Deconvolution Signal Models

• Simple or Fixed-shape regression (previous talks):
  ★ We fixed the shape of the HRF — amplitude varies
  ★ Used `-stim_times` to generate the signal model (AKA the “ideal”) from the stimulus timing
  ★ Found the amplitude of the signal model in each voxel — solution to the set of linear equations $= \beta$ weights

• Deconvolution or Variable-shape regression (now):
  ★ We allow the shape of the HRF to vary in each voxel, for each stimulus class
  ★ Appropriate when you don’t want to over-constrain the solution by assuming an HRF shape
  ★ Caveat: need to have enough time points during the HRF in order to resolve its shape (e.g., TR $\leq 3$ s)
Deconvolution: Pros & Cons (+ & −)

+ Letting HRF shape varies allows for subject and regional variability in hemodynamics

+ Can test HRF estimate for different shapes (e.g., are later time points more “active” than earlier?)

− Need to estimate more parameters for each stimulus class than a fixed-shape model (e.g., 4-15 vs. 1 parameter = amplitude of HRF)

− Which means you need more data to get the same statistical power (assuming that the fixed-shape model you would otherwise use was in fact “correct”)

− Freedom to get any shape in HRF results can give weird shapes that are difficult to interpret
Expressing HRF via Regression Unknowns

• The tool for expressing an unknown function as a finite set of numbers that can be fit via linear regression is an **expansion in basis functions**

\[ h(t) = \beta_0 \psi_0(t) + \beta_1 \psi_1(t) + \beta_2 \psi_2(t) + \cdots = \sum_{q=0}^{q=p} \beta_q \psi_q(t) \]

★ The basis functions \( \psi_q(t) \) & expansion order \( p \) are known
  o Larger \( p \) ⇒ more complex shapes & more parameters
★ The unknowns to be found (in each voxel) comprises the set of weights \( \beta_q \) for each \( \psi_q(t) \)

• \( \beta \) weights appear only by multiplying known values, and HRF only appears in signal model by linear convolution (addition) with known stimulus timing
  • Resulting signal model still solvable by linear regression
3dDeconvolve with “Tent Functions”

• Need to describe HRF shape and magnitude with a finite number of parameters
  ★ And allow for calculation of $h(t)$ at any arbitrary point in time after the stimulus times:
  \[
  r_n = \sum_{k=1}^{K} h(t_n - \tau_k) = \text{sum of HRF copies}
  \]
• Simplest set of such functions are tent functions
  ★ Also known as “piecewise linear splines”

$$T(x) = \begin{cases} 
1 - |x| & \text{for } -1 < x < 1 \\
0 & \text{for } |x| > 1 
\end{cases}$$

N.B.: cubic splines are also available
Tent Functions = Linear Interpolation

- Expansion of HRF in a set of spaced-apart tent functions is the same as linear interpolation between “knots”

\[ h(t) = \beta_0 \cdot T \left( \frac{t}{L} \right) + \beta_1 \cdot T \left( \frac{t - L}{L} \right) + \beta_2 \cdot T \left( \frac{t - 2 \cdot L}{L} \right) + \beta_3 \cdot T \left( \frac{t - 3 \cdot L}{L} \right) + \cdots \]

- Tent function parameters are also easily interpreted as function values (e.g., \( \beta_2 \) = response at time \( t = 2 \cdot L \) after stim)
- User must decide on relationship of tent function grid spacing \( L \) and time grid spacing \( TR \) (usually would choose \( L \geq TR \))
- In \texttt{3dDeconvolve}: specify duration of HRF and number of \( \beta \) parameters (details shown a few slides ahead)

N.B.: 5 intervals = 6 \( \beta \) weights
Tent Functions: Average Signal Change

- For input to group analysis, usually want to compute average signal change
  - Over entire duration of HRF (usual)
  - Over a sub-interval of the HRF duration (sometimes)

- In previous slide, with 6 $\beta$ weights, average signal change is
  \[
  \frac{1}{2} \beta_0 + \beta_1 + \beta_2 + \beta_3 + \beta_4 + \frac{1}{2} \beta_5
  \]

- First and last $\beta$ weights are scaled by half since they only affect half as much of the duration of the response

- In practice, may want to use $0 \cdot \beta_0$ since immediate post-stimulus response is not neuro-hemodynamically relevant

- All $\beta$ weights (for each stimulus class) are output into the “bucket” dataset produced by 3dDeconvolve

- Can then be combined into a single number using 3dcalc
Deconvolution and Collinearity

- Regular stimulus timing can lead to collinearity!

Equations at each data time point:
Cannot tell $\beta_0$ from $\beta_4$, or $\beta_1$ from $\beta_5$

HRF from stim #1

Tail of HRF from #1 overlaps head of HRF from #2, etc
Deconvolution Example - The Data

• `cd AFNI_data2`
  ★ data is in `ED/` subdirectory (10 runs of 136 images each; TR=2 s)
  ★ `script = s1.afni_proc_command` (in `AFNI_data2/` directory)
    o stimuli timing and GLT contrast files in `misc_files/`
  ★ this script runs program `afni_proc.py` to generate a shell script with all AFNI commands for single-subject analysis
    o Run by typing `tcsh s1.afni_proc_command`; then copy/paste `tcsh -x proc.ED.8.glt |& tee output.proc.ED.8.glt`

• Event-related study from Mike Beauchamp
  ★ 10 runs with four classes of stimuli (short videos)
    o Tools moving (e.g., a hammer pounding) - `ToolMovie`
    o People moving (e.g., jumping jacks) - `HumanMovie`
    o Points outlining tools moving (no objects, just points) - `ToolPoint`
    o Points outlining people moving - `HumanPoint`
  ★ Goal: find brain area that distinguishes natural motions (`HumanMovie` and `HumanPoint`) from simpler rigid motions (`ToolMovie` and `ToolPoint`)
Master Script for Data Analysis

- afni_proc.py
  - dsets ED/ED_r??+orig.HEAD
  - subj_id ED.8.glt
  - copy_anat ED/EDspgr
  - tcat_remove_first_trs 2
  - volreg_align_to first
  - regress_stim_times misc_files/stim_times.*.1D
  - regress_stim_labels ToolMovie HumanMovie
    ToolPoint HumanPoint
  - regress_basis 'TENT(0,14,8)'
  - regress_opts_3dD
    - gltsym ../misc_files/glt1.txt -glt_label 1 FullF
    - gltsym ../misc_files/glt2.txt -glt_label 2 HvsT
    - gltsym ../misc_files/glt3.txt -glt_label 3 MvsP
    - gltsym ../misc_files/glt4.txt -glt_label 4 HMvsHP
    - gltsym ../misc_files/glt5.txt -glt_label 5 TMvsTP
    - gltsym ../misc_files/glt6.txt -glt_label 6 HPvsTP
    - gltsym ../misc_files/glt7.txt -glt_label 7 HMvsTM

This script generates file proc.ED.8.glt (180 lines), which contains all the AFNI commands to produce analysis results into directory ED.8.glt.results/ (148 files)
Shell Script for Deconvolution - Outline

• Copy datasets into output directory for processing
• Examine each imaging run for outliers: `3dToutcount`
• Time shift each run’s slices to a common origin: `3dTshift`
• Registration of each imaging run: `3dvolreg`
• Smooth each volume in space (136 sub-bricks per run): `3dmerge`
• Create a brain mask: `3dAutomask` and `3dcalc`
• Rescale each voxel time series in each imaging run so that its average through time is 100: `3dTstat` and `3dcalc`
  ★ If baseline is 100, then a $\beta_q$ of 5 (say) indicates a 5% signal change in that voxel at tent function knot $#q$ after stimulus
  ★ Biophysics: believe % signal change is relevant physiological parameter
• Catenate all imaging runs together into one big dataset (1360 time points): `3dTcat`
  ★ This dataset is useful for plotting `-fitts` output from `3dDeconvolve` and visually examining time series fitting
• Compute HRFs and statistics: `3dDeconvolve`
Script - 3dToutcount

# set list of runs
set runs = (`count -digits 2 1 10```
# run 3dToutcount for each run
foreach run ( $runs )
    3dToutcount -automask pb00.$subj.r$run.tcat+orig > outcount_r$run.1D
end

Via 1dplot outcount_r???.1D
3dToutcount searches for “outliers” in data time series;
You should examine noticeable runs & time points
Script - 3dTshift

# run 3dTshift for each run
foreach run ( $runs )
    3dTshift -tzero 0 -quintic -prefix pb01.$subj.r$run.tshift \
        pb00.$subj.r$run.tcat+orig
end

• Produces new datasets where each time series has been
  shifted to have the same time origin
• `-tzero 0` means that all data time series are interpolated to
  match the time offset of the first slice
  • Which is what the slice timing files usually refer to
  • Quintic (5th order) polynomial interpolation is used
• 3dDeconvolve will be run on these time-shifted datasets
  • This is mostly important for Event-Related FMRI studies, where the
    response to the stimulus is briefer than for Block designs
    • (Because the stimulus is briefer)
  • Being a little off in the stimulus timing in a Block design is not likely to
    matter much
Script - 3dvolreg

```bash
# align each dset to the base volume
foreach run ( $runs )
    3dvolreg -verbose -zpad 1 -base pb01.$subj.r01.tshift+orig'[0]' \
        -1Dfile dfile.r$run.1D -prefix pb02.$subj.r$run.volreg \
        pb01.$subj.r$run.tshift+orig
end
```

- Produces new datasets where each volume (one time point) has been aligned (registered) to the #0 time point in the #1 dataset
- Movement parameters are saved into files `dfile.r$run.1D`
  - Will be used as extra regressors in `3dDeconvolve` to reduce motion artifacts

```
1dplot -volreg dfile.rall.1D
```

- Shows movement parameters for all runs (1360 time points) in degrees and millimeters
- Very important to look at this graph!
- Excessive movement can make an imaging run useless — 3dvolreg won’t be able to compensate
  - Pay attention to scale of movements: more than about 2 voxel sizes in a short time interval is usually bad
# blur each volume
foreach run ( $runs )
    3dmerge -1blur_fwhm 4 -doall -prefix pb03.$subj.r$run.blur \
    pb02.$subj.r$run.volreg+orig
end

• **Why Blur?** Reduce noise by averaging neighboring voxels time series

This is an extremely good fit for ER FMRI data!
Why Blur? - 2

- fMRI activations are (usually) blob-ish (several voxels across)
- Averaging neighbors will also reduce the fiendish multiple comparisons problem
  - Number of independent “resels” will be smaller than number of voxels (e.g., 2000 vs. 20000)
- Why not just acquire at lower resolution?
  - To avoid averaging across brain/non-brain interfaces
  - To project onto surface models
- Amount to blur is specified as FWHM (Full Width at Half Maximum) of spatial averaging filter (4 mm in script)
# Script - 3dAutomask

# create 'full_mask' dataset (union mask)
foreach run ( $runs )
    3dAutomask -dilate 1 -prefix rm.mask_r$run pb03.$subj.r$run.blur+orig
end

# get mean and compare it to 0 for taking 'union'
3dMean -datum short -prefix rm.mean rm.mask*.HEAD
3dcalc -a rm.mean+orig -expr 'ispositive(a-0)' -prefix full_mask.$subj

- **3dAutomask** creates a mask of contiguous high-intensity voxels (with some hole-filling) from each imaging run separately
- **3dMean** and **3dcalc** are used to create a mask that is the union of all the individual run masks
- **3dDeconvolve** analysis will be limited to voxels in this mask
  - Will run faster, since less data to process

Automask from EPI shown in red
Script - Scaling

# scale each voxel time series to have a mean of 100
# (subject to maximum value of 200)
foreach run ( $runs )
  3dTstat -prefix rm.mean_r$run pb03.$subj.r$run.blur+orig
  3dcalc -a pb03.$subj.r$run.blur+orig -b rm.mean_r$run+orig
      \-c full_mask.$subj+orig
      \-expr 'c * min(200, a/b*100)' -prefix pb04.$subj.r$run.scale
end

- **3dTstat** calculates the mean (through time) of each voxel’s time series data
- For voxels in the mask, each data point is scaled (multiplied) using **3dcalc** so that it’s time series will have mean = 100
- If an HRF regressor has max amplitude = 1, then its $\beta$ coefficient will represent the percent signal change (from the mean) due to that part of the signal model
- Scaled images are very boring to view
  - No spatial contrast by design!
  - Graphs have common baseline now
Script - 3dDeconvolve

3dDeconvolve -input pb04.$subj.r??scale+orig.HEAD -polort 2 -mask full_mask.$subj+orig -basis_normall 1 -num_stimts 10 -stim_times 1 stimuli/stim_times.01.1D 'TENT(0,14,8)' -stim_label 1 ToolMovie -stim_times 2 stimuli/stim_times.02.1D 'TENT(0,14,8)' -stim_label 2 HumanMovie -stim_times 3 stimuli/stim_times.03.1D 'TENT(0,14,8)' -stim_label 3 ToolPoint -stim_times 4 stimuli/stim_times.04.1D 'TENT(0,14,8)' -stim_label 4 HumanPoint -stim_file 5 dfile.rall.1D'[0]' -stim_base 5 -stim_label 5 roll -stim_file 6 dfile.rall.1D'[1]' -stim_base 6 -stim_label 6 pitch -stim_file 7 dfile.rall.1D'[2]' -stim_base 7 -stim_label 7 yaw -stim_file 8 dfile.rall.1D'[3]' -stim_base 8 -stim_label 8 dS -stim_file 9 dfile.rall.1D'[4]' -stim_base 9 -stim_label 9 dL -stim_file 10 dfile.rall.1D'[5]' -stim_base 10 -stim_label 10 dP -iresp 1 iresp_ToolMovie.$subj -iresp 2 iresp_HumanMovie.$subj -iresp 3 iresp_ToolPoint.$subj -iresp 4 iresp_HumanPoint.$subj -gltysym ../misc_files/glt1.txt -glt_label 1 FullF -gltysym ../misc_files/glt2.txt -glt_label 2 HvsT -gltysym ../misc_files/glt3.txt -glt_label 3 MvsP -gltysym ../misc_files/glt4.txt -glt_label 4 HMvsHP -gltysym ../misc_files/glt5.txt -glt_label 5 TMvsTP -gltysym ../misc_files/glt6.txt -glt_label 6 HPvsTP -gltysym ../misc_files/glt7.txt -glt_label 7 HMvsTM -fout -tout -full_first -x1D Xmat.x1D -fitts fitts.$subj -bucket stats.$subj

4 stim types

motion params

HRF outputs

GLTs
Results: Humans vs. Tools

- Color overlay: HvsT GLT contrast
- Blue (upper) graphs: Human HRFs
- Red (lower) graphs: Tool HRFs
Script - X Matrix

Via `grayplot -sep Xmat.x1D`
• -polort 2
  ★ Sets baseline (detrending) to use quadratic polynomials—in each run
• -mask full_mask.$subj+orig
  ★ Process only the voxels that are nonzero in this mask dataset
• -basis_normal 1
  ★ Make sure that the basis functions used in the HRF expansion all have maximum magnitude=1
• -stim_times 1 stimuli/stim_times.01.1D 'TENT(0,14,8)'
• -stim_label 1 ToolMovie
  ★ The HRF model for the ToolMovie stimuli starts at 0 s after each stimulus, lasts for 14 s, and has 8 basis tent functions
  o Which have knots (breakpoints) spaced 14/(8-1)=2 s apart
• -iresp 1 iresp_ToolMovie.$subj
  ★ The HRF model for the ToolMovie stimuli is output into dataset iresp_ToolMovie.ED.8.glt+orig
Script - GLTs

- `-gltsym ../misc_files/glt2.txt -glt_label 2 HvsT`
  - File `../misc_files/glt2.txt` contains 1 line of text:
    - `-ToolMovie +HumanMovie -ToolPoint +HumanPoint`
    - This is the “Humans vs. Tools” $HvsT$ contrast shown on Results slide

- This GLT means to take all 8 $\beta$ coefficients for each stimulus class and combine them with additions and subtractions as ordered:

$$LC = -\beta_0^{TM} - \cdots - \beta_7^{TM} + \beta_0^{HM} + \cdots + \beta_7^{HM} - \beta_0^{TP} - \cdots - \beta_7^{TP} + \beta_0^{HP} + \cdots + \beta_7^{HP}$$

  - This test is looking at the integrated (summed) response to the “Human” stimuli and subtracting it from the integrated response to the “Tool” stimuli

- Combining subsets of the $\beta$ weights is also possible with `-gltsym`:
  - This GLT would add up just the #2,3,4,5, & 6 $\beta$ weights for one type of stimulus and subtract the sum of the #2,3,4,5, & 6 $\beta$ weights for another type of stimulus
    - And also produce $F$- and $t$-statistics for this linear combination
Script - Multi-Row GLTs

• GLTs presented up to now have had one row
  ★ Testing if some linear combination of $\beta$ weights is nonzero; test statistic is $t$ or $F$ ($F=t^2$ when testing a single number)
  ★ Testing if the $X$ matrix columns, when added together to form one column as specified by the GLT ($+$ and $-$), explain a significant fraction of the data time series (equivalent to above)

• Can also do a single test to see if several different combinations of $\beta$ weights are all zero
  -gltsym ../misc_files/glt1.txt
  -glt_label 1 FullF
  ★ Tests if any of the stimulus classes have nonzero integrated HRF (each name means “add up those $\beta$ weights”): DOF = (4,1292)
  ★ Different than the default “Full F-stat” produced by 3dDeconvolve, which tests if any of the individual $\beta$ weights are nonzero: DOF = (32,1292)
Two Possible Formats for `-stim_times`

- If you don’t use `-local_times` or `-global_times`, 3dDeconvolve will *guess* which way to interpret numbers:
  - A single column of numbers (GLOBAL times)
    - One stimulus time per row
    - Times are relative to first image in dataset being at $t=0$
    - May not be simplest to use if multiple runs are catenated
  - One row for each run within a catenated dataset (LOCAL times)
    - Each time in $j$th row is relative to start of run #j being $t=0$
    - If some run has NO stimuli in the given class, just put a single “*” in that row as a filler
      - Different numbers of stimuli per run are OK
      - At least one row must have more than 1 time
        (so that the LOCAL type of timing file can be told from the GLOBAL)
- Two methods are available because of users’ diverse needs
  - **N.B.:** if you chop first few images off the start of each run, the inputs to `-stim_times` must be adjusted accordingly!
    - Better to use `-CENSORTR` to tell 3dDeconvolve just to ignore those points
More information about -stim_times and its variants is in the afni07_advanced talk
Spatial Models of Activation

- Smooth data in space before analysis
- Average data across anatomically-selected regions of interest ROI (before or after analysis)
  - Labor intensive (i.e., hire more students)
- Reject isolated small clusters of above-threshold voxels after analysis
Spatial Smoothing of Data

- Reduces number of comparisons
- Reduces noise (by averaging)
- Reduces spatial resolution
  - Blur it enough: Can make FMRI results look like low resolution (1990s) PET data
- Smart smoothing: average only over nearby brain or gray matter voxels
  - Uses resolution of FMRI cleverly
    - 3dBlurToFWHM and 3dBlurInMask
  - Or: average over selected ROIs
  - Or: cortical surface based smoothing
3dBlurToFWHM

• New program to smooth FMRI time series datasets to a specified smoothness (as estimated by FWHM of noise spatial correlation function)
  ★ Don’t just add smoothness (à la 3dmerge) but control it (locally and globally)
  ★ Goal: use datasets from diverse scanners

• Why blur FMRI time series?
  ★ Averaging neighbors will reduce noise
  ★ Activations are (usually) blob-ish (several voxels across)
  ★ Diminishes the multiple comparisons problem

• 3dBlurToFWHM and 3dBlurInMask blur only inside a mask region
  ★ To avoid mixing air (noise-only) and brain voxels
  ★ Partial Differential Equation (PDE) based blurring method
    ○ 2D (intra-slice) or 3D blurring
Spatial Clustering

- Analyze data, create statistical map (e.g., $t$ statistic in each voxel)
- Threshold map at a low $t$ value, in each voxel separately
  - Will have many false positives
- Threshold map by rejecting clusters of voxels below a given size
- Can control false-positive rate by adjusting $t$ threshold and cluster-size thresholds together
Multi-Voxel Statistics
Spatial Clustering & False Discovery Rate:
“Correcting” the Significance
Basic Problem

• Usually have 30–200K FMRI voxels in the brain
• Have to make at least one decision about each one:
  ★ Is it “active”?
    o That is, does its time series match the temporal pattern of activity we expect?
  ★ Is it differentially active?
    o That is, is the BOLD signal change in task #1 different from task #2?
• Statistical analysis is designed to control the error rate of these decisions
  ★ Making *lots* of decisions: hard to get perfection in statistical testing
Multiple Testing Corrections

- **Two types of errors**
  - What is $H_0$ in FMRI studies? $H_0$: no effect (activation, difference, ...) at a voxel
  - Type I error $= \text{Prob}(\text{reject } H_0 \text{ when } H_0 \text{ is true}) = \text{false positive} = p$ value
  - Type II error $= \text{Prob}(\text{accept } H_0 \text{ when } H_1 \text{ is true}) = \text{false negative} = \beta$
  - Power $= 1 - \beta$ = probability of detecting true activation
  - Strategy: controlling type I error while increasing power (decreasing type II errors)
  - Significance level $\alpha$ (magic number 0.05) : $p < \alpha$

<table>
<thead>
<tr>
<th>Justice System: Trial</th>
<th>Statistics: Hypothesis Test</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Hidden Truth</strong></td>
<td><strong>Hidden Truth</strong></td>
</tr>
<tr>
<td>Defendant Innocent</td>
<td>H$_0$ True Not Activated</td>
</tr>
<tr>
<td>Defendant Guilty</td>
<td>H$_0$ False Activated</td>
</tr>
<tr>
<td><strong>Type I Error</strong></td>
<td><strong>Type I Error</strong></td>
</tr>
<tr>
<td>(defendant very unhappy)</td>
<td>(false positive)</td>
</tr>
<tr>
<td><strong>Correct</strong></td>
<td><strong>Correct</strong></td>
</tr>
<tr>
<td>Fail to Reject</td>
<td>Don’t Reject H$_0$</td>
</tr>
<tr>
<td>Presumption of</td>
<td>(defendant isn’t activated)</td>
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<tr>
<td>Innocence (Not Guilty Verdict)</td>
<td></td>
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<tr>
<td><strong>Type II Error</strong></td>
<td><strong>Type II Error</strong></td>
</tr>
<tr>
<td>(defendant very happy)</td>
<td>(false negative)</td>
</tr>
<tr>
<td><strong>Correct</strong></td>
<td><strong>Correct</strong></td>
</tr>
</tbody>
</table>
• **Family-Wise Error (FWE)**

  ★ Multiple testing problem: voxel-wise statistical analysis
  
  o With $N$ voxels, what is the chance to make a false positive error (Type I) in one or more voxels?

  **Family-Wise Error:** $\alpha_{FW} = 1-(1-p)^N \to 1$ as $N$ increases

  o For $N \cdot p$ small (compared to 1), $\alpha_{FW} \approx N \cdot p$

  o $N \approx 20,000+$ voxels in the brain

  o To keep probability of even one false positive $\alpha_{FW} < 0.05$ (the “corrected” $p$-value), need to have $p < 0.05 / 2 \times 10^4 = 2.5 \times 10^{-6}$

  o This constraint on the per-voxel (“uncorrected”) $p$-value is so stringent that we’ll end up rejecting a lot of true positives (Type II errors) also, just to be safe on the Type I error rate

• **Multiple testing problem in FMRI**

  ★ 3 occurrences of multiple tests: individual, group, and conjunction

  ★ Group analysis is the most severe situation (have the least data, considered as number of independent samples = subjects)
Two Approaches to the “Curse of Multiple Comparisons”

★ Control FWE to keep expected total number of false positives below 1
  o Overall significance: \( \alpha_{FW} = \text{Prob}(\geq \text{one false positive voxel in the whole brain}) \)
  o Bonferroni correction: \( \alpha_{FW} = 1 - (1-p)^N \approx Np \), if \( p \ll N^{-1} \)
    - Use \( p = \alpha/N \) as individual voxel significance level to achieve \( \alpha_{FW} = \alpha \)
    - Too stringent and overly conservative: \( p = 10^{-8} \ldots 10^{-6} \)
  o Something to rescue us from this hell of statistical super-conservatism?
    - Correlation: Voxels in the brain are not independent
      - Especially after we smooth them together!
      - Means that Bonferroni correction is way way too stringent
    - Contiguity: Structures in the brain activation map
      - We are looking for activated “blobs”: the chance that pure noise \( (H_0) \) will give a set of seemingly-activated voxels next to each other is lower than getting false positives that are scattered around far apart
      - Control FWE based on spatial correlation (smoothness of image noise) and minimum cluster size we are willing to accept

★ Control false discovery rate (FDR)
  o FDR = expected proportion of false positive voxels among all detected voxels
    - Give up on the idea of having (almost) no false positives at all
Cluster Analysis: 3dClustSim

- **FWE control in AFNI**
  - Monte Carlo simulations with program 3dClustSim
    - Named for a place where primary attractions are randomization experiments
    - Randomly generate some number (e.g., 1000) of brain volumes with white noise (spatially uncorrelated)
      - That is, each “brain” volume is purely in $H_0 = \text{no activation}$
      - Noise images can be blurred to mimic the smoothness of real data
    - Count number of voxels that are false positives in each simulated volume
      - Including how many are false positives that are spatially together in clusters of various sizes (1, 2, 3, …)
    - Parameters to program
      - Size of dataset to simulate
      - Mask (e.g., to consider only brain-shaped regions in the 3D brick)
      - Spatial correlation FWHM: from 3dBlurToFWHM or 3dFWHMX
      - Connectivity radius: how to identify voxels belonging to a cluster?
        - Default = NN connection = touching faces
        - Individual voxel significance level = uncorrected $p$-value
    - Output
      - Simulated (estimated) overall significance level (corrected $p$-value)
      - Corresponding minimum cluster size at the input uncorrected $p$-value
• Example: 3dClustSim -nxyz 64 64 30 -dxyz 3 3 3 -fwhm 7

```
3dClustSim -nxyz 64 64 30 -dxyz 3 3 3 -fwhm 7

# Grid: 64x64x30 3.00x3.00x3.00 mm^3 (122880 voxels)
# CLUSTER SIZE THRESHOLD(pthr,alpha) in Voxels
# -NN 1   | alpha = Prob(Cluster >= given size)
# pthr   | 0.100  0.050  0.020  0.010
# ------- | ------- ------- ------- -------
# 0.020000    89.4   99.9  114.0  123.0
# 0.010000    56.1   62.1   70.5   76.6
# 0.005000    38.4   43.3   49.4   53.6
# 0.002000    25.6   28.8   33.3   37.0
# 0.001000    19.7   22.2   26.0   28.6
# 0.000500    15.5   17.6   20.5   22.9
# 0.000200    11.5   13.2   16.0   17.7
# 0.000100     9.3   10.9   13.0   14.8
```

At a per-voxel $p=0.005$, a cluster should have **44+** voxels to occur with $\alpha < 0.05$ from noise only.

3dClustSim can be run by `afni_proc.py` and used in AFNI Clusterize GUI.
Interactive Clustering

Report on clusters of above threshold voxels

This panel controls the clustering operation

Mean timeseries over cluster #2
**False Discovery Rate in**

- Situation: making *many* statistical tests at once
  - e.g., Image voxels in FMRI; associating genes with disease
- Want to set threshold on statistic (e.g., $F$- or $t$-value) to control *false positive* error rate
- Traditionally: set threshold to control probability of making a *single* false positive detection
  - But if we are doing 1000s (or more) of tests at once, we have to be very stringent to keep this probability low
- **FDR**: accept the fact that there will be multiple erroneous detections when making lots of decisions
  - Control the *fraction* of positive detections that are wrong
  - Of course, no way to tell which individual detections are right!
  - Or at least: control the *expected value* of this fraction
FDR: \( q \)

- Given some collection of statistics (say, \( F \)-values from 3dDeconvolve), set a threshold \( h \)
- The **uncorrected** \( p \)-**value** of \( h \) is the probability that \( F > h \) when the null hypothesis is true (no activation)
  - “Uncorrected” means “per-voxel”
  - The “corrected” \( p \)-value is the probability that any voxel is above threshold in the case that they are all unactivated
  - If have \( N \) voxels to test, \( p_{\text{corrected}} = 1-(1-p)^N \approx Np \) (for small \( p \))
    - Bonferroni: to keep \( p_{\text{corrected}} < 0.05 \), need \( p < 0.05 / N \), which is very tiny
- The FDR **\( q \)-value** of \( h \) is the fraction of false positives expected when we set the threshold to \( h \)
  - Smaller \( q \) is “better” (more stringent = fewer false detections)
Basic Ideas Behind FDR $q$

- **If** all the null hypotheses are true, **then** the statistical distribution of the $p$-values will be uniform
  - Deviations from uniformity at low $p$-values $\Rightarrow$ true positives
  - Baseline of uniformity indicates how many true negatives are hidden amongst in the low $p$-value region

Red = $p$s from Full-$F$ (real data)

Black = $p$s from pure noise (simulation) (baseline level=false +)

31,555 voxels
50 histogram bins

True +
False +

threshold $h$
How \( q \) is Calculated from Data

- Compute \( p \)-values of each statistic: \( P_1, P_2, P_3, \ldots, P_N \)
- Sort these: \( P_{(1)} \leq P_{(2)} \leq P_{(3)} \leq \cdots \leq P_{(N)} \) \( \{ \text{subscript}() \equiv \text{sorted} \} \)
- For \( k = 1..N \), \( q(k) = \min_{m \geq k} \left[ N \cdot P_{(m)}/m \right] \)
  - Easily computed from sorted \( p \)-values by looping downwards from \( k = N \) to \( k = 1 \)
- By keeping track of voxel each \( P_{(k)} \) came from: can put \( q \)-values (or \( z(q) \) values) back into image
  - This is exactly how program 3dFDR works
- By keeping track of statistic value (\( t \) or \( F \)) each \( P_{(k)} \) came from: can create curve of threshold \( h \) vs. \( z(q) \)
- **N.B.:** \( q \)-values depend on the data in all voxels, unlike these voxel-wise (uncorrected) \( p \)-values!
  - Which is why it’s important to mask brain properly
Graphical Calculation of $q$

- Graph sorted $p$-values of voxel $#k$ vs. $\kappa = k/N$ (the cumulative histogram of $p$, flipped sideways) and draw some lines from origin.

Real data: $F$-statistics from 3dDeconvolve

Ideal sorted $p$ if no true positives at all (uniform distribution)

$q=0.10$ cutoff

N.B.: $q$-values depend on data in all voxels, unlike voxel-wise (uncorrected) $p$-values!

Very small $p = $ very significant

Slope=0.10
Why This Line-Drawing Works

\[ p = 1 \]

\[ p = 0 \]

\[ \kappa = 0 \]

\[ \kappa = m_1 \]

\[ \kappa = \kappa^\# \]

\[ \kappa = k/N = \text{fractional index} \]

**Cartoon:**
Lots of \( p \approx 0 \) values; And the rest are uniformly distributed

\[ m_1 = \text{true positive fraction (unknown)} \]
\[ 1 - m_1 = \text{true negative fraction} \]

Lines intersect at \( \kappa^\# = m_1/[1 - q(1 - m_1)] \)
False positives = \( \kappa^\# - m_1 \)

\[ \text{FDR} = (\text{False +})/(\text{All +}) = q(1 - m_1) \leq q \]

More advanced FDR: estimate \( m_1 \) also

\[ \text{line: } p = (\kappa - m_1)/(1 - m_1) \]

\[ \text{line: } p = q\kappa \]
Same Data: threshold $F$ vs. $z(q)$

$z \approx 1.96$ is $q \approx 0.05$; Corresponds (for this data) to $F \approx 1.5$

$z=9$ is $q \approx 10^{-19}$; larger values of $z$ aren't useful!
Recent Changes to 3dFDR

• Don’t include voxels with \( p=1 \) (e.g., \( F=0 \)), even if they are in the \(-\text{mask}\) supplied on the command line
  ▪ This changes decreases \( N \), which will decrease \( q \) and so increase \( z(q) \): recall that \( q(k) = \min_{m \geq k} \left[ \frac{N \cdot P(m)}{m} \right] \)

• Sort with Quicksort algorithm
  ▪ Faster than the bin-based sorting in the original code
  ▪ Makes a big speed difference on large 1 mm\(^3\) datasets
    o Not much speed difference on small 3 mm\(^3\) grids, since there aren’t so many voxels to sort

• Default mode of operation is ‘–new’ method
  ▪ Prints a warning message to let user know things have changed from the olden days
  ▪ User can use ‘–old’ method if desired
FDR curves: $h$ vs. $q$

- **3dDeconvolve**, **3dANOVAX**, **3dttest**, and **3dNLfim** now compute FDR curves for all statistical sub-bricks and store them in output header.

- **3drefit -addFDR** does same for other datasets.
  - **3drefit -unFDR** can be used to delete such info.

- **AFNI** now shows $p$- and $q$-values below the threshold slider bar.
  - Interpolates FDR curve from header (threshold → $z$ → $q$).
  - Can be used to adjust threshold by “eyeball”.

$q = N/A$ means it’s not available. $MDF$ hint = “missed detection fraction”
FDR Statistical Issues

• FDR is conservative ($q$-values are too large) when voxels are positively correlated (e.g., from spatially smoothing)
  ▪ Correcting for this is not so easy, since $q$ depends on data (including true positives), so a simulation like `3dClustSim` is hard to conceptualize
  ▪ At present, FDR is an alternative way of controlling false positives, vs. `3dClustSim` (clustering)
    o Thinking about how to combine FDR and clustering

• Accuracy of FDR calculation depends on $p$-values being uniformly distributed under the null hypothesis
  ▪ Statistic-to-$p$ conversion should be accurate, which means that null $F$-distribution (say) should be correctly estimated
  ▪ Serial correlation in FMRI time series means that `3dDeconvolve` denominator DOF is too large
    ▪ $\Rightarrow$ $p$-values will be too small, so $q$-values will be too small
      o `3dREMLfit` can ride to the rescue!
FWE or FDR?

• These 2 methods control Type I error in different sense
  ★ FWE: \( \alpha_{FW} = \text{Prob}(\geq \text{one false positive voxel/cluster in the whole brain}) \)
    ▪ Frequentist’s perspective: Probability among many hypothetical activation maps gathered under identical conditions
    ▪ Advantage: can directly incorporate smoothness into estimate of \( \alpha_{FW} \)
  ★ FDR = expected fraction of false positive voxels among all detected voxels
    ▪ Focus: controlling false positives among detected voxels in one activation map, as given by the experiment at hand
    ▪ Advantage: not afraid of making a few Type I errors in a large field of true positives

★ Concrete example
  ▪ Individual voxel \( p = 0.001 \) for a brain of 25,000 EPI voxels
  ▪ Uncorrected \( \rightarrow \approx 25 \) false positive voxels in the brain
  ▪ FWE: corrected \( p = 0.05 \) \( \rightarrow \approx 5\% \) of the time would expect one or more false positive clusters in the entire volume of interest
  ▪ FDR: \( q = 0.05 \) \( \rightarrow \approx 5\% \) of voxels among those positively labeled ones are false positive

• What if your favorite blob fails to survive correction?
  ★ Tricks (don’t tell anyone we told you about these)
    ▪ One-tail \( t \)-test?
    ▪ ROI-based statistics – e.g., grey matter mask, or whatever regions you focus on
  ★ Analysis on surface; or, Use better group analysis tool (3dLME, 3dMEMA, etc.)
• Conjunction
  ★ Dictionary: “a compound proposition that is true if and only if all of its component propositions are true”
  ★ FMRI: areas that are active under 2 or more conditions (AND logic)
    o e.g, in a visual language task and in an auditory language task
  ★ Can also be used to mean analysis to find areas that are exclusively activated in one task but not another (XOR logic) or areas that are active in either task (non-exclusive OR logic)
  ★ If have $n$ different tasks, have $2^n$ possible combinations of activation overlaps in each voxel (ranging from nothing there to complete overlap)
  ★ Tool: 3dcalc applied to statistical maps
    o Heaviside step function defines a On/Off logic
    o $\text{step}(t-a) = 0$ if $t < a$
      $= 1$ if $t > a$
    o Can be used to apply more than one time
• Example of forming all possible conjunctions
  ★ 3 contrasts/tasks A, B, and C, each with a t-stat from 3dDeconvolve
  ★ Assign each a number, based on binary positional notation:
    o A: $001_2 = 2^0 = 1$; B: $010_2 = 2^1 = 2$; C: $100_2 = 2^2 = 4$
  ★ Create a mask using 3 sub-bricks of $t$ (e.g., threshold = 4.2)
    
    \[
    \text{3dcalc -a ContrA+tlrc -b ContrB+tlrc -c ContrC+tlrc} \ \backslash
    \text{-expr '1*step(a-4.2)+2*step(b-4.2)+4*step(c-4.2)' } \ \backslash
    \text{-prefix ConjAna}
    \]
  ★ Interpret output, which has 8 possible ($=2^3$) scenarios:
    000$_2$ = 0: none are active at this voxel
    001$_2$ = 1: A is active, but no others
    010$_2$ = 2: B, but no others
    011$_2$ = 3: A and B, but not C
    100$_2$ = 4: C but no others
    101$_2$ = 5: A and C, but not B
    110$_2$ = 6: B and C, but not A
    111$_2$ = 7: A, B, and C are all active at this voxel

Can display each combination with a different color and so make pretty pictures that might even mean something!
• **Multiple testing correction issue**
  ★ How to calculate the $p$-value for the conjunction map?
  ★ No problem, *if* each entity was corrected (e.g., cluster-size thresholded at $t=4.2$) before conjunction analysis, via 3dClustSim
  ★ But that may be too stringent (conservative) and over-corrected
  ★ With 2 or 3 entities, analytical calculation of conjunction $p_{\text{conj}}$ is possible
    ▪ Each individual test can have different uncorrected (per-voxel) $p$
    ▪ Double or triple integral of tails of non-spherical (correlated) Gaussian distributions — not available in simple analytical formulae
  ★ With more than 3 entities, may have to resort to simulations
    ▪ Monte Carlo simulations? (AKA: Buy a fast computer)
    ▪ Will Gang Chen write such a program? Only time will tell!