the marker locations into the dataset header

- Notes on positioning AC/PC markers:
 - ➡ The structures dimensions are on the order of typical high-res images. Do not fret about a matter such as:
 - Q: Do I put the Sup. AC marker on the top voxel where I see still the the structure or on the one above it?
 - A: Either option is OK, just be consistent. The same goes for setting the bounding box around the brain discussed ahead. Remember, intra-subject anatomical variability is more than the 1 or 2 mm you are concerned about.
 - → Typically, all three markers fall in the same mid-saggital plane
- Why, oh why, two mid-saggital points?
 - [Quality?] Contrary to our desires, no two hemispheres in their natural setting can be perfectly separated by a mid-saggital plane. When you select a mid-saggital point, you are defining a plane (with AC/PC points) that forms an acceptable separation between left and right sides of the brain.
 - ➤ To get a better approximation of the mid-saggital plane, AFNI insists on another mid-saggital point and uses the average of the two planes. It also insists that these two planes are not off from one another by more than 2°
- I am Quality! How do I escape the tyranny of the [Quality?] check?
 - → If you know what you're doing and want to elide the tests:
 - Set AFNI_MARKERS_NOQUAL environment variable to YES
 - This is a times needed when you are applying the transform to brains of children or monkeys which differ markedly in size from mature human brains.

- When [Transform Data] is available, pressing it will close the [Define Markers] panel, write marker locations into the dataset header, and create the +acpc datasets that follow from this one
 - → The [AC-PC Aligned] coordinate system is now enabled in the main AFNI controller window
 - → In the future, you could re-edit the markers, if desired, then re-transform the dataset (but you wouldn't make a mistake, would you?)
 - → If you don't want to save edited markers to the dataset header, you must quit AFNI without pressing [Transform Data] or [Define Markers]
- ◆ ls ⇒ The newly created ac-pc dataset, anat+acpc.HEAD, is located in our demo_tlrc/ directory
- At this point, only the header file exists, which can be viewed when selecting the [AC-PC Aligned] button
 - → more on how to create the accompanying .BRIK file later...

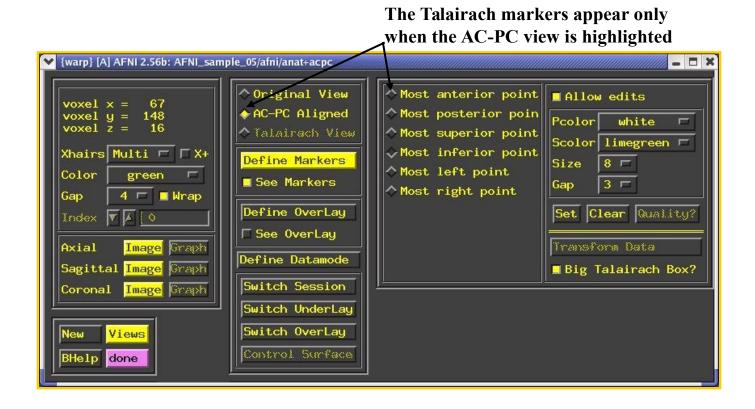
• <u>Scaling to Talairach-Tournoux (+tlrc) coordinates</u>:

 We now stretch/shrink the brain to fit the Talairach-Tournoux Atlas brain size (sample TT Atlas pages shown below, just for fun)



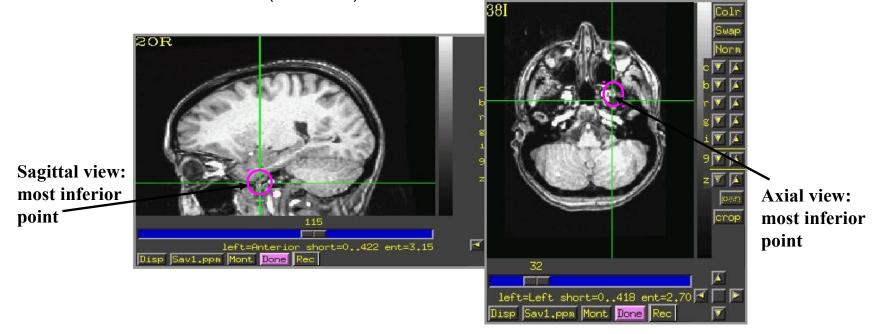
Most anterior to AC	70 mm		
AC to PC	23 mm		
Mesterment prosperior	49 mm	Length of cerebrum	172
AC to most superior AC to left (or right)	74 mm 68 mm	Height of cerebrum Width of cerebrum	116 mm 136 mm

- Class example Selecting the Talairach-Tournoux markers:
 - There are 12 sub-regions to be scaled (3 A-P x 2 I-S x 2 L-R)
 - To enable this, the transformed +acpc dataset gets its own set of markers
 - → Click on the [AC-PC Aligned] button to view our volume in ac-pc coordinates
 - → Select the [<u>Define Markers</u>] control panel
 - ♦ A new set of six Talairach markers will appear:



- Using the same methods as before (i.e., select marker toggle, move focus there,
 [Set]), you must mark these extreme points of the cerebrum
 - → Using 2 or 3 image windows at a time is useful

→ Hardest marker to select is [Most inferior point] in the temporal lobe, since it is near other (non-brain) tissue:



- → Once all 6 are set, press [Quality?] to see if the distances are reasonable
 - Leave [Big Talairach Box?] Pressed IN
 - ⇒ Is a legacy from earliest (1994-6) days of AFNI, when 3D box size of +tlrc datasets was 10 mm smaller in I-direction than the current default

- Once the quality check is passed, click on [<u>Transform Data</u>] to save the +tlrc header
- ◆ ls ⇒ The newly created +tlrc dataset, anat+tlrc.HEAD, is located in our demo tlrc/ directory
 - → At this point, the following anatomical datasets should be found in our demo tlrc/ directory:

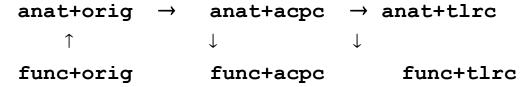
```
anat+orig.HEAD anat+orig.BRIK
anat+acpc.HEAD
anat+tlrc.HEAD
```

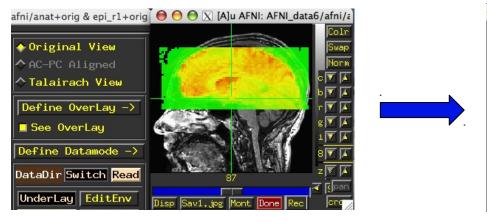
In addition, the following functional dataset (which I -- the instructor -- created earlier) should be stored in the demo tlrc/ directory:

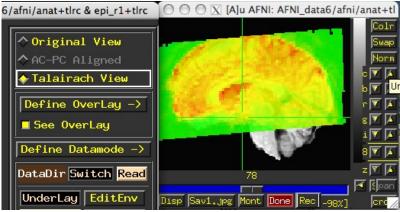
```
func_slim+orig.HEAD func_slim+orig.BRIK
```

Note that this functional dataset is in the +orig format (not +acpc or +tlrc)

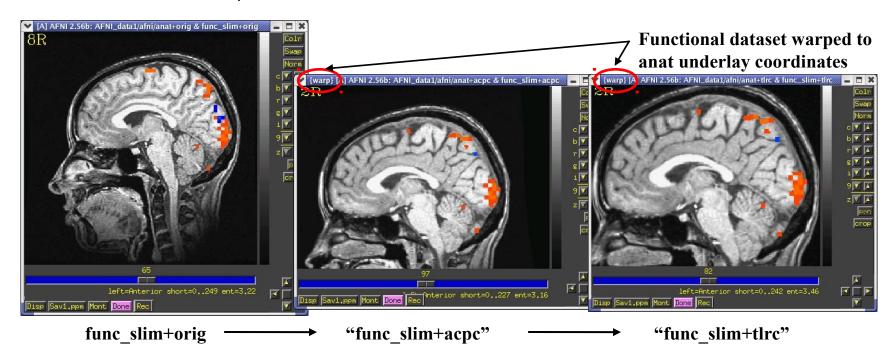
- Automatic creation of "follower datasets":
 - After the anatomical +orig dataset in a directory is resampled to +acpc and +tlrc coordinates, all the other datasets in that directory will automatically get transformed datasets as well
 - → These datasets are created automatically inside the interactive AFNI program, and are not written (saved) to disk (i.e., only header info exists at this point)
 - → How followers are created (arrows show geometrical relationships):





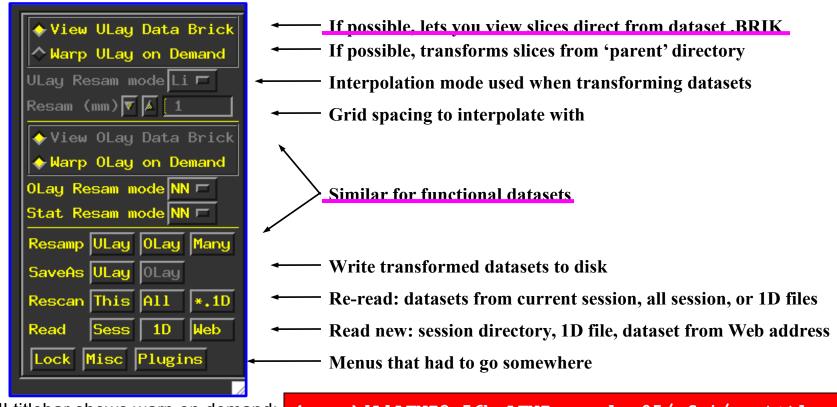


- How does AFNI actually create these follower datsets?
 - → After [<u>Transform Data</u>] creates <u>anat+acpc</u>, other datasets in the same directory are scanned
 - ⇒ AFNI defines the geometrical transformation ("warp") from func_slim+orig using the to3d-defined relationship between func_slim+orig and anat+orig, AND the markers-defined relationship between anat+orig and anat+acpc
 - A similar process applies for warping func slim+tlrc
 - These warped functional datasets can be viewed in the AFNI interface:



 Next time you run AFNI, the followers will automatically be created internally again when the program starts

- "Warp on demand" viewing of datasets:
 - → AFNI doesn't actually resample all follower datasets to a grid in the re-aligned and restretched coordinates
 - This could take quite a long time if there are a lot of big 3D+time datasets
 - Instead, the dataset slices are transformed (or warped) from +orig to +acpc or +tlrc for viewing as needed (on demand)
 - → This can be controlled from the [Define Datamode] control panel:

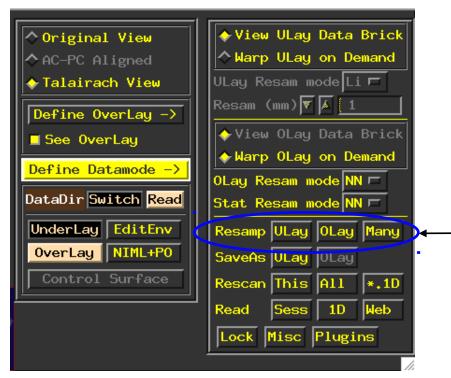


AFNI titlebar shows warp on demand:

{warp} [A]AFNI2.56b:AFNI_sample_05/afni/anat+tlrc

Creating follower data

- Writing "follower datasets" to disk:
 - Recall that when we created anat+acpc and anat+tlrc datasets by pressing [Transform Data], only .HEAD files were written to disk for them
 - In addition, our follower datasets func_slim+acpc and func_slim+tlrc are not stored in our demo_tlrc/ directory. Currently, they can only be viewed in the AFNI graphical interface
 - Questions to ask:
 - How do we write our anat .BRIK files to disk?
 - How do we write our warped follower datasets to disk?
 - To write a dataset to disk (whether it be an anat .BRIK file or a follower dataset), use one of the [Define Datamode] ⇒ Resamp buttons:



<u>ULay</u> writes current underlay dataset to disk

<u>OLay</u> writes current overlay dataset to disk

<u>Many</u> writes multiple datasets in a directory to disk

- Class example Writing anat (Underlay) datasets to disk:
 - ♦ You can use [Define Datamode] ⇒ Write ⇒ [ULay] to write the current anatomical dataset .BRIK out at the current grid spacing (cubical voxels), using the current anatomical interpolation mode
 - After that, [View ULay Data Brick] will become available
 - Is ⇒ to view newly created .BRIK files in the demo_tlrc/ directory:

```
anat+acpc.HEADanat+acpc.BRIK
anat+tlrc.HEADanat+tlrc.BRIK
```

- Class example Writing func (Overlay) datasets to disk:
 - ◆ You can use [Define Datamode] ⇒ Write ⇒ [OLay] to write the current functional dataset .HEAD and BRIK files into our demo tlrc/ directory
 - After that, [View OLay Data Brick] will become available
 - **⇒** 1s ⇒ to view newly resampled func files in our demo_tlrc/ directory:

```
func_slim+acpc.HEAD func_slim+acpc.BRIK
func slim+tlrc.HEAD func slim+tlrc.BRIK
```

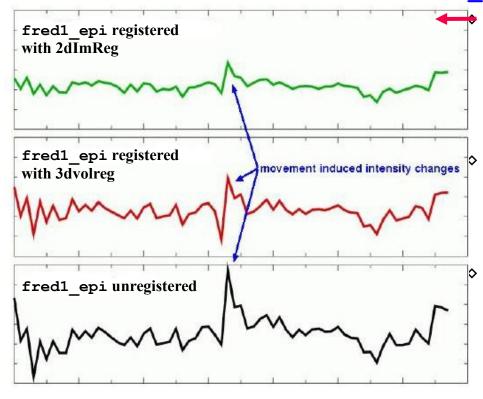
• Command line program adwarp can also be used to write out .BRIK files for transformed datasets:

```
adwarp -apar anat+tlrc -dpar func+orig
```

- The result will be: func+tlrc.HEAD and func+tlrc.BRIK
- Why bother saving transformed datasets to disk anyway?
 - Datasets without .BRIK files are of limited use:
 - → You can't display 2D slice images from such a dataset
 - ➤ You can't use such datasets to graph time series, do volume rendering, compute statistics, run any command line analysis program, run any plugin...
 - ⇒ If you plan on doing any of the above to a dataset, it's best to have
 both a . HEAD and . BRIK files for that dataset

- Examination of time series fred2_epi+orig and fred2_epi_vr_+orig shows that head movement up and down happened within about 1 TR interval
 - → Assumption of rigid motion of 3D volumes is not good for this case
 - Can do 2D slice-wise registration with command

```
2dImReg -input fred2_epi+orig \
  -basefile fred1_epi+orig \
  -base 4 -prefix fred2 epi 2Dreg
```



Graphs of a single voxel time series near the edge of the brain:

- → Top = slice-wise alignment
- → Middle = volume-wise adjustment
- **→** Bottom = no alignment

For **this** example, **2dImReg** appears to produce better results. This is because most of the motion is 'head nodding' and the acquisition is sagittal

You should also use AFNI to scroll through the images (using the Index control)
during the period of pronounced
movement

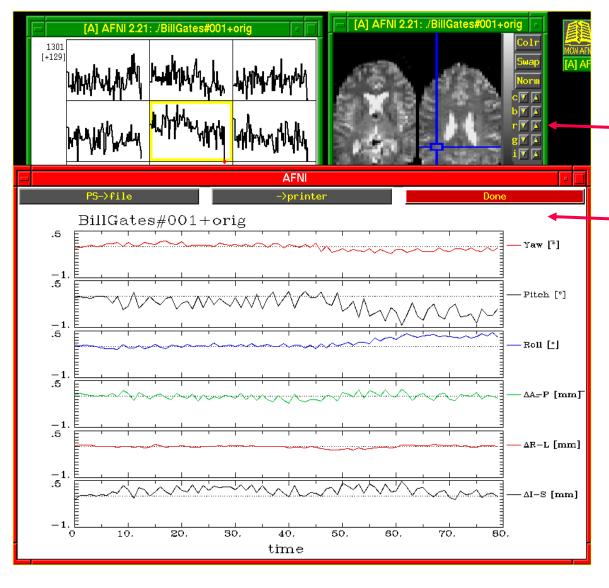
Helps see if registration fixed problems

Real-Time 3D Image Registration

- The image alignment method using in 3dvolreg is also built into the AFNI real-time image acquisition plugin
 - howe by command afni -rt
 - ♦ Then use Define Datamode → Plugins → RT Options to control the operation of real-time (RT) image acquisition
- Images (2D or 3D arrays of numbers) can be sent into AFNI through a TCP/IP socket
 - See the program rtfeedme.c for sample of how to connect to AFNI and send the data
 - → Also see file **README**.realtime for lots of details
 - 2D images will be assembled into 3D volumes = AFNI sub-bricks
- Real-time plugin can also do 3D registration when each 3D volume is finished, and graph the movement parameters in real-time
 - Useful for seeing if the subject in the scanner is moving his head too much
 - ➡ If you see too much movement, telling the subject will usually help

- Realtime motion correction can easily be setup if DICOM images are made available on disk as the scanner is running.
- The script demo.realtime present in the AFNI_data1/EPI_manyruns directory demonstrates the usage:

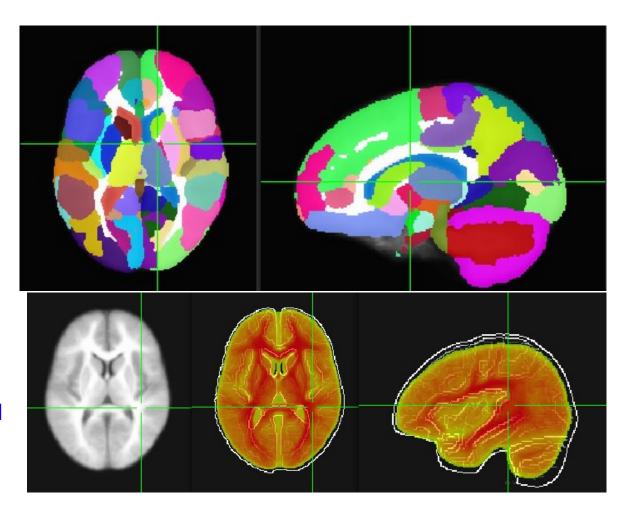
```
#!/bin/tcsh
# demo real-time data acquisition and motion detection with afni
# use environment variables in lieu of running the RT Options plugin
setenv AFNI REALTIME Registration
                                       3D: realtime
setenv AFNI REALTIME Graph
                                        Realtime
if (!-d afni) mkdir afni
cd afni
afni -rt &
sleep 5
cd ...
echo ready to run Dimon
echo -n press enter to proceed...
set stuff = $<
Dimon -rt -use imon -start dir 001 -pause 200
```



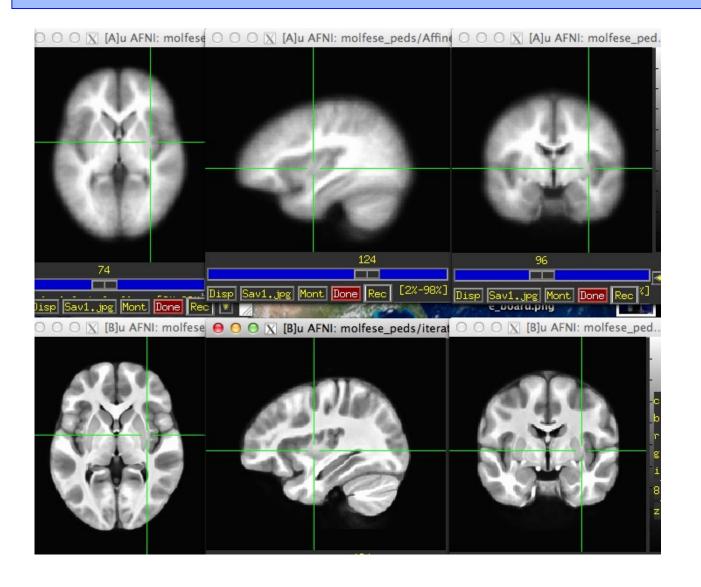
- Screen capture from example of real-time image acquisition and registration
 - Images and time series graphs can be viewed as data comes in
 - Graphs of movement parameters

Haskins Pediatric Atlas

- Pediatric brain atlas and templates (7-12 years old) – Peter Molfese, Haskins Laboratories
- Manually corrected segmentation from Freesurfer.
- Probabilistic, MPM and template
- ~75 subjects -> 500 (ages 6-13)
- Affine, nonlinear averages, ideal/typical subjects, outliers



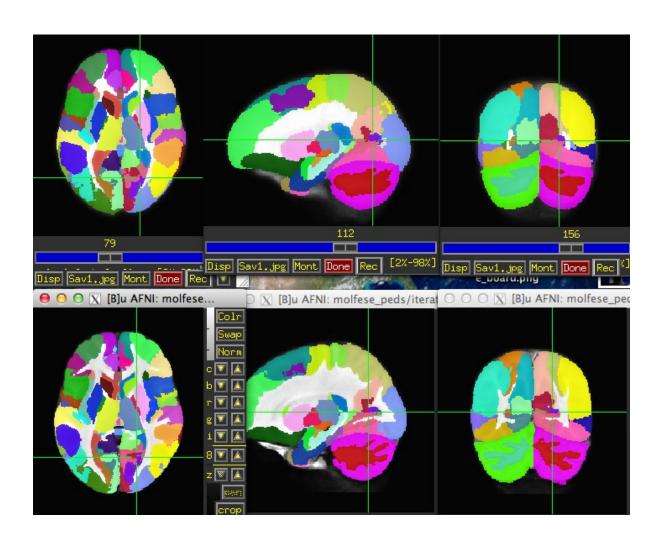
Haskins Pediatric Atlas - templates



Affine Group

Nonlinear Group I – iterative

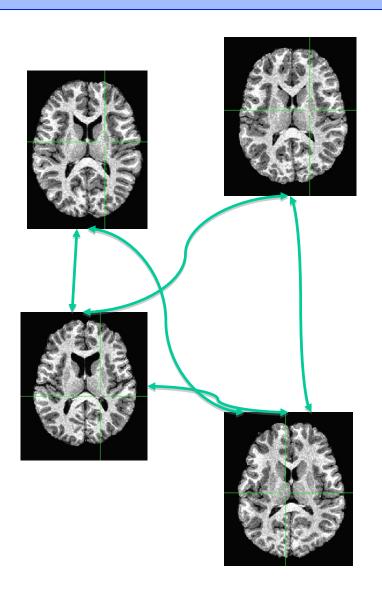
Haskins Pediatric Atlas – MPM atlases



Affine Group

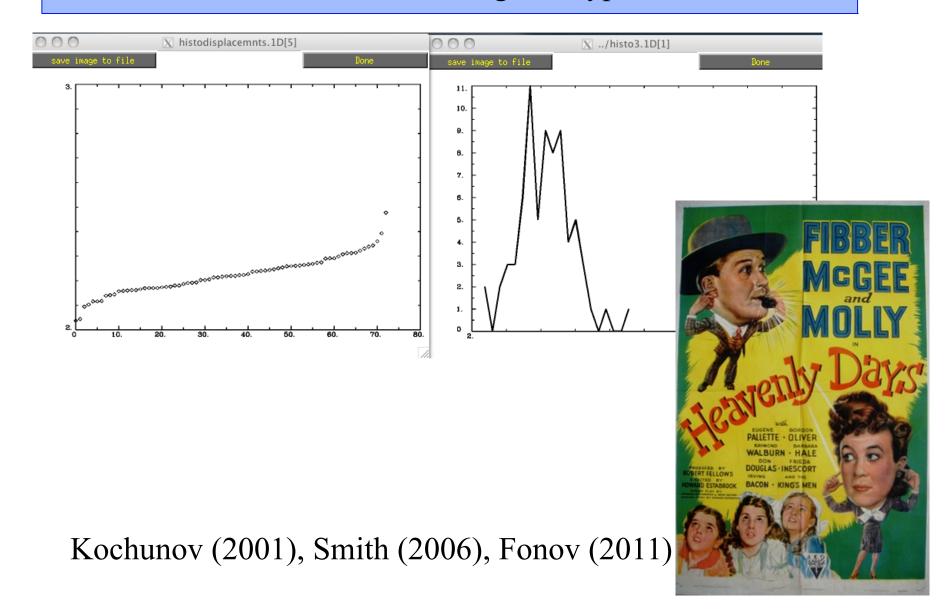
Nonlinear Group I – iterative

Haskins Pediatric Atlas – Finding the "typical" kid's brain

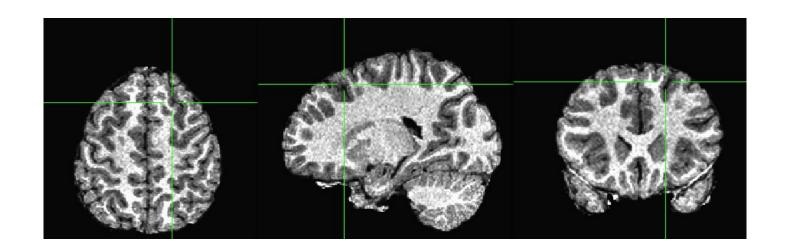


- 1. Make roughly same size with affine warp
- 2. Align every subject to every other
- 3. Find the mean of the absolute displacement at every voxel in the brain for each subject for warp between that subject and all others
- 4. Find sum of mean displacement across brain
- 5. Rank subjects by mean absolute displacement
- 6. Minimum displacement Winner! Typical subject
- 7. Maximum displacement QC? Atypical subjects

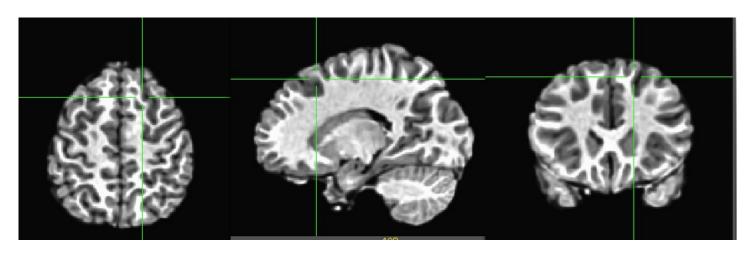
Haskins Pediatric Atlas – Finding the "typical" kid's brain



Haskins Pediatric Atlas – Finding the "typical" kid's brain

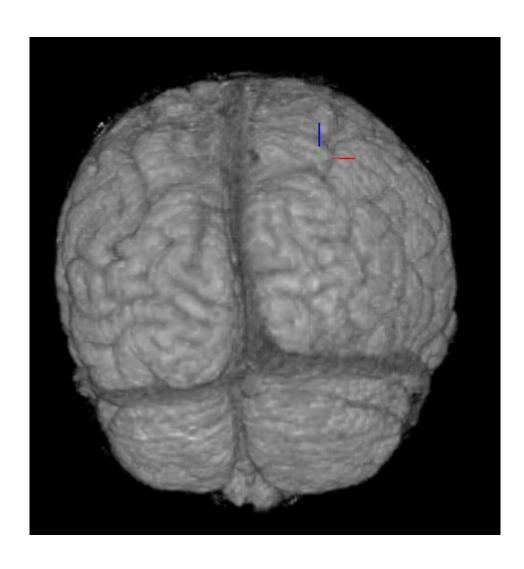


 sn_xxx



anisotropically smoothed

Haskins Pediatric Atlas – Finding the "atypical" kid's brain



Petalia – torque asymmetry